
RIM20
Rotor Insertion Flowmeter
Installation and Maintenance Instructions



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Customer Notice for Oxygen Service

This flowmeter is not intended for oxygen service.

Spirax Sarco Limited is not liable for any damage or personal injury, whatsoever, resulting from the use of Spirax Sarco Rotor Insertion Flowmeters for oxygen gas.

If oxygen service is required please consult factory.

Customer Notice for EMC Class Division

This flowmeter is suitable for EMC Class A environments only.

Class A equipment is suitable for use in all establishments other than domestic and those connected to a low voltage power supply network which supplies buildings used for domestic purposes.

There may be potential difficulties in ensuring electromagnetic compatibility in other environments, due to conducted as well as radiated disturbances.

1. Safety information

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1. Safety information

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GL51 9NQ
GB

We use **Warning**, **Caution** and **Note** statements throughout this book to draw your attention to important information.



Warning!

This statement appears with information that is important to protect people and equipment from damage. Pay very close attention to all warnings that apply to your application.



Caution!

This statement appears with information that is important for protecting your equipment and performance. Read and follow all cautions that apply to your application.



Note

This statement appears with a short message to alert you to an important detail.

1.1 Receipt of system components

When receiving a Spirax Sarco mass flowmeter, carefully check the outside packing carton for damage incurred in shipment. If the carton is damaged, notify the local carrier and submit a report to the factory or distributor.

Remove the packing slip and check that all ordered components are present. Make sure any spare parts or accessories are not discarded with the packing material. Do not return any equipment to the factory without first contacting Spirax Sarco Customer Service.

1.2 Technical assistance

If you encounter a problem with your flowmeter, review the configuration information for each step of the installation, operation and set up procedures.

Verify that your settings and adjustments are consistent with factory recommendations. Refer to Section 6, Troubleshooting, for specific information and recommendations.

If the problem persists after following the troubleshooting procedures outlined in Section 6, Contact Spirax Sarco Customer Support between 8:00 a.m. and 5:00 p.m.

When calling Technical Support, have the following information on hand:

- the serial number and Spirax Sarco order number (all marked on the meter nameplate)
- the problem you are encountering and any corrective action taken
- application information (fluid, pressure, temperature and piping configuration)



Warning!

Agency approval for hazardous location installations varies between flowmeter models.

Consult the flowmeter nameplate for specific flowmeter approvals before any hazardous location installation.

Hot tapping must be performed by a trained professional, regulations often require a hot tap permit. The manufacturer of the hot tap equipment and/or the contractor performing the hot tap is responsible for providing proof of such a permit.

All flowmeter connections, isolation valves and fittings for cold/hot tapping must have the same or higher pressure rating as the main pipeline.

For RIM20 rotor Insertion flowmeter installations, an Insertion tool must be used for any installation where a flowmeter is inserted under pressure greater than 3.45 bar g (50 psi g).

To avoid serious injury, DO NOT loosen a compression fitting under pressure.

To avoid potential electric shock, follow National Electric Code or your local code when wiring this unit to a power source. Failure to do so could result in injury or death.

All ac power connections must be in accordance with published CE directives. All wiring procedures must be performed with the power Off.

Before attempting any flowmeter repair, verify that the line is not pressurized. Always remove main power before disassembling any part of the mass flowmeter.



Caution!

Calibration must be performed by qualified personnel. Spirax Sarco strongly recommends that you return your flowmeter to the factory for calibration.

In order to achieve accurate and repeatable performance, the flowmeter must be installed with the specified minimum length of straight pipe upstream and downstream of the flowmeter's sensor head.

When using toxic or corrosive gases, purge the line with inert gas for a minimum of four hours at full gas flow before installing the flowmeter.

For RIM20 rotor Insertion flowmeter installations, the sensor alignment pointer must point downstream in the direction of flow.

The ac wire insulation temperature rating must meet or exceed 85 °C (185 °F).

2. Introduction

2.1 RIM20 rotor insertion flowmeters

The Spirax Sarco RIM20 rotor insertion flowmeters provide a reliable solution for process flow measurement. From a single entry point in the pipeline, RIM20 flowmeters offer precise measurements of mass or volumetric flowrates.

2.2 Multi-variable mass flowmeters

Mass flowmeters utilize three primary sensing elements: a rotating turbine velocity sensor, an RTD temperature sensor, and a solid state pressure sensor to measure the mass flowrate of gases, liquids, and steam. Meters are available as loop powered devices or with up to three 4-20 mA Analogue output signals for monitoring your choice of the six process variables (energy flow, mass flow, volumetric flow, temperature, pressure and fluid density). The Energy Monitoring option permits realtime calculation of energy consumption for a facility or process.

2.3 Volumetric flowmeters

The primary sensing element of a volumetric flowmeter is a rotating turbine velocity sensor. Meters are loop powered. The Analogue 4-20 mA output signal offers your choice of volumetric or mass flowrate. Mass flowrate is based on a constant value for fluid density stored in the instrument's memory.

Both the mass and volumetric flowmeters can be ordered with a local keypad/display which provides instantaneous flowrate, total, and process parameters in engineering units. A pulse output signal for remote totalization and MODBUS, BACnet or HART communications are also available. RIM20 digital electronics allows for easy reconfiguration for most gases, liquids and steam. The Spirax Sarco RIM20 flowmeters' simple installation combines with an easy-to-use interface that provides quick set up, long term reliability and accurate mass flow measurement over a wide range of flows, pressures and temperatures.

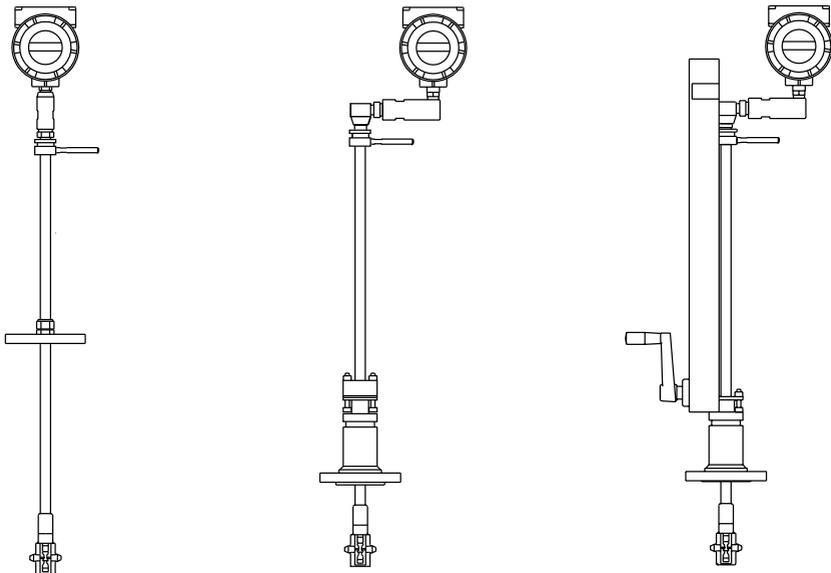


Fig. 1 Rotor Insertion multivariable Mass flowmeters

2.4 How the RIM20 rotor insertion flowmeter operates

The RIM20 rotor insertion flowmeters are designed to monitor mass flowrate by directly measuring three variables-fluid velocity, temperature and pressure. The built-in flow computer calculates the mass flowrate and volumetric flowrate based on these three direct measurements. To measure fluid velocity, the flowmeter incorporates a rotating turbine in the flow stream. The rotation is converted into an electrical output which is proportional to fluid velocity.

Temperature is measured using a platinum resistance temperature detector (PRTD) and pressure measurement is achieved using a solid-state pressure transducer.

2.5 Velocity measurement

Fluid passing through the turbine causes its rotor to spin. The rotor is fabricated from 17-4PH stainless steel which is slightly magnetic, and is positioned in close proximity to a passive magnetic pickup coil. As each blade rotates by the pickup coil, a small sinusoidal voltage is generated. This sinusoidal voltage is then amplified, filtered, and shaped by the measurement electronics. The frequency of the signal is proportional to the flowing velocity.

2.6 Flow velocity range

To ensure trouble-free operation, turbine flowmeters must be correctly sized so that the flow velocity range through the meter lies within the measurable velocity range. The measurable range is defined by the minimum and maximum velocity using the following table.

| Rotor | Gas or Steam | | | |
|-------|------------------|--------|------------------|--------|
| | Minimum velocity | | Maximum velocity | |
| | m/sec | ft/sec | m/sec | ft/sec |
| R40 | 1.07 | 3.5 | 13.11 | 43.0 |
| R30 | 1.22 | 4.0 | 19.05 | 62.5 |
| R25 | 1.52 | 5.0 | 24.38 | 80.0 |
| R20 | 2.13 | 7.0 | 30.48 | 100.0 |
| R15 | 2.59 | 8.5 | 41.03 | 134.6 |
| R10 | 3.66 | 12.0 | 62.48 | 205.0 |

Table 1 Measurable range

The pressure drop for the RIM20 rotor insertion flowmeters is negligible.

2.7 Temperature measurement

RIM20 rotor insertion flowmeters use a 1000 ohm platinum resistance temperature detector (PRTD) to measure fluid temperature.

2.8 Pressure measurement

The RIM20 rotor insertion flowmeters incorporate a solid-state pressure transducer isolated by a 316L stainless steel diaphragm. The transducer itself is micromachined silicon, fabricated using integrated circuit processing technology.

A nine-point pressure/temperature calibration is performed on every sensor. Digital compensation allows these transducers to operate within a 0.3% of full scale accuracy band within the entire ambient temperature range of -40 to 60 °C (-40 °F to 140 °F). Thermal isolation of the pressure transducer ensures the same accuracy across the allowable process fluid temperature range of -200 to 400 °C (-330 °F to 750 °F).

2.9 Flowmeter configuration

The RIM20 rotor insertion flowmeters has a sensing head which contains the turbine rotor, temperature sensor, and pressure tap.

The pressure sensor is located in the pressure transducer housing between the stem and electronics housing.

The meter is installed through a full port block valve and mounting adapter having a clear, cylindrical port diameter of 47.625 mm (1.875") diameter. It can be installed during system downtime or using standard "Hot Tap" procedures.

The meter directly monitors the velocity at a point in the cross-sectional area of a pipe, duct, or stack. The velocity at a point in the pipe varies as a function of the Reynolds number. When a fluid flows through a pipe, the velocity generated is not constant across the diameter. The fluid velocity varies across the diameter of the pipe creating a "Velocity Profile".

That is, velocities near the center of the pipe are faster than those nearer to the wall. In addition, the velocity profile varies in concert with flowrate from the lowest to the highest flows. Mathematical descriptions of this profile have been developed for over 100 years. By knowing the velocity profile and the flowrate at a single point, the average flowrate can be determined. The accuracy of the flowrate computation depends on adherence to the piping installation requirements given in Section 2. If adherence to those guidelines cannot be met, contact the factory for specific installation advice.

2.10 Multivariable options

The RIM20 model is available with the following options:

- V, volumetric flowmeter;
- VT, velocity and temperature sensors;
- VTP, velocity, temperature, and pressure sensors;
- VTEM energy output options;
- VTPM, energy options with pressure;
- VTEP, external pressure transmitter input.

2.11 Line size / process connections

The RIM20 rotor insertion flowmeter can be used in line sizes DN50 (2") and greater and is built with a compression fitting or packing gland design using 50 mm (2") NPT, or DN50 (2") flanged connections (ANSI 150, 300, 600, PN16, 40, or 63 class flanges). The packing gland design can be ordered with a permanent or removable retractor.

2.12 Flowmeter electronics

RIM20 flowmeter electronics are available mounted directly to the flowmeter, or remotely mounted. The electronics housing may be used indoors or outdoors, including wet environments. Available input power options are: dc loop powered (2-wire), dc powered, or ac powered.

Three Analogue output signals are available for your choice of three of the six process variables: energy flowrate, mass flowrate, volumetric flowrate, temperature, pressure or fluid density. A pulse output signal for remote totalization and MODBUS, BACnet or HART communications are also available.

RIM20 flowmeters include a local 2 x 16 character LCD display housed within the enclosure. Local operation and reconfiguration is accomplished using six pushbuttons operated via finger touch. For hazardous locations, the six buttons can be operated with the electronics enclosure sealed using a hand-held magnet, thereby not compromising the integrity of the hazardous location certification.

The electronics include nonvolatile memory that stores all configuration information. The nonvolatile memory allows the flowmeter to function immediately upon power up, or after an interruption in power. All flowmeters are calibrated. The instrument is configured for the customer's flow application.

3. Installation

3.1 Installation overview

The RIM20 rotor insertion flowmeter installations are simple and straightforward. After reviewing the installation requirements given below, see Section 3.4 for RIM20 installation instructions.



Warning!

Consult the flowmeter nameplate for specific flowmeter approvals before any hazardous location installation.

3.2 Flowmeter installation requirements

Before installing the flowmeter, verify the installation site allows for these considerations:

1. Line pressure and temperature will not exceed the flowmeter rating.
2. The location meets the required minimum number of pipe diameters upstream and downstream of the sensor head as illustrated in Figure 2.
3. Safe and convenient access with adequate overhead clearance for maintenance purposes.
4. Verify that the cable entry into the instrument meets the specific standard required for hazardous area installations. The cable entry device shall be of a certified flameproof type, suitable for the conditions of use and correctly installed. The degree of protection of at least IP66 to EN 60529 is only achieved if certified cable entries are used that are suitable for the application and correctly installed. Unused apertures shall be closed with suitable blanking elements.
5. For remote installations, verify the supplied cable length is sufficient to connect the flowmeter sensor to the remote electronics.

Also, before installation check your flow system for anomalies such as:

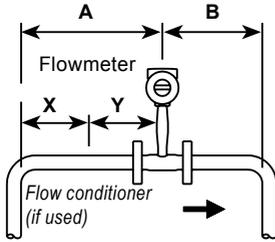
- leaks
- valves or restrictions in the flow path that could create disturbances in the flow profile that might cause unexpected flowrate indications
- avoid areas where high RF, EMI, or other electrical interference may be present. Devices such as VFD's (variable frequency drives), large ac motors, etc.

3.3 Unobstructed flow requirements

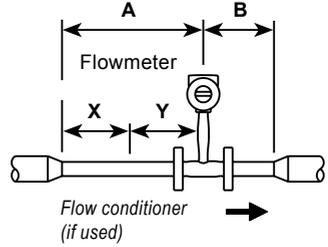
Select an installation site that will minimize possible distortion in the flow profile. Valves, elbows, control valves and other piping components may cause flow disturbances. Check your specific piping condition against the examples shown below. In order to achieve accurate and repeatable performance install the flowmeter using the recommended number of straight run pipe diameters upstream and downstream of the sensor.

Note: For liquid applications in vertical pipes, avoid installing with flow in the downward direction because the pipe may not be full at all points.

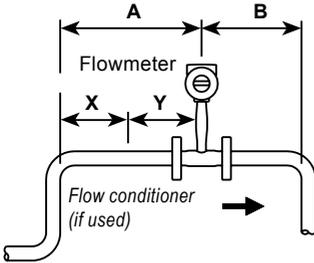
Choose to install the meter with flow in the upward direction if possible.



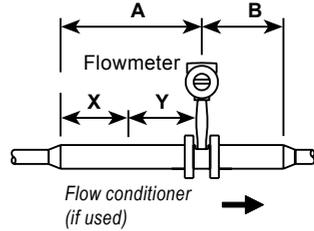
Example 1 : One 90° elbow before the RIM20 flowmeter



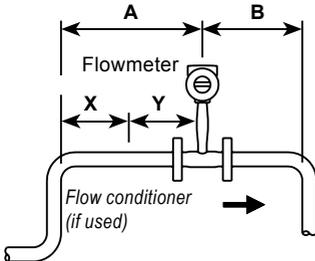
Example 4 : Reduction before the RIM20 flowmeter



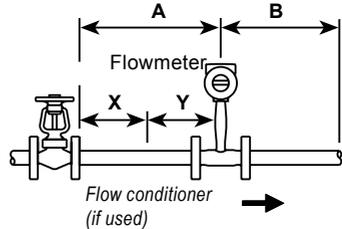
Example 2 : Two 90° elbow before the RIM20 flowmeter in one plane



Example 5 : Expansion before the RIM20 flowmeter



Example 3 : Two 90° elbow before the RIM20 flowmeter out of plane (if there are three 90° bends present, double the recommended length)



Example 6 : If the regulator or valve is partially closed before the RIM20 flowmeter (If the valve is always wide open, base the pipe length requirements on fitting directly preceding it)

Fig. 2
Recommended pipe length requirements for Installation

D = Internal diameter of channel.

N/A = Not applicable

| Example | Minimum required upstream diameters | | | | Minimum required downstream diameters | |
|---------|-------------------------------------|-----------------------|-----|-----|---------------------------------------|---------------------|
| | No flow conditioner | With flow conditioner | | | With flow conditioner | No flow conditioner |
| | A | A | X | Y | B | B |
| 1 | 10 D | 5 D | 2 D | 3 D | 5 D | 4 D |
| 2 | 15 D | 11 D | 5 D | 6 D | 5 D | 4 D |
| 3 | 30 D | 12 D | 5 D | 7 D | 5 D | 4 D |
| 4 | 10 D | 8 D | 3 D | 5 D | 5 D | 4 D |
| 5 | 30 D | 13 D | 6 D | 7 D | 5 D | 4 D |

3.4 Insertion flowmeter installation

Prepare the pipeline for installation using either a cold tap or hot tap method described on the following pages. Refer to a standard code for all pipe tapping operations. The following tapping instructions are general in nature and intended for guideline purposes only. Before installing the meter, review the mounting position and isolation valve requirements given below.

3.4.1 Mounting position

Allow clearance between the electronics enclosure top and any other obstruction when the meter is fully retracted.

3.4.2 Isolation valve selection

An isolation valve is available as an option with RIM20 flowmeters. If you supply the isolation valve, it must meet the following requirements:

1. A minimum valve bore diameter of 47.625 mm (1.875") is required, and the valve's body size should be DN50 (2"). Normally, gate valves are used.
2. Verify that the valve's body and flange rating are within the flowmeter's maximum operating pressure and temperature.
3. Choose an isolation valve with at least 50 mm (2") existing between the flange face and the gate portion of the valve. This ensures that the flowmeter's sensor head will not interfere with the operation of the isolation valve.

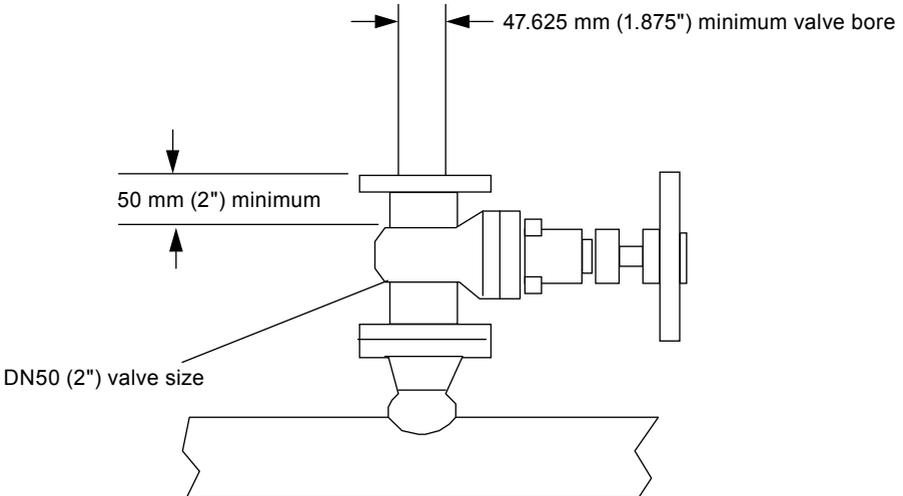


Fig. 3 Isolation valve requirements

3.5 Cold tap guidelines

Refer to a standard code for all pipe tapping operations. The following tapping instructions are general in nature and intended for guideline purposes only.



Caution!

When using toxic or corrosive gases, purge the line with inert gas for a minimum of four hours at full gas flow before installing the flowmeter.

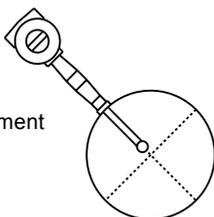


Warning!

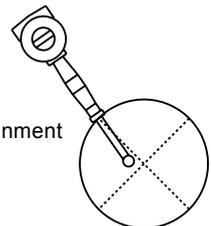
All flowmeter connections, isolation valves and fittings for cold tapping must have the same or higher pressure rating as the main pipeline.

1. Turn off the flow of process gas, liquid or steam. Verify that the line is not pressurised.
2. Confirm that the installation site meets the minimum upstream and downstream pipe diameter requirements. See Figure 2.
3. Use a cutting torch or sharp cutting tool to tap into the pipe. The pipe opening must be at least 47.625 mm (1.875") in diameter. (Do not attempt to insert the sensor probe through a smaller hole.)
4. Remove all burrs from the tap. Rough edges may cause flow profile distortions that could affect flowmeter accuracy. Also, obstructions could damage the sensor assembly when inserting into the pipe.
5. After cutting, measure the thickness of the cut-out and record this number for calculating the insertion depth.
6. Weld the flowmeter pipe connection on the pipe. Make sure this connection is within $\pm 5^\circ$ perpendicular to the pipe centerline.
7. Install the isolation valve (if used).
8. When welding is complete and all fittings are installed, close the isolation valve or cap the line. Run a static pressure check on the welds. If pressure loss or leaks are detected, repair the joint and retest.
9. The first time the sensor is inserted, install the check-disc tool on the flowmeter rather than the rotor.
10. Open the isolation valve (if used) and insert the check-disc tool. After successful insertion, retract the sensor and remove the flowmeter.
11. Install the rotor and connect the meter to the pipe process connection.
12. Calculate the sensor probe insertion depth and insert the sensor probe into the pipe as described on the following pages.

Fig. 4 Correct alignment



Incorrect alignment



3.6 Hot tap guidelines

Refer to a standard code for all pipe tapping operations. The following tapping instructions are general in nature and intended for guideline purposes only.



Warning!

Hot tapping must be performed by a trained professional. US. regulations often require a hot tap permit. The manufacturer of the hot tap equipment and/or the contractor performing the hot tap is responsible for providing proof of such a permit.



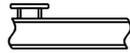
Warning!

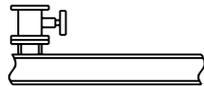
All flowmeter connections, isolation valves, and fittings for hot tapping must have the same or higher pressure rating as the main pipeline.

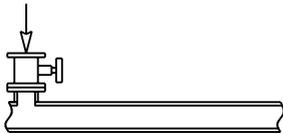
1. Confirm that the installation site meets the minimum upstream and downstream pipe diameter requirements.
2. Weld a two" mounting adapter on the pipe. Make sure the mounting adapter is within $\pm 5^\circ$ perpendicular to the pipe centerline (see previous page). The pipe opening must be at least 47.625 mm (1.875") in diameter.
3. Connect a two" process connection on the mounting adapter.
4. Connect an isolation valve on the process connection. The valve's full open bore must be at least 47.625 mm (1.875") in diameter.
5. Run a static pressure check on the welds. If pressure loss or leaks are detected, repair the joint and re-test.
6. Connect the hot tapping equipment to the isolation valve, open the isolation valve and drill at least a 47.625 mm (1.875") diameter hole.
7. Retract the drill, close the isolation valve, and remove the hot tapping equipment.
8. The first time the sensor is installed, install the check-disc tool on the flowmeter rather than the rotor.
9. Open the isolation valve and insert the check-disc tool. After successful insertion, retract the sensor, close the isolation valve and remove the flowmeter.
10. Install the rotor, connect the flowmeter to the isolation valve and open the isolation valve.
11. Calculate the sensor probe insertion depth and insert the sensor probe into the pipe as described on the following pages.

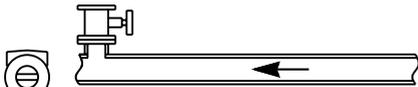
 Check upstream and downstream requirements

 Weld mounting adapter

 Connect process connection (flange or NPT)

 Connect isolation valve and test for leaks

 Hot tap pipe

 Purge pipe

 Connect meter to valve, calculate insertion depth, install flowmeter

Fig. 5 Hot tap sequence

3.7 Flowmeter Insertion

The sensor head must be properly positioned in the pipe. For this reason, it is important that insertion length calculations are carefully followed. A sensor probe inserted at the wrong depth in the pipe will result in inaccurate readings.

insertion flowmeters are applicable to pipes DN50 (2") and larger. For pipe sizes DN250 (10") and smaller, the centerline of the meter's sensing head is located at the pipe's centerline. For pipe sizes larger than DN250 (10"), the centerline of the sensing head is located 5" from the inside wall of the pipe.

Insertion flowmeters are available in three probe lengths:

Standard Probe configuration is used with most flowmeter process connections. The length, S, of the stem is 728.21 mm (28.67").

Compact Probe configuration is used with compression fitting process connections. The length, S, of the stem is 312.42 mm (12.3").

12" Extended Probe configuration is used with exceptionally lengthy flowmeter process connections. The length, S, of the stem is 1 033.02 mm (40.67").

3.7.1 Use the correct Insertion formula



Warning!

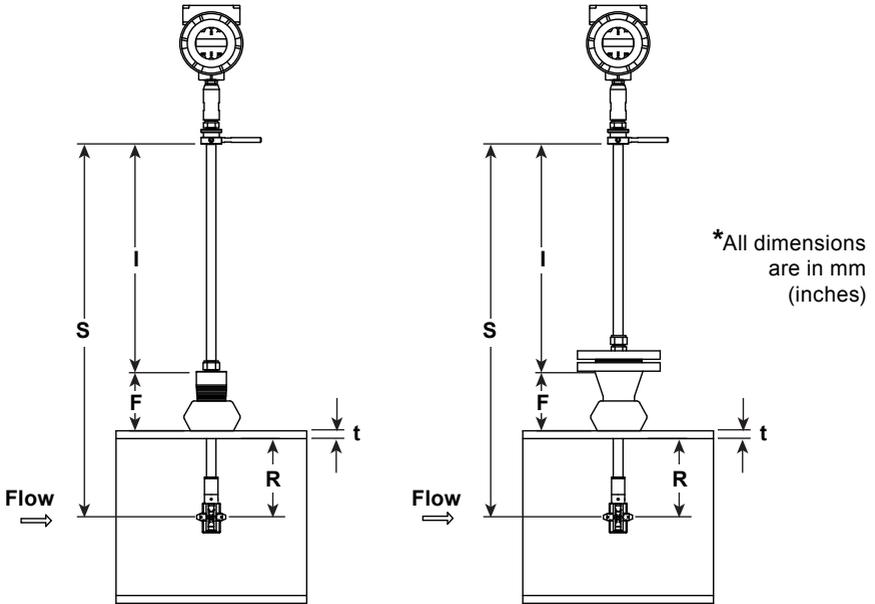
An Insertion tool must be used for any installation where a flowmeter is inserted under pressure greater than 3.45 bar g (50 psi g).

Depending on your flowmeter's process connection, use the applicable insertion length formula and installation procedure as follows:

- flowmeters with a compression type connection (NPT or flanged) follow the instructions beginning on page 19.
- flowmeters with a packing gland type connection (NPT or flanged) configured with an insertion tool, follow the instructions beginning on page 21.
- flowmeters with a packing gland type connection (NPT or flanged) without an insertion tool, follow the instructions beginning on page 26.

3.8 Installing flowmeters with a compression connection*

Use the following formula to determine insertion length for flowmeters (NPT and flanged) with a compression process connection. The installation procedure is given on the next page.



Insertion length formula

$$I = S - F - R - t$$

Where:

- I** = insertion length.
- S** = Stem length - the distance from the center of the sensor head to the base of the enclosure adapter
 S = 728.218 mm (28.67") for standard probes;
 S = 312.42 mm (12.3") for compact;
 S = 1 033.02 mm (40.67") for 304.8 mm (12") extended.
- F** = Distance from the raised face of the flange or top of NPT stem housing to the outside of the pipe wall.
- R** = Pipe inside diameter ÷ 2 for pipes DN250 (10") and smaller.
- R** = 125 mm (5") for pipe diameters larger than DN250 (10").
- t** = Thickness of the pipe wall. (Measure the disk cut-out from the tapping procedure or check a piping handbook for thickness.)

Fig. 6 Insertion calculation (compression type)

Example:

To install a RIM20 meter with a standard probe (S = 728.218 mm (28.67")) into a DN350 (14") schedule 40 pipe, the following measurements are taken:

$$F = 76.2 \text{ mm (3") } R = 127 \text{ mm (5") } t = 11.125 \text{ mm (0.438")}$$

The insertion length for this example is 513.842 mm (20.23"). Insert the stem through the fitting until an insertion length of 513.842 mm (20.23") is measured with a ruler.

3.8.1 Insertion procedure for meters with a compression connection

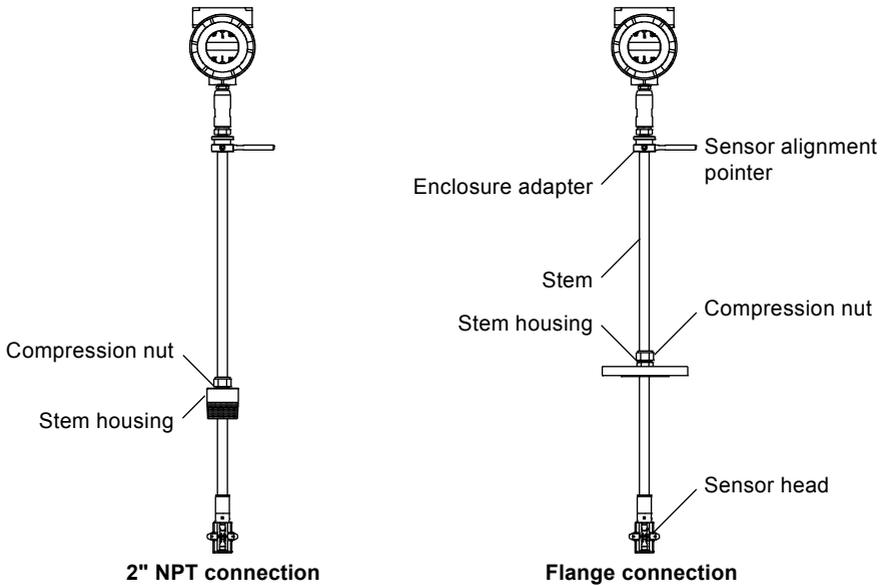


Fig. 7 Flowmeter with compression type fitting



Caution!

The sensor alignment pointer must point downstream, in the direction of flow.



Warning!

To avoid serious injury, DO NOT loosen the compression fitting under pressure.

1. Calculate the required sensor probe insertion length.
2. Fully retract the stem until the sensor head is touching the bottom of the stem housing. Slightly tighten the compression nut to prevent slippage.
3. Bolt or screw the flowmeter assembly into the process connection. Use Teflon tape or pipe sealant to improve the seal and prevent seizing on NPT styles.
4. Hold the meter securely while loosening the compression fitting. Insert the sensor into the pipe until the calculated insertion length, l , is measured between the base of the enclosure adapter and the top of the stem housing, or to the raised face of the flanged version. Do not force the stem into the pipe.
5. Align the sensor head using the sensor alignment pointer. Adjust the alignment pointer parallel to the pipe and pointing downstream.
6. Tighten the compression fitting to lock the stem in position. When the compression fitting is tightened, the position is permanent.

3.9 Installing flowmeters with a packing gland connection*

Use the formula below to determine the insertion depth for flowmeters (NPT and flanged) equipped with an insertion tool. To install, see the next page for instructions for meters with a permanent insertion tool. For meters with a removable insertion tool, see page 24.

Insertion length formula

$$I = F + R + t - 34.29 \text{ mm (1.35")}$$

Where:

- I = Insertion length.
- F = Distance from the raised face of the flange or top of the process connection for NPT style meters to the top outside of the process pipe.
- R = Pipe inside diameter + 2 for pipes 250 mm (10") and smaller.
- R = 127 mm (5") for pipe diameters larger than DN250 (10").
- t = Thickness of the pipe wall. (Measure the disk cutout from the tapping procedure or check a piping handbook for thickness.)

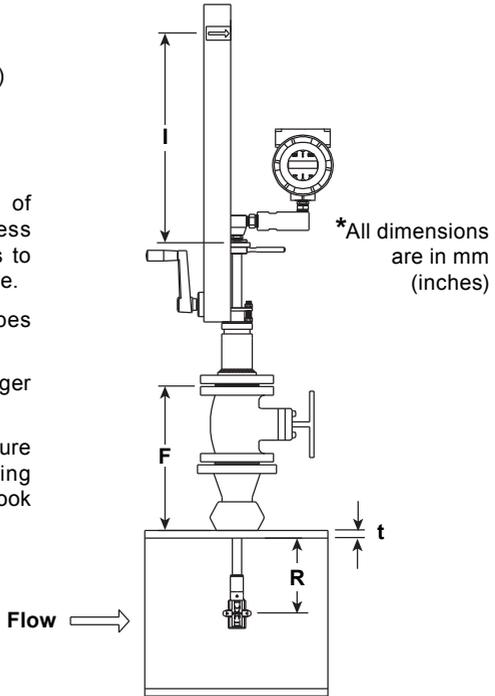


Fig. 8 Insertion calculation (Meters with insertion tool)

Example 1: Flange Style Meters:

To install a RIM20 flowmeter into a DN350 (14") schedule 40 pipe, the following measurements are taken:

$$F = 304.8 \text{ mm (12") } R = 127 \text{ mm (5") } t = 11.125 \text{ mm (0.438")}$$

The example insertion length is 408.686 mm (16.09").

Example 2: NPT Style Meters:

The length of thread engagement on the NPT style meters is also subtracted in the equation. The length of the threaded portion of the NPT meter is 29.972 mm (1.18"). Measure the thread portion still showing after the installation and subtract that amount from 29.972 mm (1.18"). This gives you the thread engagement length. If this cannot be measured use 13.97 mm (.55") for this amount.

$$F = 304.8 \text{ mm (12") } R = 127 \text{ mm (5") } t = 11.125 \text{ mm (0.438")}$$

The example insertion length is 394.716 mm (15.54").

3.9.1 Insertion procedure for flowmeters with permanent Insertion tool

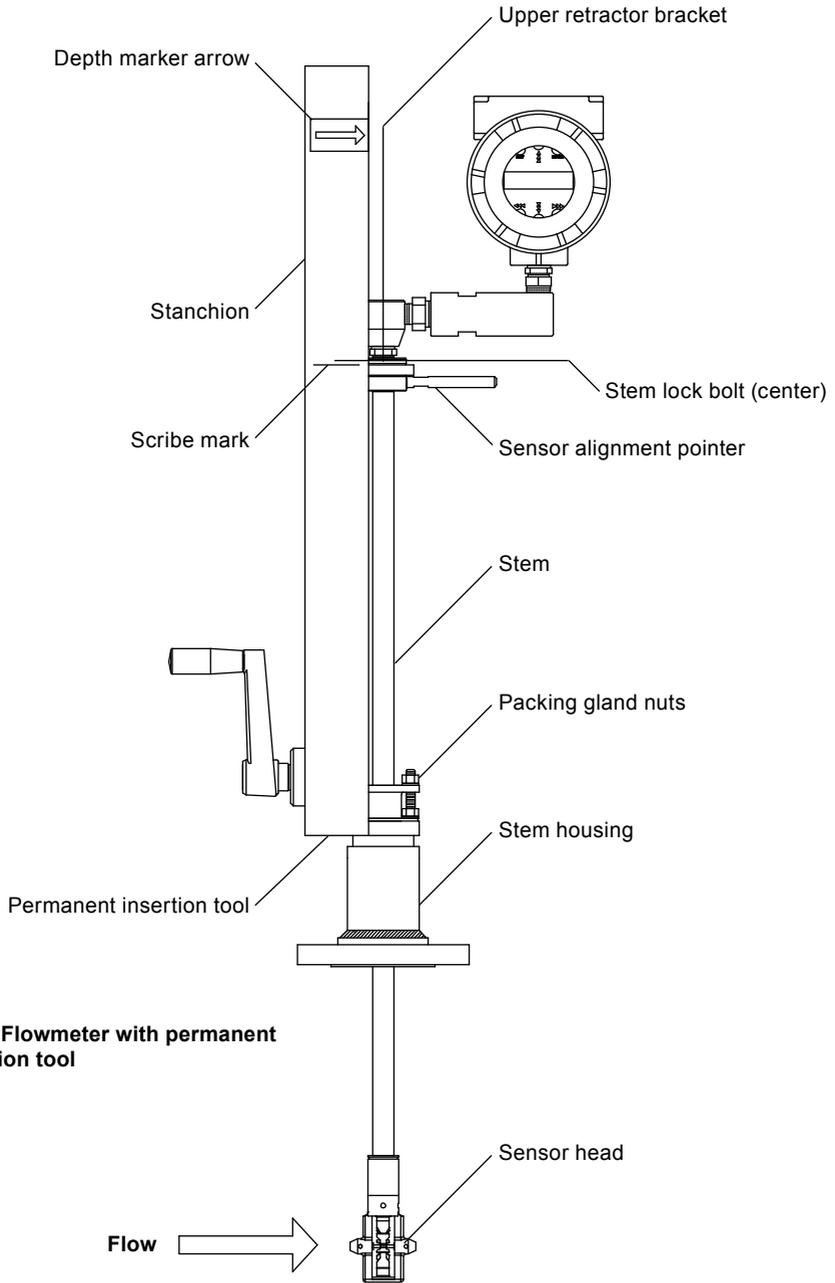


Fig. 9 Flowmeter with permanent insertion tool



Caution!

The sensor alignment pointer must point downstream, in the direction of flow.



Note

If line pressure is above 34.47 bar g (500 psi g), it could require up to 33.895 N-m (25 ft lb) of torque to insert the flowmeter. Do not confuse this with possible interference in the pipe.

1. Calculate the required sensor probe insertion length (see previous page). Measure from the depth marker arrow down the stanchion and scribe a mark at the calculated insertion depth.
2. Fully retract the flowmeter until the sensor head is touching the bottom of the stem housing. Attach the meter assembly to the DN50 (2") full-port isolation valve, if used. Use Teflon tape or pipe sealant to improve seal and prevent seizing on NPT style.
3. Loosen the two packing gland nuts on the stem housing of the meter.

Loosen the stem lock bolt adjacent to the sensor alignment pointer. Align the sensor head using the sensor alignment pointer. Adjust the alignment pointer parallel to the pipe and pointing downstream. Tighten the stem lock bolt to secure the sensor position.
4. Slowly open the isolation valve to the full open position. If necessary, slightly tighten the two packing gland nuts to reduce the leakage around the stem.
5. Turn the insertion tool handle clockwise to insert the sensor head into the pipe. Continue until the top of the upper retractor bracket aligns with the insertion length position scribed on the stanchion. Do not force the stem into the pipe.
6. Tighten the packing gland nuts to stop leakage around the stem. Do not torque over 27.116 N-m (20 ft-lb).

3.9.2 Insertion procedure for flowmeters with removable insertion tool

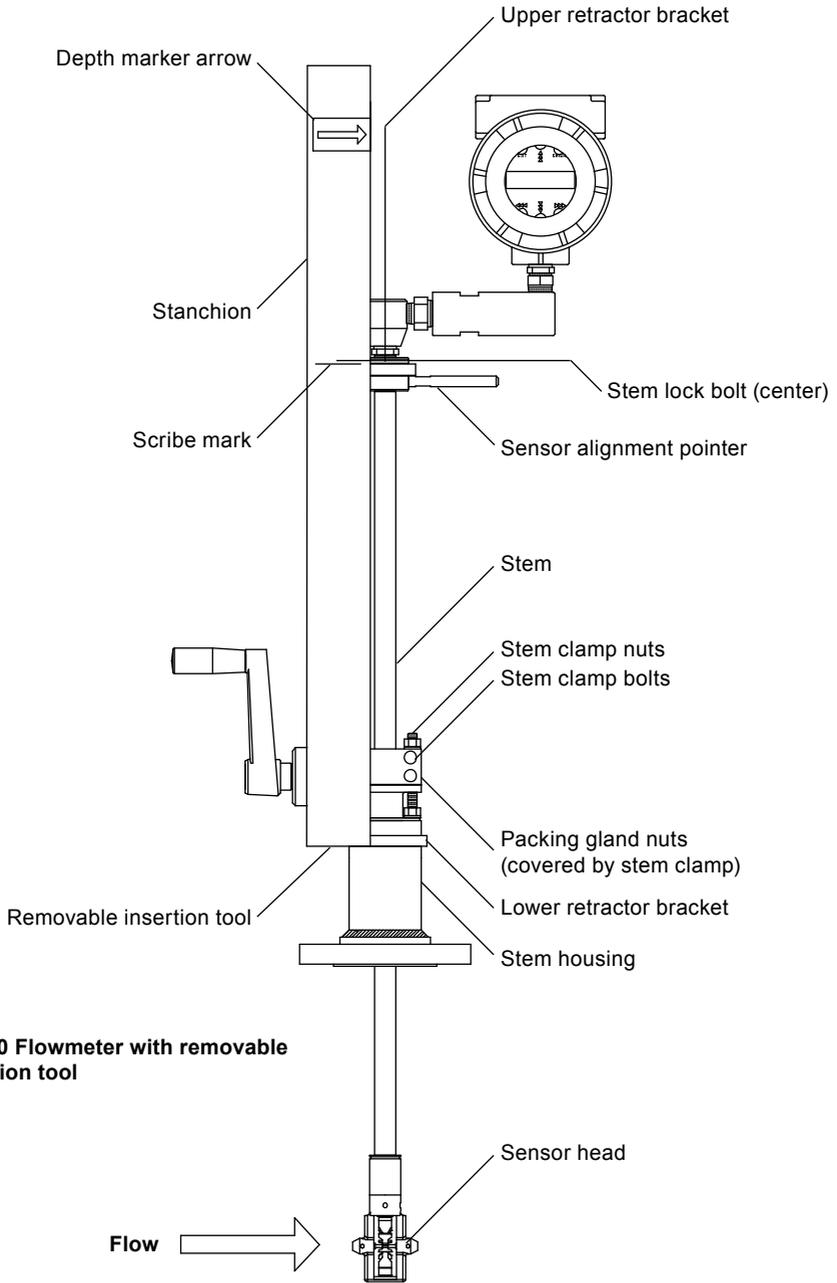


Fig. 10 Flowmeter with removable Insertion tool



Caution!

The sensor alignment pointer must point downstream, in the direction of flow.



Note

If line pressure is above 34.473 bar g (500 psi g), it could require up to 33.895 N-m (25 ft lb) of torque to insert the flowmeter.

Do not confuse this with possible interference in the pipe.

1. Calculate the required sensor probe insertion length. Measure from the depth marker arrow down the stanchion and scribe a mark at the calculated insertion depth.
2. Fully retract the flowmeter until the sensor head is touching the bottom of the stem housing. Attach the meter assembly to the DN50 (2") full-port isolation valve, if used. Use Teflon tape or pipe sealant to improve seal and prevent seizing on NPT style.
3. Remove the two top stem clamp nuts and loosen two stem clamp bolts. Slide the stem clamp away to expose the packing gland nuts.
4. Loosen the two packing gland nuts. Loosen the stem lock bolt adjacent to the sensor alignment pointer. Align the sensor head using the sensor alignment pointer. Adjust the alignment pointer parallel to the pipe and pointing downstream. Tighten the stem lock bolt to secure the sensor position.
5. Slowly open the isolation valve to the full open position. If necessary, slightly tighten the two packing gland nuts to reduce the leakage around the stem.
6. Turn the insertion tool handle clockwise to insert the stem into the pipe. Continue until the top of the upper retractor bracket lines up with the insertion length mark scribed on the stanchion. Do not force the stem into the pipe.
7. Tighten the packing gland nuts to stop leakage around the stem. Do not torque over 33.895 N-m (20 ft-lbs).
8. Slide the stem clamp back into position. Torque stem clamp bolts to 20.38 N-m (15 ft-lbs). Replace the stem clamp nuts and torque to 13.56 - 20.34 N-m (10 - 15 ft-lbs).
9. To separate the insertion tool from the flowmeter, remove four socket head cap bolts securing the upper and lower retractor brackets. Remove the insertion tool.

3.10 Installation of meters with packing gland connection (No Insertion Tool)*

Use the following formula to determine insertion depth for meters with a packing gland connection (NPT and flanged) without an insertion tool.

Insertion length formula

$$I = S - F - R - t$$

Where:

- I** = Insertion length.
- S** = Stem length - the distance from the center of the sensor head to the base of the enclosure adapter
- S** = 728.218 mm (28.67") for standard probes;
- S** = 1 033.02 mm (40.67") for 304.8 mm (12") extended probes.
- F** = Distance from the raised face of the flange or top of NPT stem housing to the outside of the pipe wall.
- R** = Pipe inside diameter ÷ 2 for pipes DN250 (10") and smaller.
- R** = 127 mm (5") for pipe diameters larger than 250 mm (10").
- t** = Thickness of the pipe wall. (Measure the disk cut-out from the tapping procedure or check a piping handbook for thickness.)

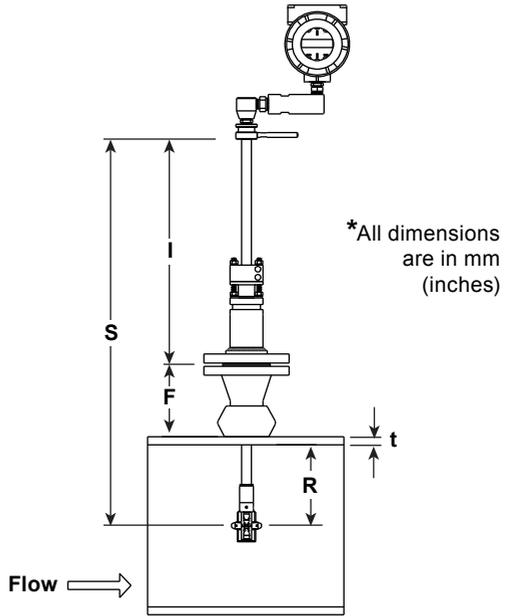


Fig. 11 Insertion calculation (Meters without insertion tool)

Example:

To install a RIM20 flowmeter with a standard probe ($S = 728.218 \text{ mm (28.67")}$) into a DN350 (14") schedule 40 pipe, the following measurements are taken:

$$F = 76.2 \text{ mm (3") } R = 127 \text{ mm (5") } t = 11.125 \text{ mm (0.438")}$$

The example insertion length is 513.842 mm (20.23").

3.10.1 Insertion procedure for flowmeters with no insertion tool (Packing gland connection)



Warning!

The line pressure must be less than 3.48 bar g (50 psi g) for installation.



Caution!

The sensor alignment pointer must point downstream, in the direction of flow.

1. Calculate the required sensor probe insertion length.
2. Fully retract the stem until the sensor head is touching the bottom of the stem housing. Remove the two top stem clamp nuts and loosen two stem clamp bolts. Slide the stem clamp away to expose the packing gland nuts. Loosen the two packing gland nuts.
3. Align the sensor head using the sensor alignment pointer. Adjust the alignment pointer parallel to the pipe and pointing downstream.
4. Insert the sensor head into the pipe until insertion length, l , is achieved. Do not force the stem into the pipe.
5. Tighten the packing gland nuts to stop leakage around the stem. Do not torque over 27.116 N-m (20 ft-lbs).
6. Slide the stem clamp back into position. Torque stem clamp bolts to 20.337 N-m (15 ft-lbs). Replace the stem clamp nuts and torque to 13.56 - 20.337 N-m (10 - 15 ft-lbs).

3.11 Display / Keypad adjustment (All meters)

The orientation of the display / keypad may be changed in 90 degree increments for easier viewing.

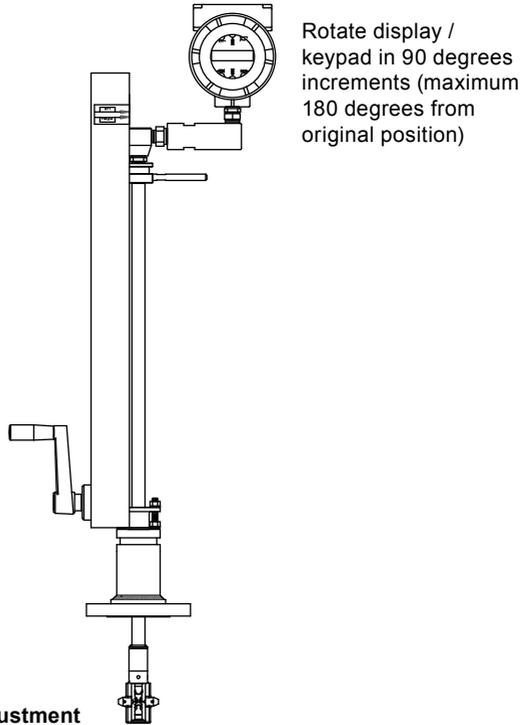


Fig. 12 Display / keypad viewing adjustment

The electronics boards are electro-statically sensitive. Wear a grounding wrist strap and make sure to observe proper handling precautions required for static-sensitive components.

To adjust the display:

1. Disconnect power to the flowmeter.
2. Loosen the small set screw which secures the electronics enclosure cover. Unscrew and remove the cover.
3. Loosen the 4 captive screws.
4. Carefully pull the display/microprocessor board away from the meter standoffs. Make sure not to damage the connected ribbon cable.
5. Rotate the display/microprocessor board to the desired position. Maximum turn, two positions left or two positions right (180°).
6. Align the board with the captive screws. Check that the ribbon cable is folded neatly behind the board with no twists or crimps.
7. Tighten the screws. Replace the cover and set screw. Restore power to the meter.

3.12 Loop power flowmeter wiring connections



Warning!

To avoid potential electric shock, follow National Electric Code safety practices or your local code when wiring this unit to a power source and to peripheral devices. Failure to do so could result in injury or death. All wiring procedures must be performed with the power off.

The NEMA 4X enclosure contains an integral wiring compartment located in the smaller end of the enclosure. Two 3/4-inch female NPT conduit entries are available for separate power and signal wiring. For all hazardous area installations, make sure to use an agency-approved fitting at each conduit entry. The cable entry device shall be of a certified flameproof type, suitable for the conditions of use and correctly installed. The degree of protection of at least IP66 to EN 60529 is only achieved if certified cable entries are used that are suitable for the application and correctly installed.

Unused apertures shall be closed with suitable blanking elements.

If conduit seals are used, they must be installed within 457 mm (18") of the enclosure.

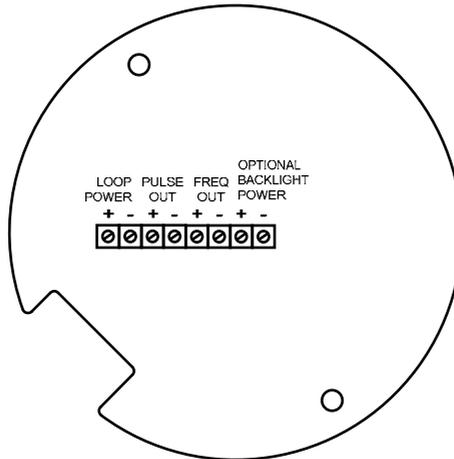


Fig. 13 Loop power wiring terminals

3.13 Input power connections

To access the wiring terminal blocks, locate and loosen the small set screw which locks the small enclosure cover in place. Unscrew the cover to expose the terminal block.

3.13.1 dc power wiring

Connect 4-20 mA loop power (12 to 36 Vdc at 25 mA, 1W max.) to the +Loop Power and -Loop Power terminals on the terminal block.

Torque all connections to 0.5 to 0.6 N-m (4.43 to 5.31 in lbs).

The dc power wire size must be 20 to 10 AWG with the wire stripped 7 mm (¼").

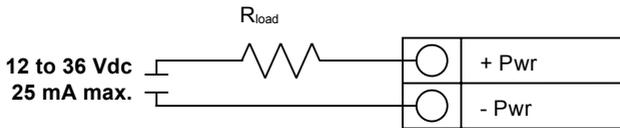


Fig. 14 dc power connections

3.14 4-20 mA output connections

The RIM20 flowmeter has a single 4-20 mA loop. The 4-20 mA loop current is controlled by the meter electronics. The electronics must be wired in series with the sense resistor or current meter. The current control electronics require 12 volts at the input terminals to operate correctly.

The maximum loop resistance (load) for the current loop output is dependent upon the supply voltage and is given in Figure 14. The 4-20 mA loop is optically isolated from the flowmeter electronics.

R_{load} is the total resistance in the loop, including the wiring resistance ($R_{load} = R_{wire} + R_{sense}$). To calculate R_{max} , the maximum R_{load} for the loop, subtract the minimum terminal voltage from the supply voltage and divide by the maximum loop current, 20 mA. Thus:

The maximum resistance $R_{load} = R_{max} = (V_{supply} - 12V) / 0.020 A$

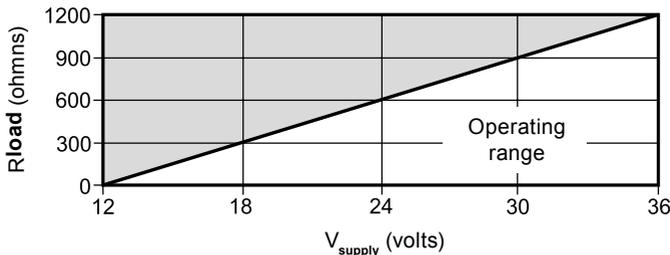


Fig. 15 Load Resistance Versus Input Voltage

3.15 Pulse output connections

The pulse output is used for a remote counter. When the preset volume or mass (defined in the totalizer settings, see Section 4) has passed the meter, the output provides a 50 millisecond square pulse.

The pulse output requires a separate 5 to 36 Vdc power supply. The pulse output optical relay is a normally-open single-pole relay. The relay has a nominal 200 volt/160 ohm rating. This means that it has a nominal on-resistance of 160 ohms, and the largest voltage that it can withstand across the output terminals is 200 volts. However, there are current and power specifications that must be observed. The relay can conduct a current up to 40 mA and can dissipate up to 320 mW. The relay output is isolated from the meter electronics and power supply.

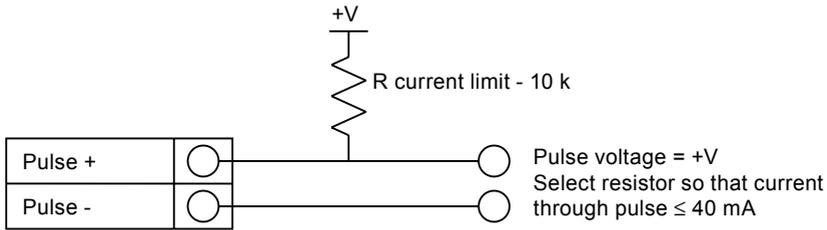


Fig. 16 Isolated pulse output using external power

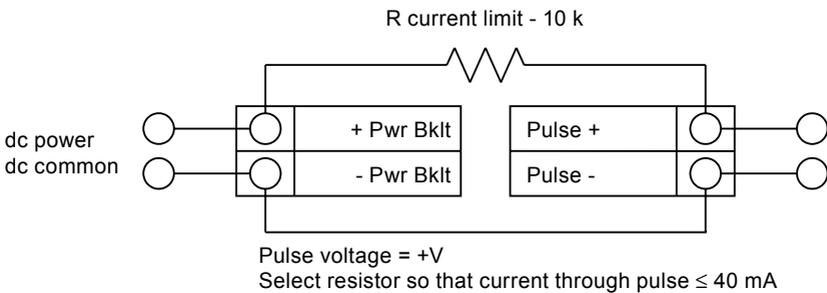


Fig. 17 Non-isolated pulse output using external power supply

3.16 Frequency output connections

The frequency output is used for a remote counter. It can be scaled to output a 1 to 10 kHz signal proportional to mass or volume flow, temperature, pressure or density.

The frequency output requires a separate 5 to 36 Vdc power supply; however, there are current and power specifications that must be observed.

The output can conduct a current up to 40 mA and can dissipate up to 200 mW. The output is isolated from the meter electronics and power supply.

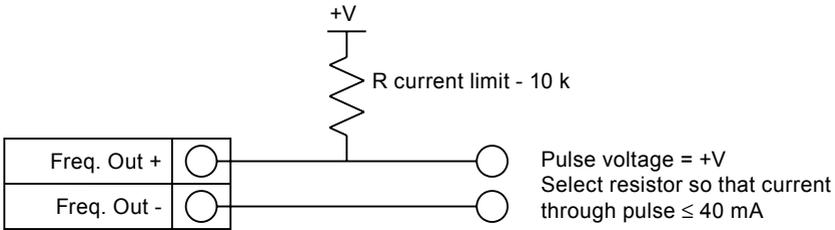


Fig. 18 Isolated pulse output using external power

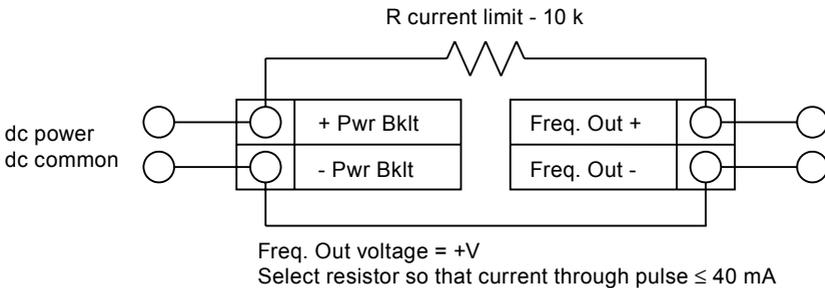


Fig. 19 Non-isolated frequency output using external power supply

3.17 Optional backlight connection

The loop power meter has an optional backlight connection provided. It is intended to be powered by a separate 12 to 36 Vdc at 35 mA max. power supply or by the pulse power input. Both options are shown below.

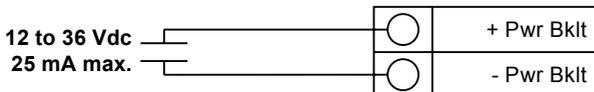


Fig. 20 Backlight using external power supply

3.18 Remote electronics wiring

The remote electronics enclosure should be mounted in a convenient, easy to reach location. For hazardous location installations, make sure to observe agency requirements for installation. Allow some slack in the interface cable between the junction box and the remote electronics enclosure.

To prevent damage to the wiring connections, do not put stress on the terminations at any time. The meter is shipped with temporary strain relief glands at each end of the cable. Disconnect the cable from the meter's terminal block inside the junction box-not at the remote electronics enclosure. Remove both glands and install appropriate conduit entry glands and conduit. The cable entry device shall be of a certified flameproof type, suitable for the conditions of use and correctly installed. The degree of protection of at least IP66 to EN 60529 is only achieved if certified cable entries are used that are suitable for the application and correctly installed. Unused apertures shall be closed with suitable blanking elements. When installation is complete, reconnect each labeled wire to the corresponding terminal position on the junction box terminal block. Make sure to connect each wire pair's shield.

Note: incorrect connection will cause the meter to malfunction.

Note: Numeric code in junction box label matches wire labels.

Fig. 21 Loop power volumetric flowmeter junction box sensor connections

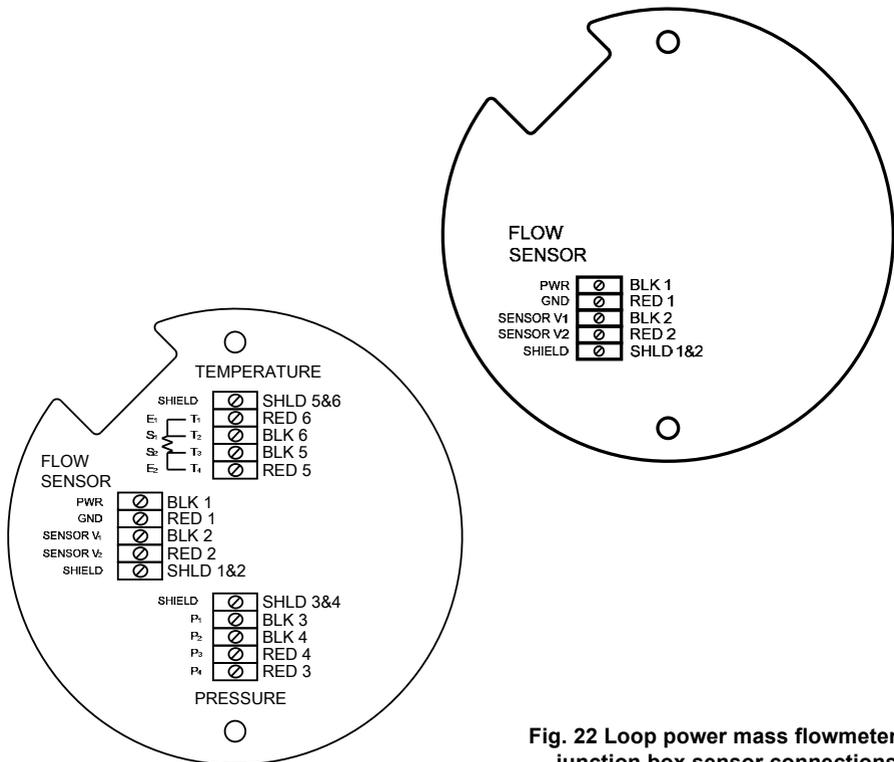


Fig. 22 Loop power mass flowmeter junction box sensor connections

3.19 High power flowmeter wiring connections



Warning!

To avoid potential electric shock, follow National Electric Code safety practices or your local code when wiring this unit to a power source and to peripheral devices. Failure to do so could result in injury or death. All ac power connections must be in accordance with published CE directives. All wiring procedures must be performed with the power off.

The NEMA 4X enclosure contains an integral wiring compartment located in the smaller end of the enclosure. Two ¾" female NPT conduit entries are available for separate power and signal wiring. For all hazardous area installations, make sure to use an agency-approved fitting at each conduit entry. The cable entry device shall be of a certified flameproof type, suitable for the conditions of use and correctly installed. The degree of protection of at least IP66 to EN 60529 is only achieved if certified cable entries are used that are suitable for the application and correctly installed.

Unused apertures shall be closed with suitable blanking elements.

If conduit seals are used, they must be installed within 457 mm (18") of the enclosure.

3.20 Input power connections



Caution!

The ac wire insulation temperature rating must meet or exceed 85 °C (185 °F).

To access the wiring terminal blocks, locate and loosen the small set screw which locks the small enclosure cover in place. Unscrew the cover to expose the terminal block.

3.20.1 ac power wiring

The ac power wire size must be 20 to 10 AWG with the wire stripped 7 mm (1/4").

The wire insulation temperature must meet or exceed 85 °C (185 °F).

Connect 100 to 240 Vac (5 W maximum) to the Hot and Neutral terminals on the terminal block.

Connect the ground wire to the safety ground lug (⊕).

Torque all connections to 0.5 to 0.6 N-m (4.43 to 5.31 in-lbs).

Use a separate conduit entry for signal lines to reduce the possibility of ac noise interference.

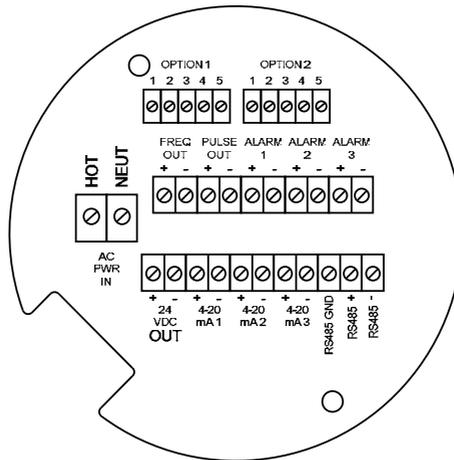


Fig. 23 ac wiring terminals

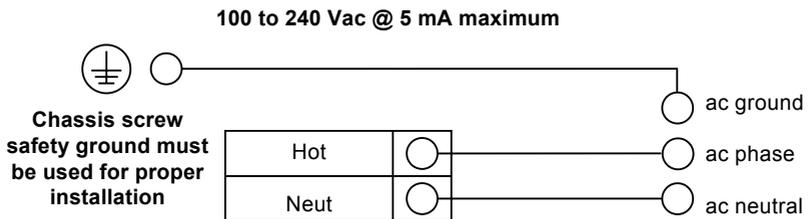


Fig. 24 ac power connections

3.20.2 dc power wiring



Caution!

The dc wire insulation temperature rating must meet or exceed 85 °C (185 °F).

The dc power wire size must be 20 to 10 AWG with the wire stripped 7 mm (¼"). Connect 18 to 36 Vdc (300 mA, 9 W maximum) to the +dc Pwr and -dc Pwr terminals on the terminal block.

Torque all connections to 0.5 to 0.6 N-m (4.43 to 5.31 in lbs).

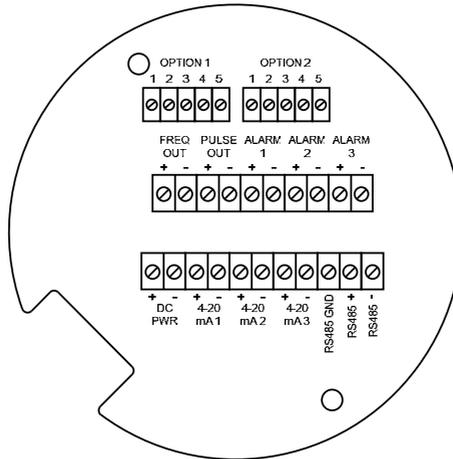


Fig. 25 dc wiring terminals

18 to 36 Vdc @ 25 mA max.

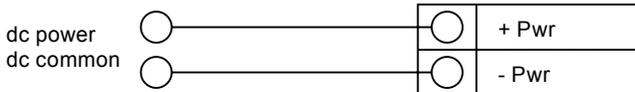


Fig. 26 dc Power Connections

3.21 4-20 mA output connections

The standard RIM20 flowmeter has a single 4-20 mA loop. Two additional loops are available on the optional communication board. The 4-20 mA loop current is controlled by the meter electronics. The electronics must be wired in series with the sense resistor or current meter. The current control electronics require 12 volts at the input terminals to operate correctly.

The maximum loop resistance (load) for the current loop output is dependent upon the supply voltage and is given in Figure 26. The 4-20 mA loop is optically isolated from the flowmeter electronics.

R_{load} is the total resistance in the loop, including the wiring resistance ($R_{load} = R_{wire} + R_{sense}$).

To calculate R_{max} , the maximum R_{load} for the loop, subtract the minimum terminal voltage from the supply voltage and divide by the maximum loop current, 20 mA. Thus:

$$\text{The maximum resistance } R_{load} = R_{max} = (V_{supply} - 12V) / 0.020 \text{ A}$$

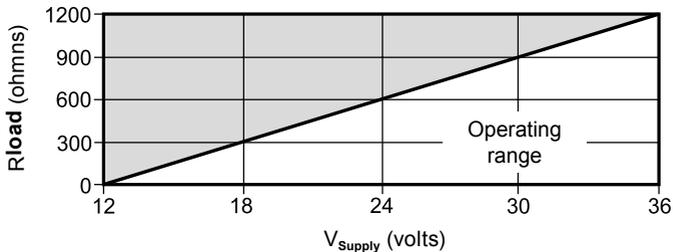


Fig. 27 Load resistance versus Input voltage

ac and dc powered flowmeters

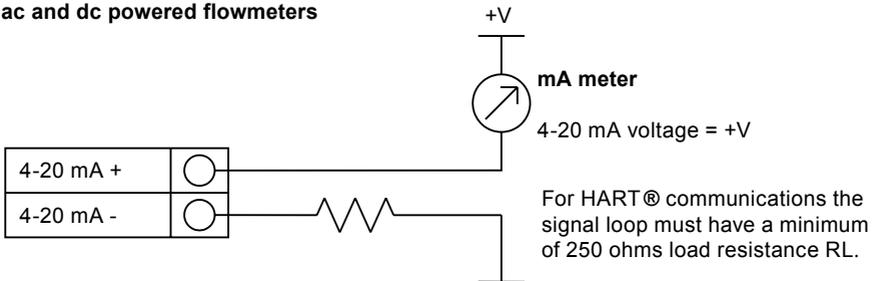


Fig. 28 Isolated 4-20 mA output with external power supply

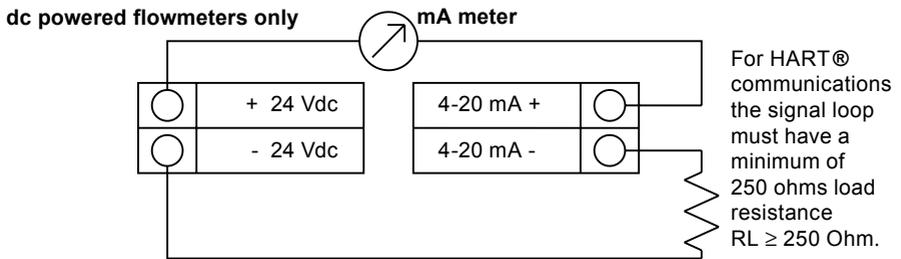


Fig. 29 Non-isolated 4-20 mA output using flowmeter input power supply

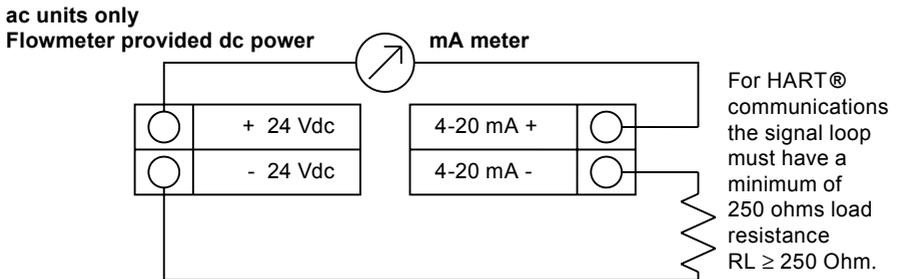


Fig. 30 Isolated 4-20 mA output using meter provided power supply

3.22 Frequency output connections

The frequency output is used for a remote counter. It can be scaled to output a 1 to 10 kHz signal proportional to mass or volume flow, temperature, pressure or density.

The frequency output requires a separate 5 to 36 Vdc power supply; however, there are current and power specifications that must be observed.

The output can conduct a current up to 40 mA and can dissipate up to 200 mW. The output is isolated from the meter electronics and power supply.

There are three connection options for the frequency output—the first with a separate power supply (Figure 31), the second using the flowmeter power supply (Figure 32)(dc powered units only), and the third using the internal 24 Vdc power supply (Figure 33)(ac powered units only). Use the first option with a separate power supply (5 to 36 Vdc) if a specific voltage is needed for the frequency output. Use the second configuration if the voltage at the flowmeter power supply is an acceptable driver voltage for the load connected. (Take into account that the current used by the frequency load comes from the meter's power supply). Use the third configuration if you have an ac powered unit only. In any case, the voltage of the frequency output is the same as the voltage supplied to the circuit.

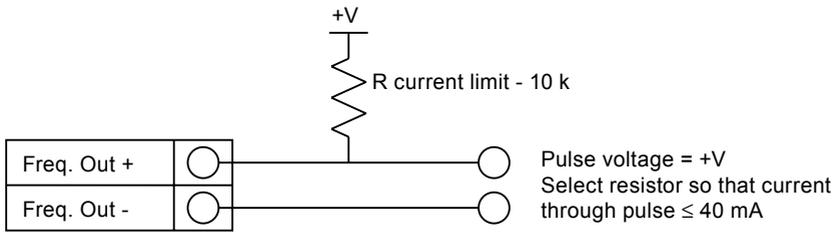


Fig. 31 Isolated frequency output using external power supply

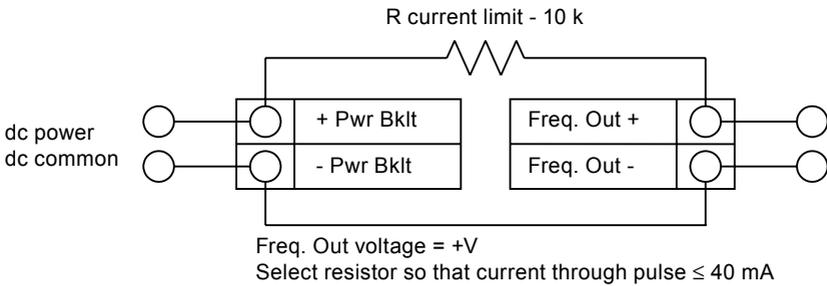


Fig. 32 Non-isolated frequency output using input power supply

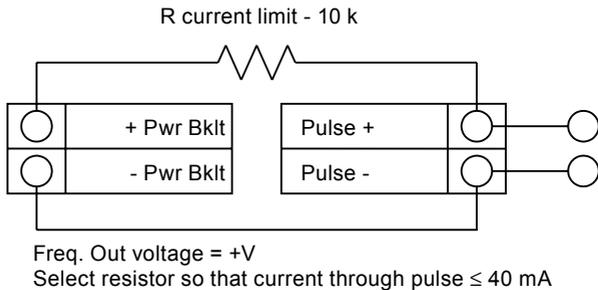


Fig. 33 Isolated frequency output using meter provided power supply

3.23 Pulse output connections

The pulse output is used for a remote counter. When the preset volume or mass (defined in the totalizer settings, see Section 4) has passed the meter, the output provides a 50 millisecond square pulse.

The pulse output optical relay is a normally-open single-pole relay. The relay has a nominal 200 volt/160 ohm rating. This means that it has a nominal on-resistance of 160 ohms, and the largest voltage that it can withstand across the output terminals is 200 volts. However, there are current and power specifications that must be observed. The relay can conduct a current up to 40 mA and can dissipate up to 320 mW. The relay output is isolated from the meter electronics and power supply.

There are three connection options for the pulse output—the first with a separate power supply (Figure 34), the second using the flowmeter power supply (Figure 35)(dc powered units only), and the third using the internal 24 Vdc power supply (Figure 36)(ac powered units only). Use the first option with a separate power supply (5 to 36 Vdc) if a specific voltage is needed for the pulse output. Use the second configuration if the voltage at the flowmeter power supply is an acceptable driver voltage for the load connected. (Take into account that the current used by the pulse load comes from the meter's power supply). Use the third configuration if you have an ac powered unit only. In any case, the voltage of the pulse output is the same as the voltage supplied to the circuit.

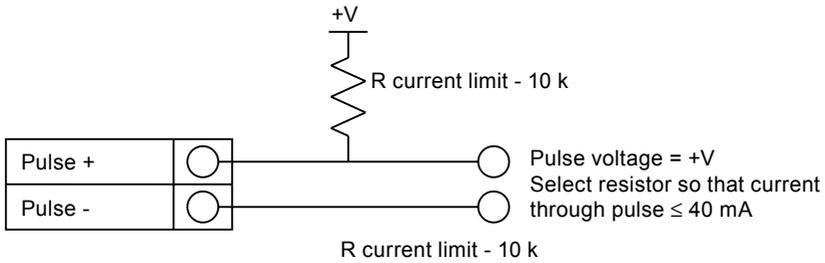


Fig. 34 Isolated pulse output with external power supply

dc powered flowmeters

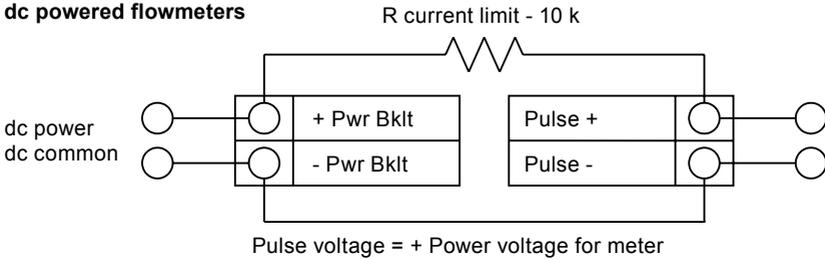


Fig. 35 Non-isolated pulse output using input power supply

ac units only

Flowmeter provided dc power

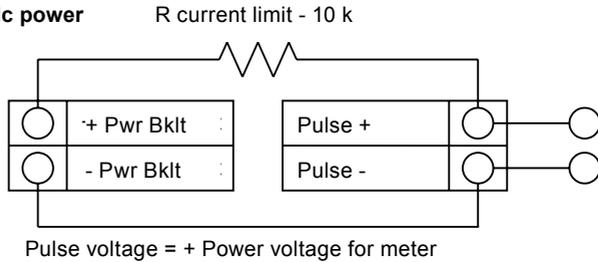


Fig. 36 Isolated pulse output using flowmeter provided power supply

3.24 Alarm output connections

One alarm output (Alarm 1) is included on the standard RIM20 flowmeter. Two or more alarms (Alarm 2 and Alarm 3) are included on the optional communication board. The alarm output optical relays are normally- open single-pole relays. The relays have a nominal 200 volt/160 ohm rating. This means that each relay has a nominal on-resistance of 160 ohms and the largest voltage that it can withstand across the output terminals is 200 volts. However, there are current and power specifications that must be observed. The relay can conduct a current up to 40 mA and can dissipate up to 320 mW. The relay output is isolated from the meter electronics and power supply. When the alarm relay is closed, the current draw will be constant. Make sure to size Rload appropriately.

There are three connection options for the alarm output-the first with a separate power supply (Figure 37), the second using the flowmeter power supply (Figure 38)(dc powered units only) and the third with the meter provided power supply (Figure 39)(ac powered units only). Use the first option with a separate power supply (5 to 36 Vdc) if a specific voltage is needed for the alarm output. Use the second configuration if the voltage at the flowmeter power supply is an acceptable driver voltage for the load connected. (Take into account that the current used by the alarm load comes from the meter's power supply). Use the third if you have an ac powered unit only. In any case, the voltage of the alarm output is the same as the voltage supplied to the circuit.

The alarm output is used for transmitting high or low process conditions as defined in the alarm settings (see Section 4).

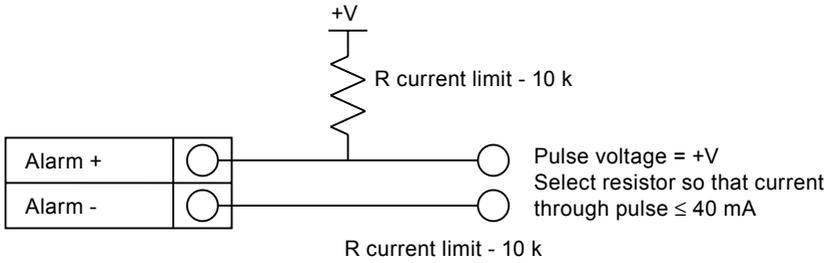


Fig. 37 Isolated pulse output with external power supply

dc powered flowmeters

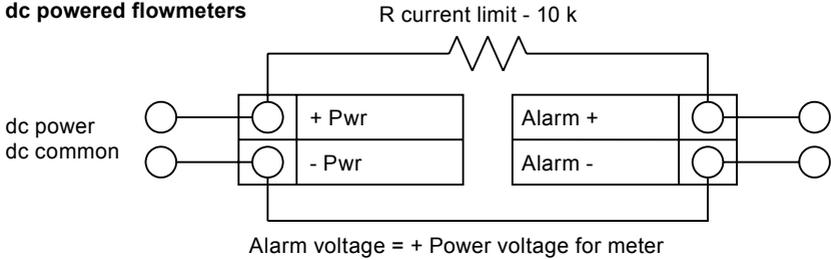


Fig. 38 Non-isolated pulse output using input power supply

ac units only

Flowmeter provided dc power

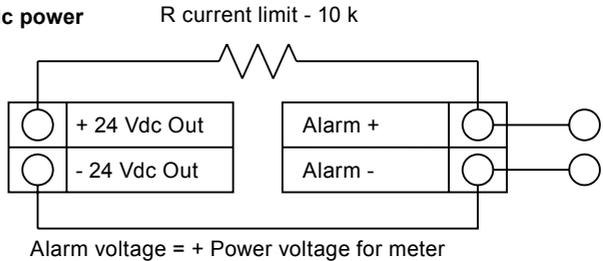


Fig. 39 Isolated pulse output using flowmeter provided power supply

3.25 Remote electronics wiring

The remote electronics enclosure should be mounted in a convenient, easy to reach location. For hazardous location installations, make sure to observe agency requirements for installation. Allow some slack in the interface cable between the junction box and the remote electronics enclosure.

To prevent damage to the wiring connections, do not put stress on the terminations at any time.

The meter is shipped with temporary strain relief glands at each end of the cable. Disconnect the cable from the meter's terminal block inside the junction box-not at the remote electronics enclosure. Remove both glands and install appropriate conduit entry glands and conduit. The cable entry device shall be of a certified flameproof type, suitable for the conditions of use and correctly installed. The degree of protection of at least IP66 to EN 60529 is only achieved if certified cable entries are used that are suitable for the application and correctly installed. Unused apertures shall be closed with suitable blanking elements. When installation is complete, reconnect each labeled wire to the corresponding terminal position on the junction box terminal block. Make sure to connect each wire pair's shield.

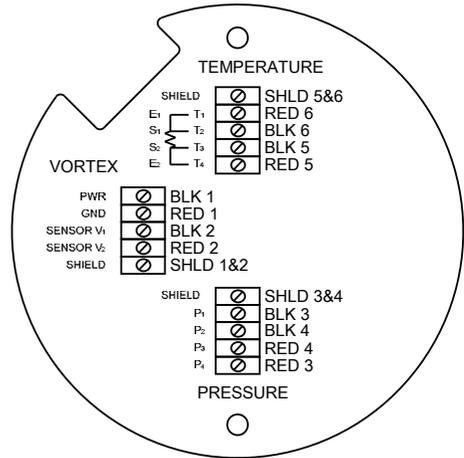


Fig. 40 High Power flowmeter junction box sensor connections

Note: incorrect connection will cause the meter to malfunction.

Note: Numeric code in junction box label matches wire labels.

3.26 Optional input electronics wiring

The meter has two optional input wiring terminals. These can be used to input a Remote or Second RTD input in the case of an Energy Monitoring meter, for the input of a Remote Pressure Transducer, to pass a Contact Closure or for a Remote Density measurement to name a few. In any case, the wiring diagram will be included with the meter if any of the options are specified. Otherwise, the optional terminal blocks will be left blank and non functional.

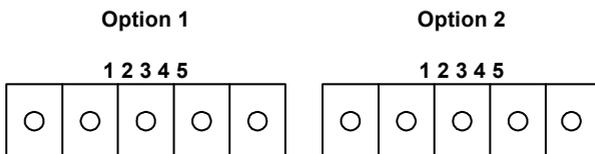


Fig. 41

3.27 Optional Energy EMS RTD Input Wiring

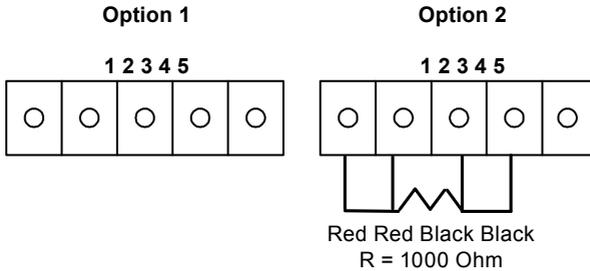


Fig. 42 Optional energy EMS RTD input wiring

The recommended customer supplied second RTD is a Class A 1000 ohm 4-wire platinum RTD. If a second RTD is not being used, then the factory supplied 1000 ohm resistor needs to be installed in its place.

3.28 Optional external 4-20 mA input wiring

The meter is set to have Option 1 used for the external input. Programming menus that pertain to the optional 4-20 mA input are located in the Hidden Diagnostics Menu in Section 5.

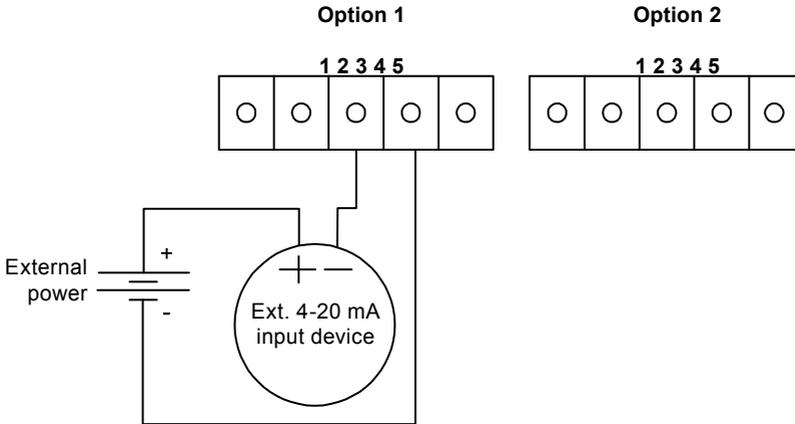


Fig. 43 External 4-20 mA input wiring - External power supply

Follow the above diagram to wire the external 4-20 mA input into the flowmeter using an external power supply.

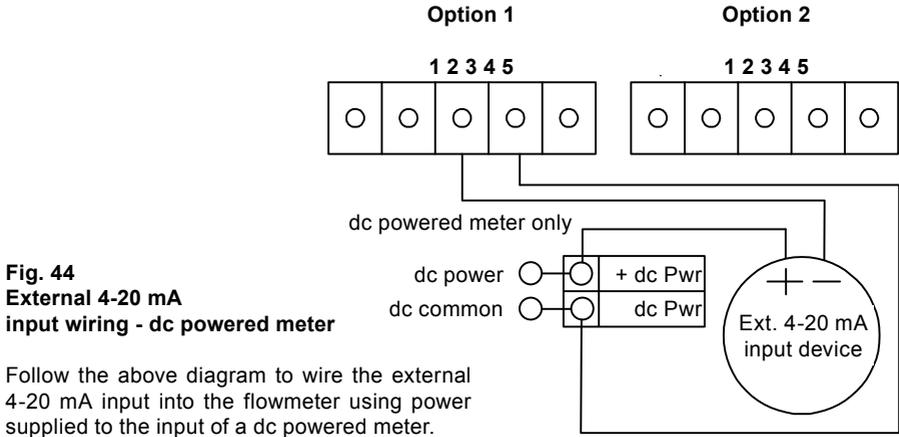


Fig. 44
External 4-20 mA
input wiring - dc powered meter

Follow the above diagram to wire the external 4-20 mA input into the flowmeter using power supplied to the input of a dc powered meter.

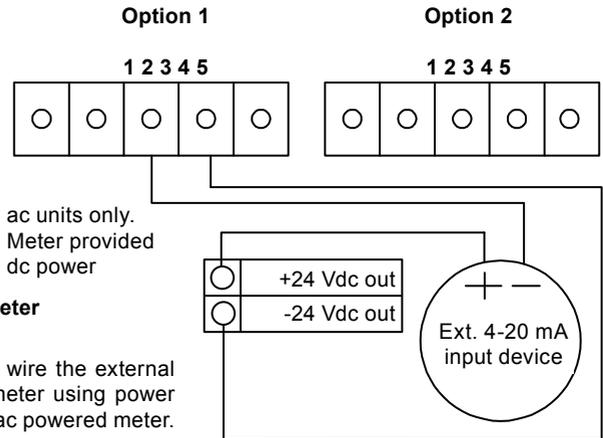


Fig. 45
External 4-20 mA
input wiring - ac powered meter

Follow the above diagram to wire the external 4-20 mA input into the flowmeter using power from the 24 Vdc output of an ac powered meter.

3.29 Optional external contact closure input wiring

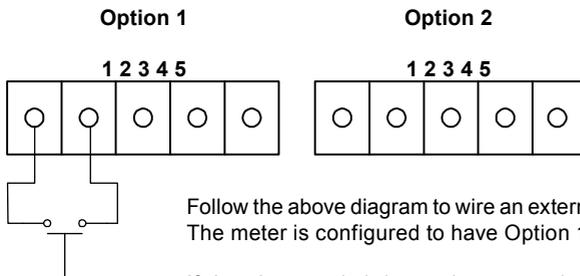


Fig. 46
Optional external contact
closure input wiring

Follow the above diagram to wire an external switch input into the flowmeter. The meter is configured to have Option 1 used for the external input.

If the above switch is used to remotely reset the totalizer a pushbutton switch with a momentary contact closure is recommended.

4. Operating instructions

After installing the RIM20 rotor insertion flowmeter, you are ready to begin operation. The sections in this Section explain the display/keypad commands, meter start-up and programming.

The meter is ready to operate at start up without any special programming.

To enter parameters and system settings unique to your operation, see the following pages for instructions on using the setup menus.

4.1 Flowmeter display/keypad

The flowmeter's digital electronics allow you to set, adjust and monitor system parameters and performance. A full range of commands are available through the display/keypad. The LCD display gives 2 x 16 characters for flow monitoring and programming.

The six push-buttons can be operated with the enclosure cover removed. Or, the explosion-proof cover can remain in place and the keypad operated with a hand-held magnet positioned at the side of the enclosure as shown in Figure 47.

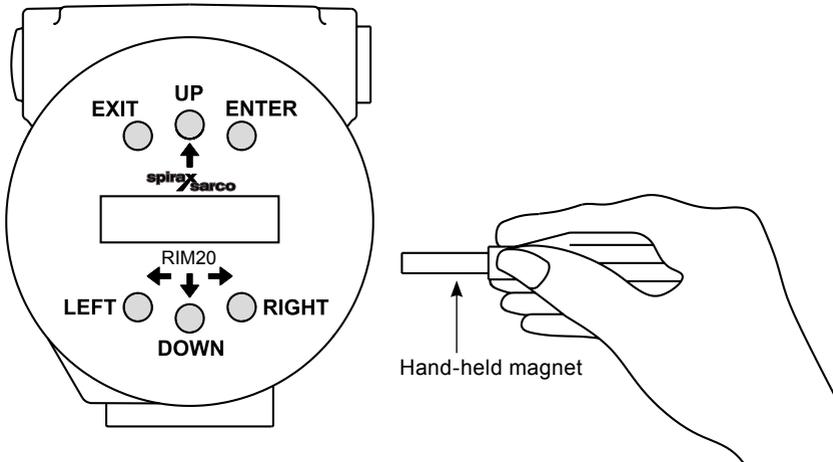


Fig. 47 Display/keypad commands

From the Run mode, the ENTER key allows access to the Setup Menu (through a password screen). Within the Setup Menu, pressing ENTER activates the current field.

To set new parameters, press the ENTER key until an underline cursor appears.

Use \uparrow \downarrow \leftarrow \rightarrow the keys to select new parameters.

Press ENTER to continue. (If change is not allowed, ENTER has no effect.) All outputs are disabled when using the Setup Menu.

The EXIT key is active within the Setup Menu.

When using a Setup Menu, EXIT returns you to the Run mode. If you are changing a parameter and make a mistake, EXIT allows you to start over.

The \uparrow \downarrow \leftarrow \rightarrow keys advance through each screen of the current menu. When changing a system parameter, all \uparrow \downarrow \leftarrow \rightarrow keys are available to enter new parameters.

4.2 Start-up



Note

Starting the flowmeter or pressing EXIT will always display the Run mode screens.

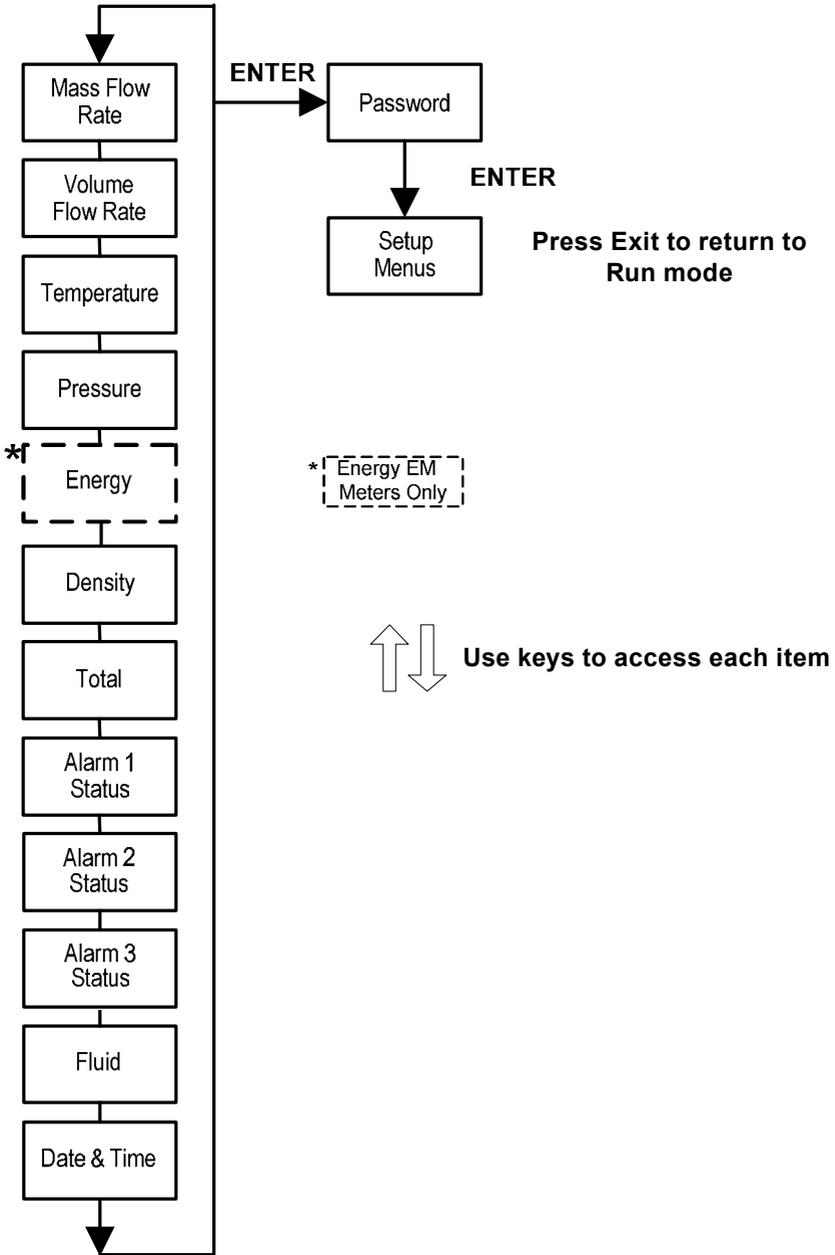
To begin flowmeter operation:

1. Verify the flowmeter is installed and wired as described in Section 3.
2. Apply power to the meter. At start up, the unit runs a series of selftests that check the RAM, ROM, EPROM and all flow sensing components.

After completing the self-test sequence, the Run mode screens appear.

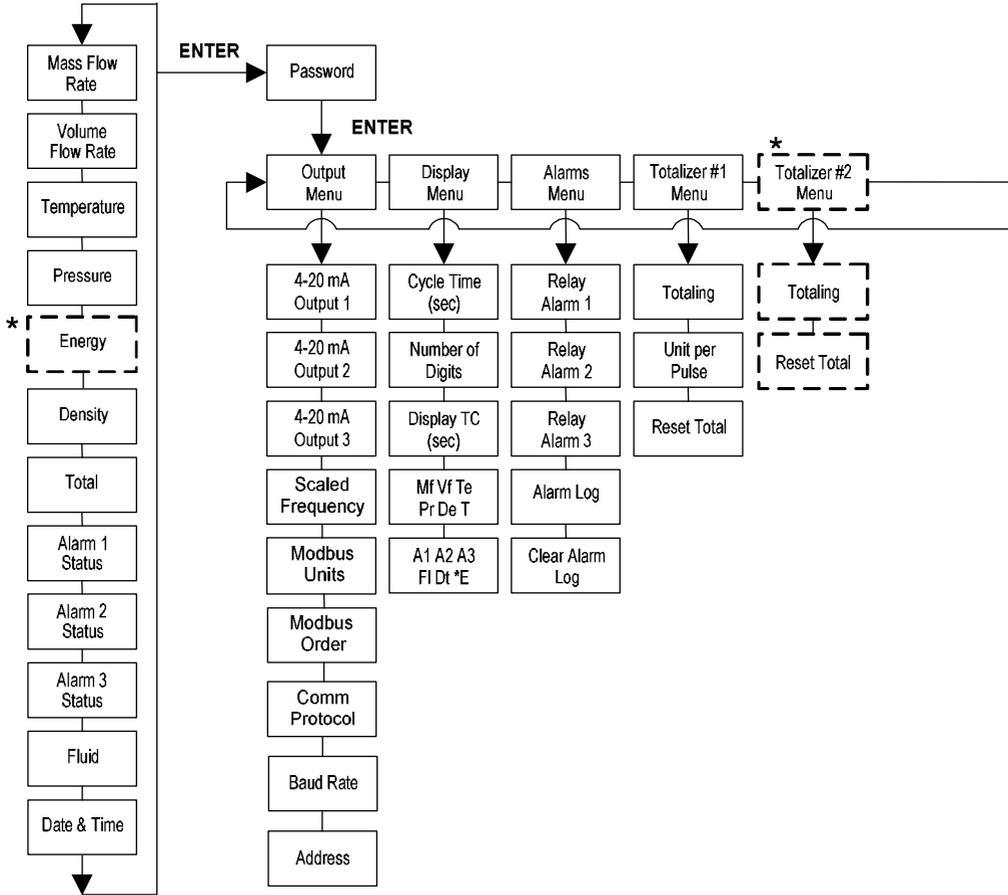
3. The Run mode displays flow information as determined by system settings. Some screens depicted on the next page may not be displayed based on these settings. Press the arrow keys to view the Run mode screens.
4. Press the ENTER key from any Run mode screen to access the Setup Menus. Use the Setup Menus to configure the meter's multiparameter features to fit your application.

Run mode screens

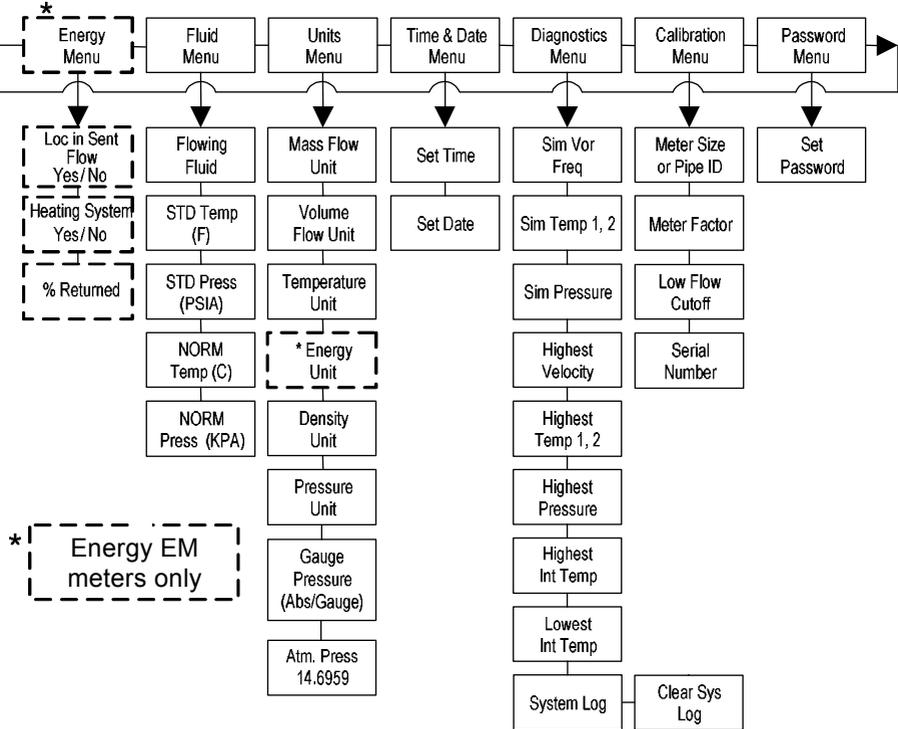


4.3 Using the set-up menus

Run mode screens



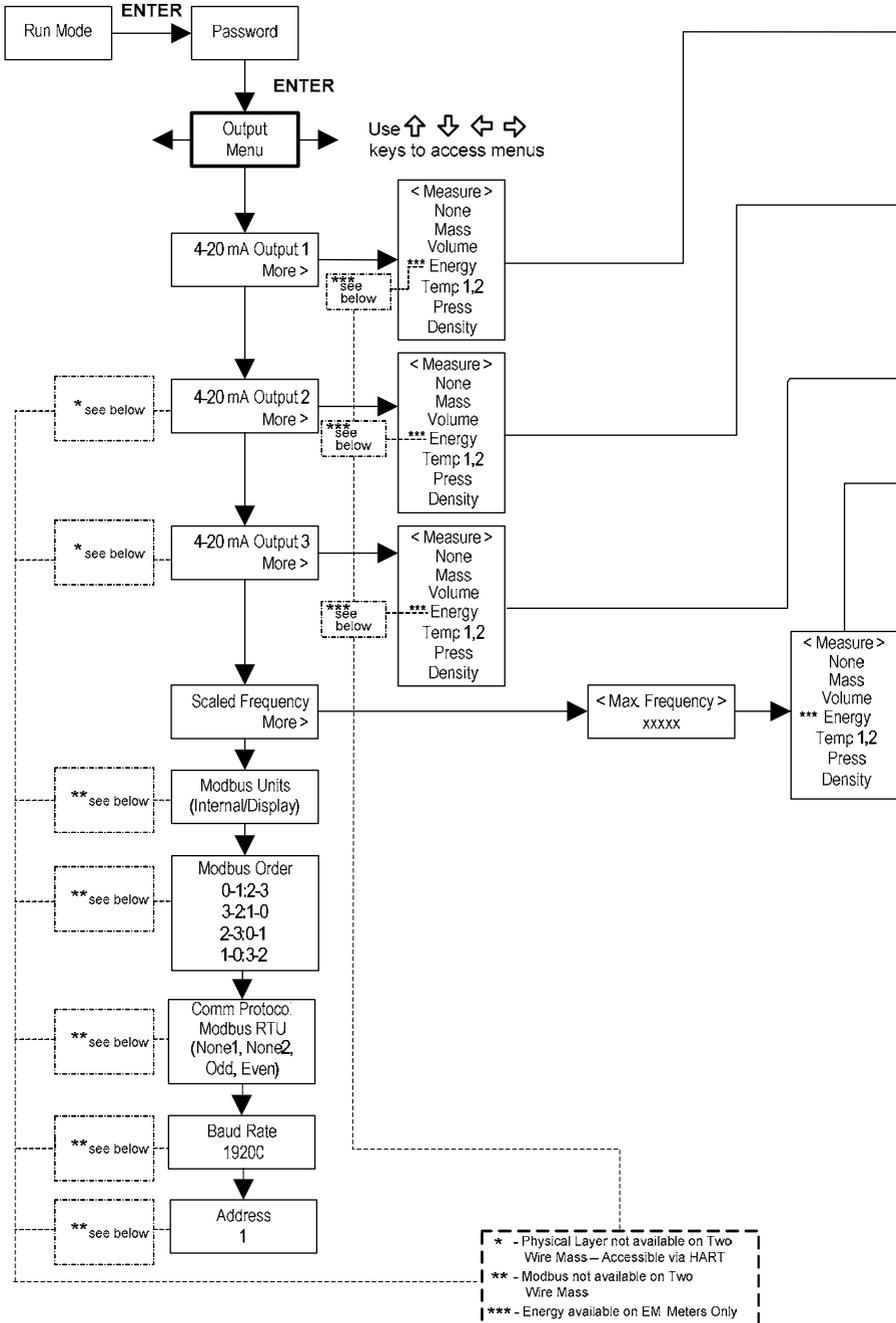
Setup menus

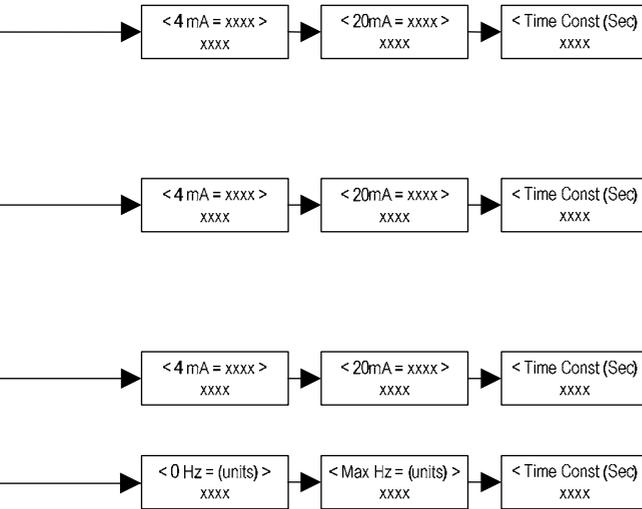


4.4 Programming the flowmeter

1. Enter the Setup Menu by pressing the ENTER key until prompted for a password. (All outputs are disabled while using the Setup Menus.)
2. Use the $\uparrow\downarrow\leftarrow\rightarrow$ keys to select the password characters (1234 is the factory-set password). When the password is correctly displayed, press ENTER to continue.
3. Use the Setup Menus described on the following pages to customize the multiparameter features of your RIM20 flowmeter. (The entire lower display line is available for entering parameters.) Some items depicted in the graphic on the preceding page may not be displayed based on flowmeter configuration settings
4. To activate a parameter, press ENTER. Use the $\uparrow\downarrow\leftarrow\rightarrow$ keys to make selections. Press ENTER to continue. Press EXIT to save or discard changes and return to Run mode.
5. Program the UNITS menu first because later menus will be based on the units selected.

4.5 Output menu





Example for setting an output

The following shows how to set Output 1 to measure mass flow with 4 mA = 0 lb/hr and 20 mA = 100 lb/hr with a time constant of 5 seconds. (All outputs are disabled while using the Setup Menus.)

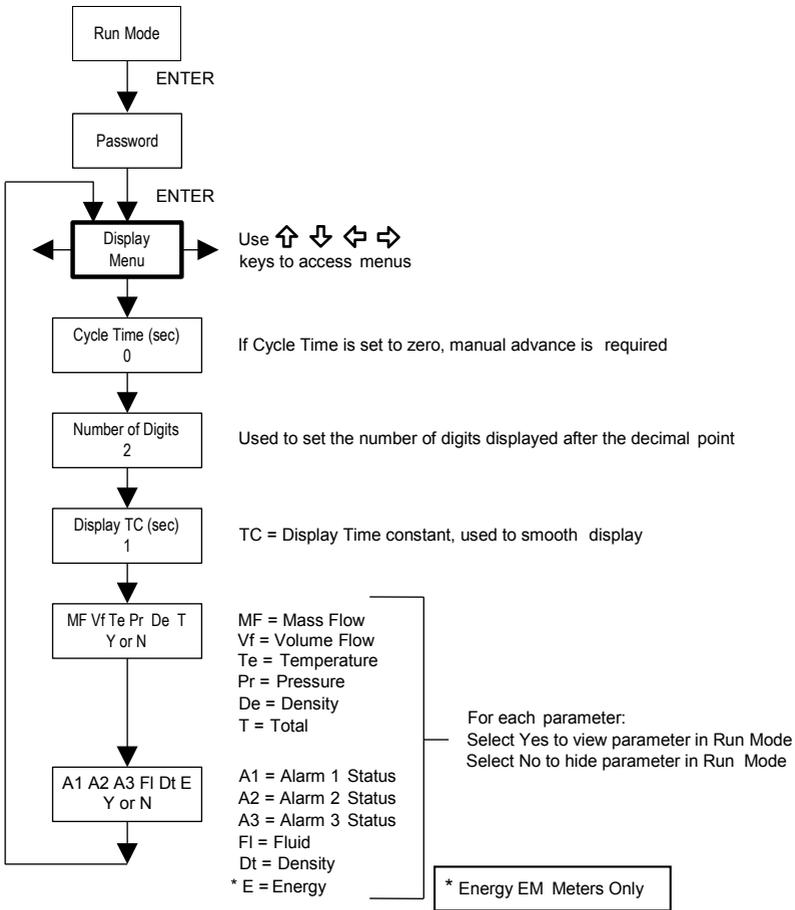
First, set the desired units of measurement:

1. Use $\uparrow\downarrow\leftarrow\rightarrow$ keys to move to the Units Menu.
2. Press key until Mass Flow Unit appears. Press ENTER.
3. Press key until lb appears in the numerator. Press \rightarrow key to move the underline cursor to the denominator. Press the key until hr appears in the denominator. Press ENTER to select.
4. Press key until Units Menu appears.

Second, set the Analogue output:

1. Use $\uparrow\downarrow\leftarrow\rightarrow$ keys to move to the Output Menu.
2. Press the key until 4-20 mA Output 1 appears.
3. Press \rightarrow key to access Measure selections. Press ENTER and press the key to select Mass. Press ENTER.
4. Press \rightarrow key to set the 4 mA point in the units you have selected for mass of lb/hr. Press ENTER and use $\uparrow\downarrow\leftarrow\rightarrow$ keys to set 0 or 0.0. Press ENTER.
5. Press \rightarrow key to set the 20 mA point. Press ENTER and use $\uparrow\downarrow\leftarrow\rightarrow$ keys to set 100 or 100.0. Press ENTER.
6. Press \rightarrow key to select the Time Constant. Press ENTER and use $\uparrow\downarrow\leftarrow\rightarrow$ keys to select 5. Press ENTER.
7. Press the EXIT key and answer YES to permanently save your changes.

4.6 Display menu



Use the Display Menu to set the cycle time for automatic screen sequencing used in the Run Mode, change the precision of displayed values, smooth the values or enable or disable each item displayed in the Run mode screens.

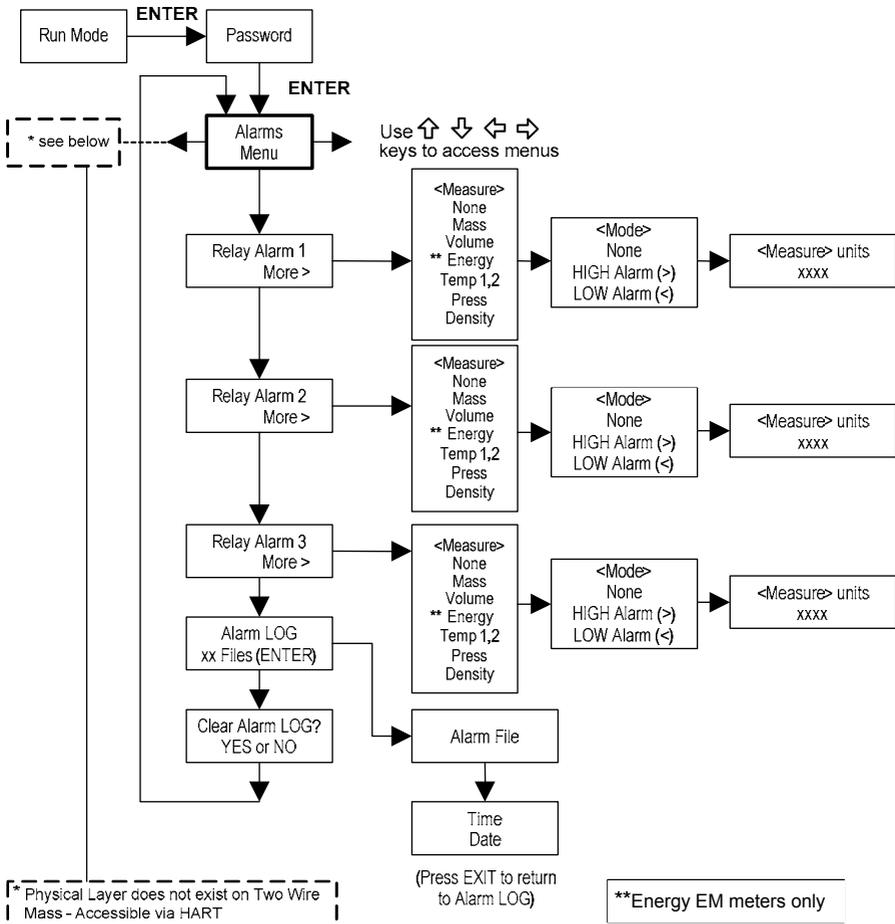
Example for changing a run mode display item

The following shows how to remove the temperature screen from the Run mode screens.

Note: all outputs are disabled while using the Setup Menus.

1. Use ⇐⇒ keys to move to the Display Menu.
2. Press ↓ key until Mf Vf Pr Te De T appears.
3. Press ENTER to select. Press ⇒ key until the cursor is positioned below Te.
4. Press ↓ key until N appears. Press ENTER to select.
5. Press EXIT and then ENTER to save changes and return to the Run mode.

4.7 Alarms menu



Example for setting an alarm

The following shows how to set Relay Alarm 1 to activate if the mass flowrate is greater than 100 lb/hr. You can check the alarm configuration in the Run mode by pressing the keys until Alarm [1] appears. The lower line displays the mass flowrate at which the alarm activates. Note: all outputs are disabled while using the Setup Menus.

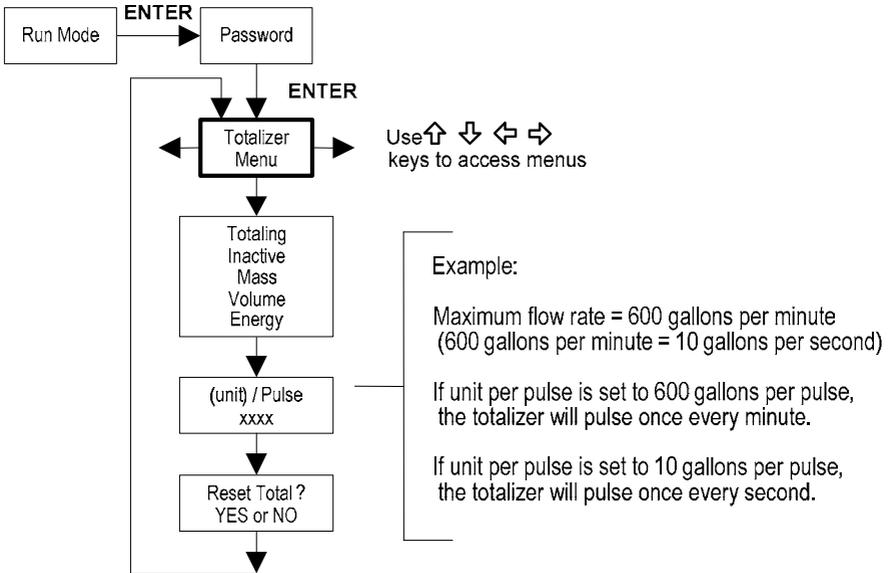
First, set the desired units of measurement:

1. Use ⇐⇒ keys to move to the Units Menu.
2. Press ↓ key until Mass Flow Unit appears. Press ENTER.
3. Press ↓ key until lb appears in the numerator. Press ⇒ key to move the underline cursor to the denominator. Press the ↓ key until hr appears in the denominator. Press ENTER to select.
4. Press ↑ key until Units Menu appears.

Second, set the alarm:

1. Use ⇐⇒ keys to move to the Alarms Menu.
2. Press the ↓ key until Relay Alarm 1 appears.
3. Press ⇒ key to access Measure selections. Press ENTER and use the key to select Mass. Press ENTER.
4. Press ⇒ key to select the alarm Mode. Press ENTER and use key to select HIGH Alarm. Press ENTER.
5. Press ⇒ key to select the value that must be exceeded before the alarm activates. Press ENTER and use ↑↓⇐⇒ keys to set 100 or 100.0. Press ENTER.
6. Press the EXIT key to save your changes. (Alarm changes are always permanently saved.) (Up to three relay alarm outputs are available depending on meter configuration.)

4.8 Totalizer #1 menu



Use the Totalizer Menu to configure and monitor the totalizer. The totalizer output is a 50 millisecond (.05 second) positive pulse (relay closed for 50 milliseconds). The totalizer cannot operate faster than one pulse every 100 millisecond (0.1 second). A good rule to follow is to set the unit per pulse value equal to the maximum flow in the same units per second. This will limit the pulse to no faster than one pulse every second.

Example for setting an alarm

The following shows how to set the totalizer to track mass flow in kg/sec. (All outputs are disabled while using the Setup Menus.)

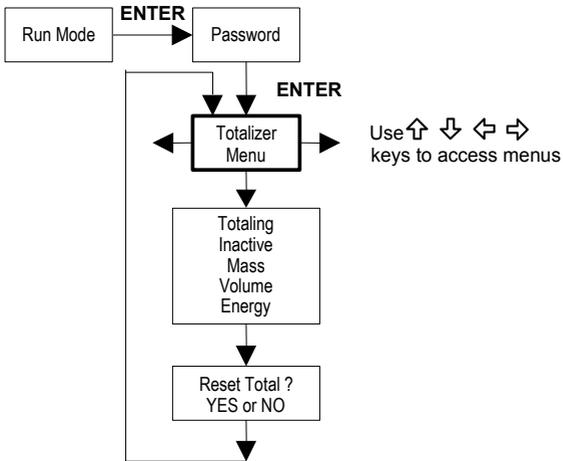
First, set the desired units of measurement:

1. Use $\leftarrow\rightarrow$ keys to move to the Units Menu.
2. Press \downarrow key until Mass Flow Unit appears. Press ENTER.
3. Press \downarrow key until kg appears in the numerator. Press \downarrow key to move the underline cursor to the denominator. Press the \downarrow key until sec appears in the denominator. Press ENTER to select.
4. Press \uparrow key until Units Menu appears.

Second, set the pulse output:

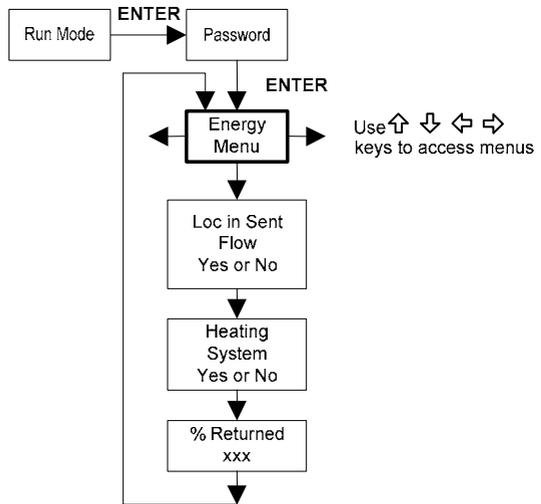
1. Use $\leftarrow\rightarrow$ keys to move to the Totalizer Menu.
2. Press the \downarrow key until Totaling appears.
3. Press ENTER and press the \downarrow key to select Mass. Press ENTER.
4. Press \downarrow key to set the pulse output in the units you have selected for mass flow of kg/sec. Press ENTER and use $\uparrow\downarrow\leftarrow\rightarrow$ keys to set the pulse value equal to the maximum flow in the same units per second. Press ENTER.
5. To reset the totalizer, press \downarrow key until Reset Total? appears. Press ENTER and the key to reset the totalizer if desired. Press ENTER.
6. Press the EXIT key and answer YES to permanently save your changes.

4.9 Totalizer #2 menu



Use the Totalizer #2 to Monitor Flow or Energy. Note that Totalizer #2 does not operate a relay, it is for monitoring only.

4.10 Energy menu - For EM energy meters only



Configuration:

There are several possibilities regarding the measurement of water or steam energy given the location of the meter and the use of a second RTD. The table below summarizes the possibilities:

| Fluid | Meter location | Second RTD | Measurement |
|-------|--------------------|---------------------------------|------------------|
| Water | "Sent" Flow Line | "Return" Flow Line | Change in Energy |
| Water | "Return" Flow Line | "Sent" Flow Line | Change in Energy |
| Water | "Sent" Flow Line | None | Outgoing Energy |
| Steam | "Sent" Flow Line | "Return" Flow Line (condensate) | Change in Energy |
| Steam | "Sent" Flow Line | None | Outgoing Energy |

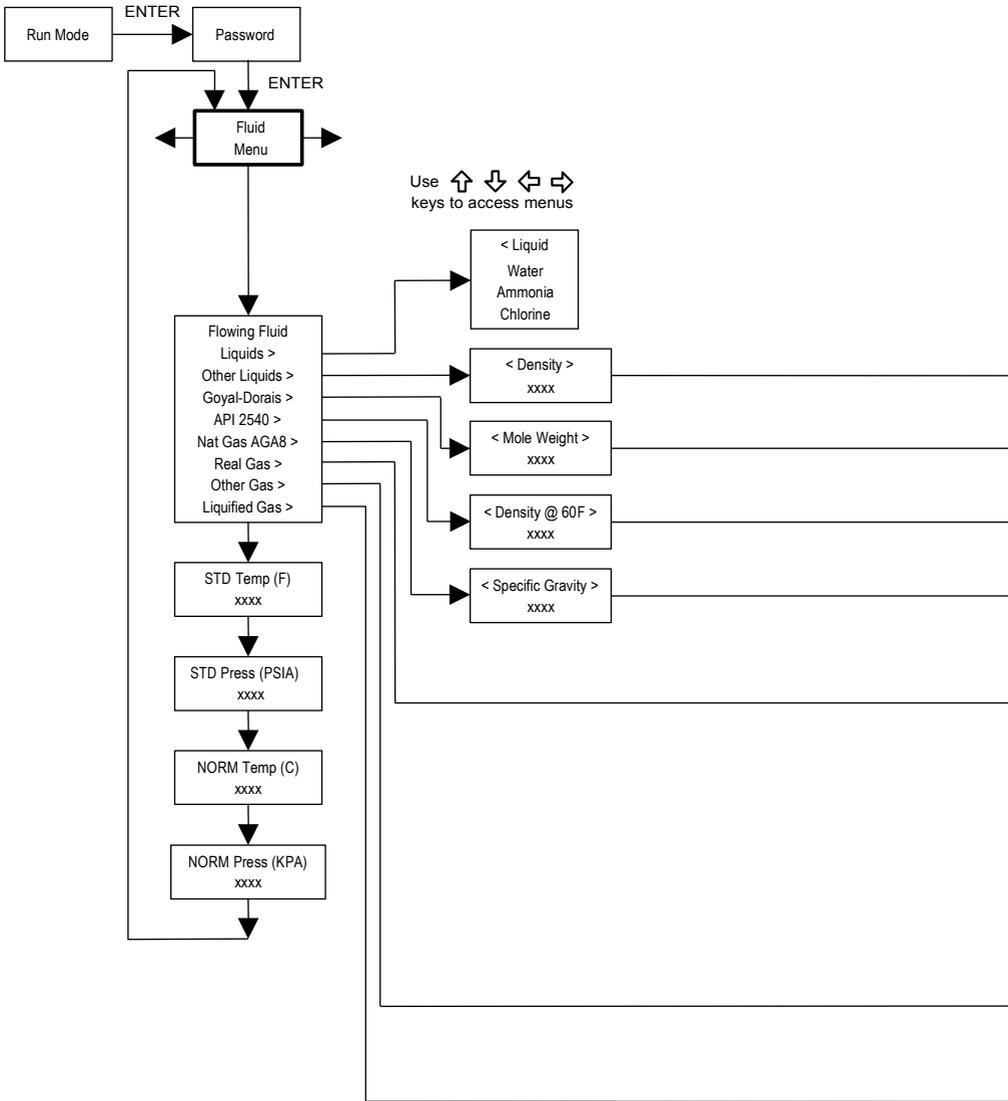
As above, you must properly configure the meter in the Energy Menu.

1. Loc in Sent Flow? Select Yes or No based on where the meter is located. Refer to the above table
2. Heating System? Select Yes for a hot water system used for heating. Select No for a chilled water system used for cooling. Always select Yes for a steam system.
3. % Returned. Select a number between 0% and 100%. Estimate the amount of water that returns.

It is usually 100%, or can be less than 100% if historical data shows the amount of makeup water used. If a second RTD is not used, set to 0%. When 0% is selected, the energy calculation represents the outgoing energy only (no return energy is subtracted).

NOTE: the meter ships from the factory assuming 0% return and has a 1000 ohm resistor installed in the RTD #2 wiring location. This needs to be removed if the meter is to be used in a manner other than with 0% return and with the customer supplied RTD in its place.

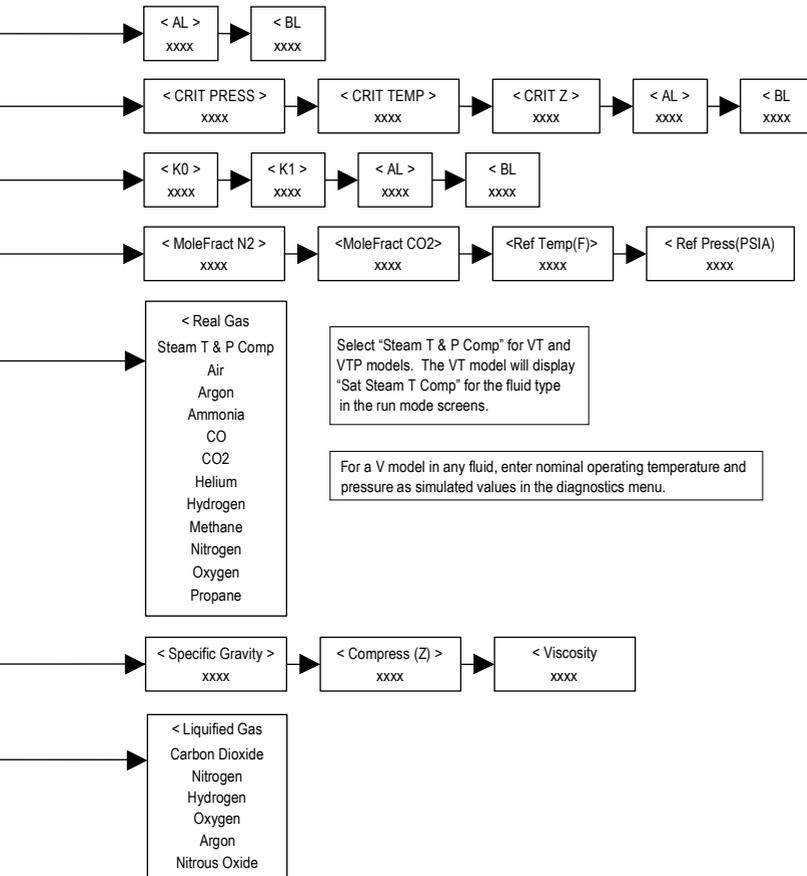
4.11 Fluid menu



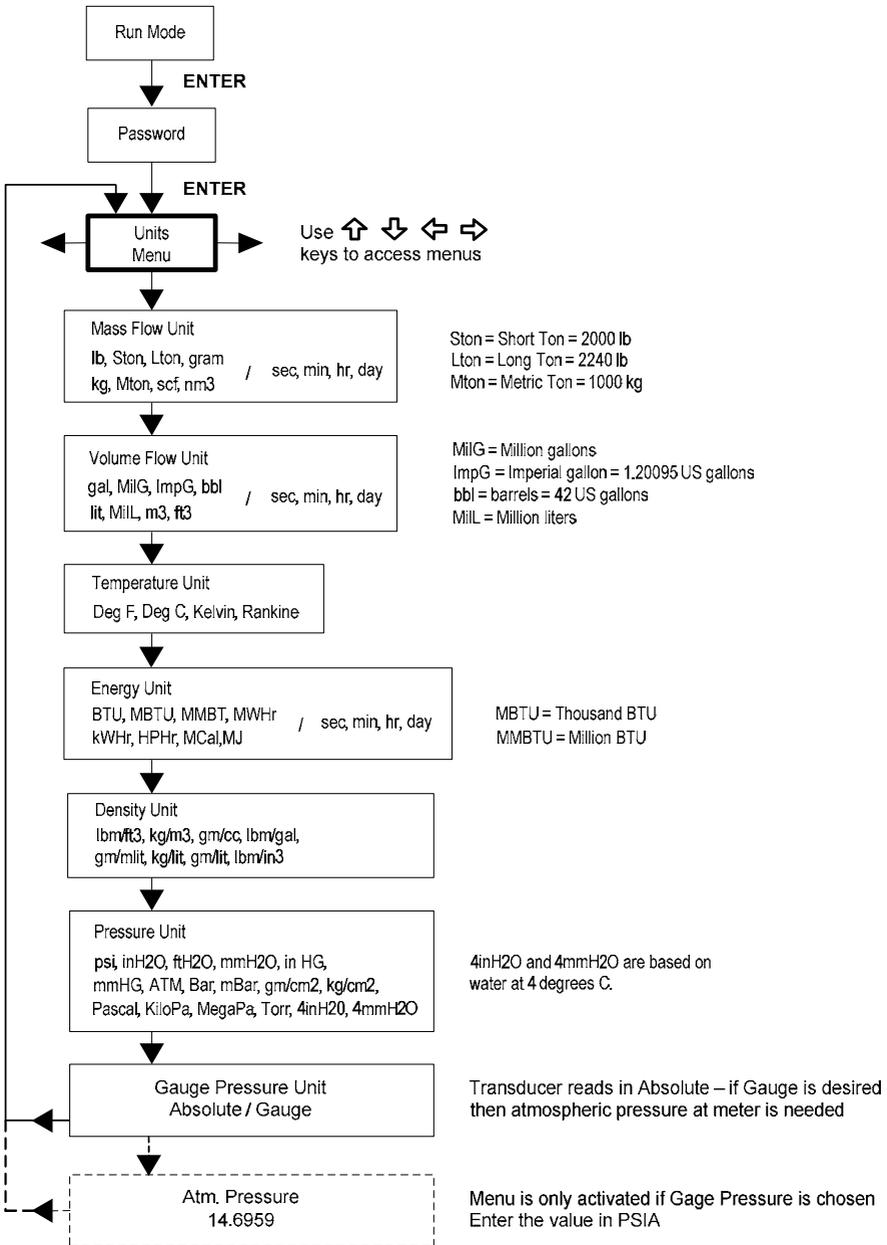
Use the Fluid Menu to configure the flowmeter for use with common gases, liquids and steam. Your flowmeter is pre-programmed at the factory for your application's process fluid. Reference Richard W. Miller, Flow Measurement Engineering Handbook (Third Edition, 1996), for definition and use of the Goyal-Doraiswamy equation and for the definition and use of the API 2540 equation. See Appendix C for Fluid Calculation equations.

The units of measurement used in the Fluid Menu are preset and are as follows:

- Mole Weight = lbm/(lbm-mol),
- CRIT PRESS = psi a,
- CRIT TEMP = °R,
- Density = Kg/m³ and
- Viscosity = cP (centipoise).

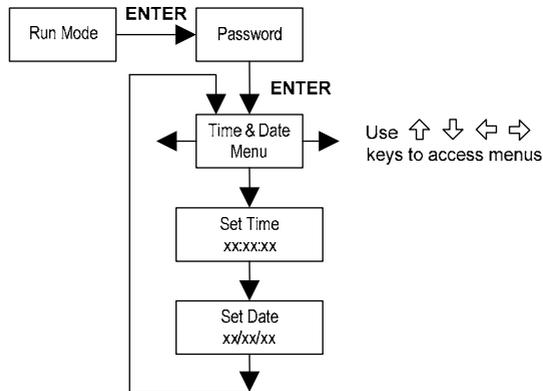


4.12 Units menu



Use the Units Menu to configure the flowmeter with the desired units of measurement. (These are global settings and determine what appears on all screens.)

4.13 Time and date menu



Use the Time and Date Menu to enter the correct time and date into the flowmeter's memory. The parameters are used in the Run mode and the alarm and system log files.

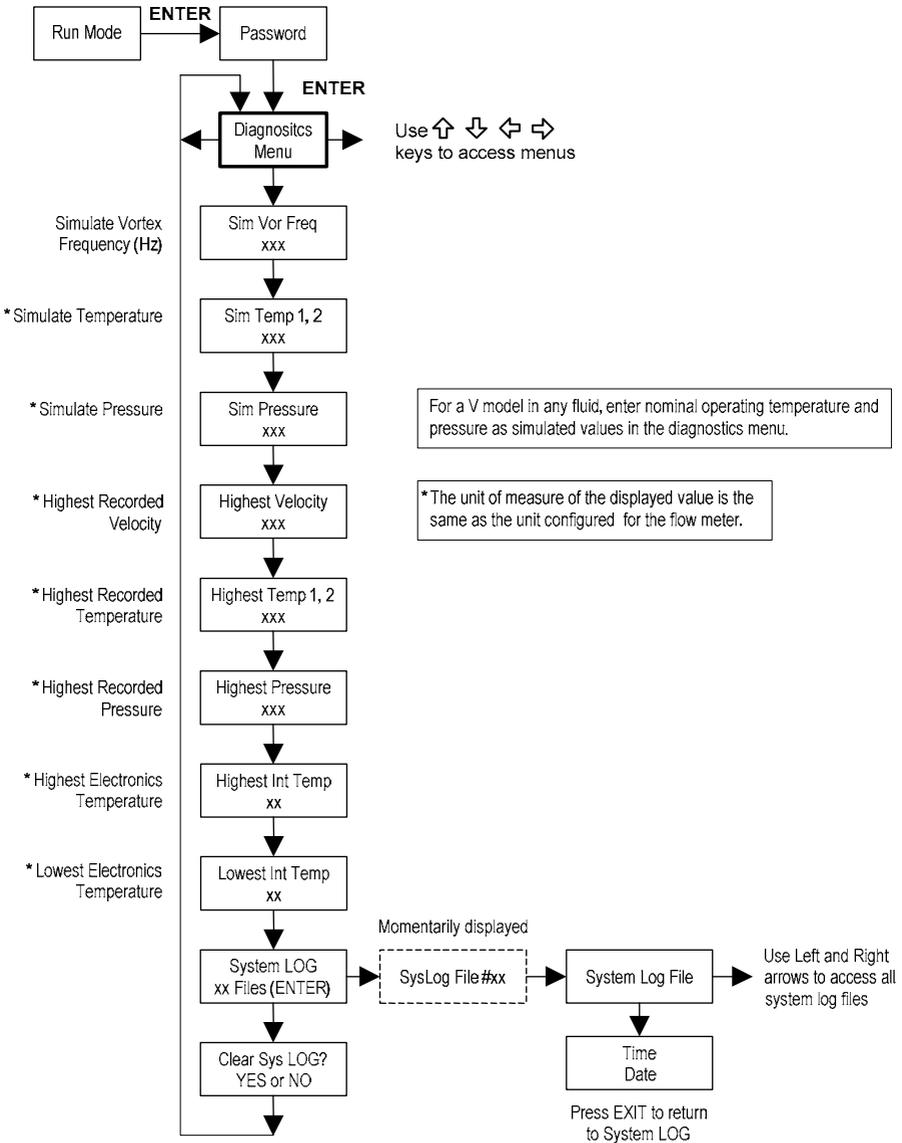
Note: Time is displayed in AM/PM format, but military format is used to set the time. For example, 1:00 PM is entered as 13:00:00 in the Set Time menu.

Example for setting the time

How to set the time to 12:00:00. You can check the time in the Run mode by pressing the keys until the Time & Date screen appears. Note: all outputs are disabled while using the Setup Menus.

1. Use ← → keys to move to the Time and Date Menu.
2. Press key until Set Time appears. Press ENTER.
3. Press ↓ key until 1 appears. Press → key to move the underline cursor to the next digit. Press the ↓ key until 2 appears. Continue sequence until all desired parameters are entered.
Press ENTER to return to the Time and Date Menu.
4. Press EXIT to return to the Run mode.

4.14 Diagnostics menu

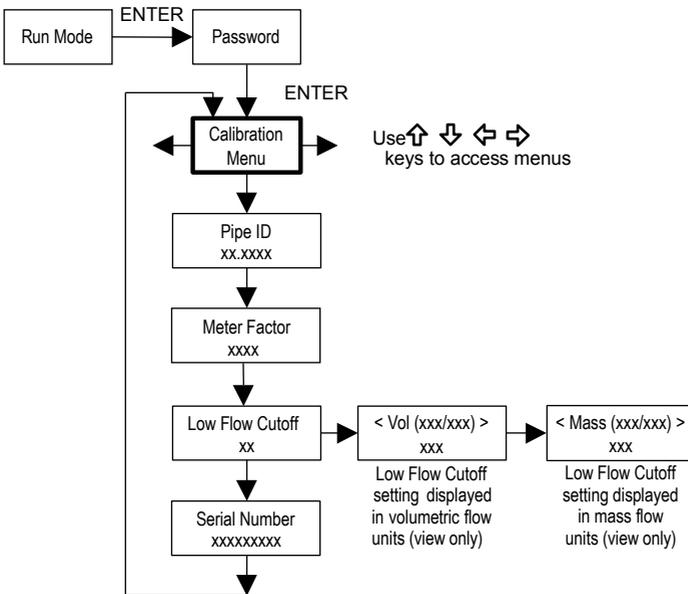


Use the Diagnostics Menu to simulate operation and review the system files. The system log files contain time/date stamped messages including: power on, power off, programming time outs, parameter faults, incorrect password entry and other various information relative to system operation and programming.

The simulated inputs are for testing the meter to verify that the programming is correct. They are also used to enter nominal operating temperature and pressure for the V only model. Simulated turbine frequency allows you to enter any value for the sensor input in Hz. The meter will calculate a flowrate based on the corresponding value and update all Analogue outputs (the totalizer display and output is not affected by a simulated frequency). The simulated pressure and temperature settings work the same way. The meter will output these new values and will use them to calculate a new density for mass flow measurement. Note: when your diagnostic work is complete, make sure to return the values to zero to allow the electronics to use the actual transducer values. For the V only model keep the temperature and pressure at nominal operating conditions.

If the meter display indicates a temperature or pressure fault, a substitute value can be entered to allow flow calculations to continue at a fixed value until the source of the fault is identified and corrected. The units of measure of the displayed values are the same as the units configured for the flowmeter.

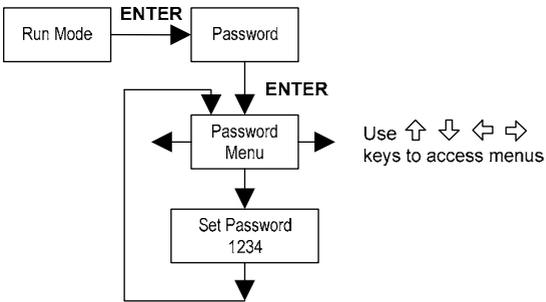
4.15 Calibration menu



The Calibration menu contains the calibration coefficients for the flowmeter. These values should be changed only by properly trained personnel. The Low Flow Cutoff is set at the factory.

Consult the factory for help with these settings if the meter is showing erratic flowrate.

4.16 Password menu



Use the Password Menu to set or change the system password. The factory-set password is 1234.

5. Serial communications

5.1 HART communications

The HART Communications Protocol (Highway Addressable Remote Transducer Protocol) is a bidirectional digital serial communications protocol. The HART signal is based on the Bell 202 standard and is superimposed on 4-20 mA Output 1. Peer-to-peer (Analogue / digital) and multi-drop (digital only) modes are supported.



Warning!

Place controls in manual mode when making configuration changes to the turbine meter.

5.2 Wiring

The diagrams below detail the proper connections required for HART communications:

5.2.1 Loop powered meter wiring

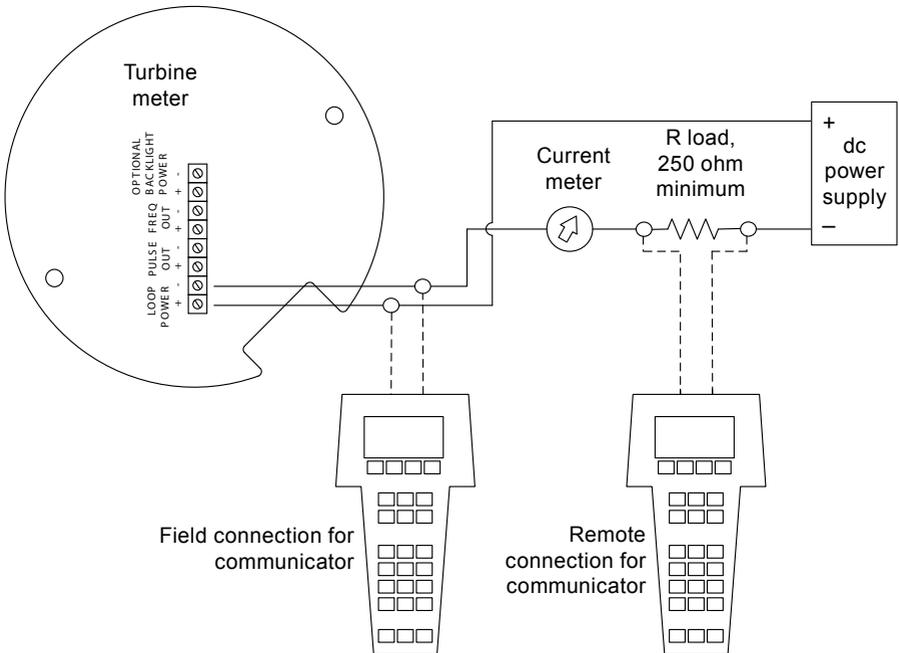
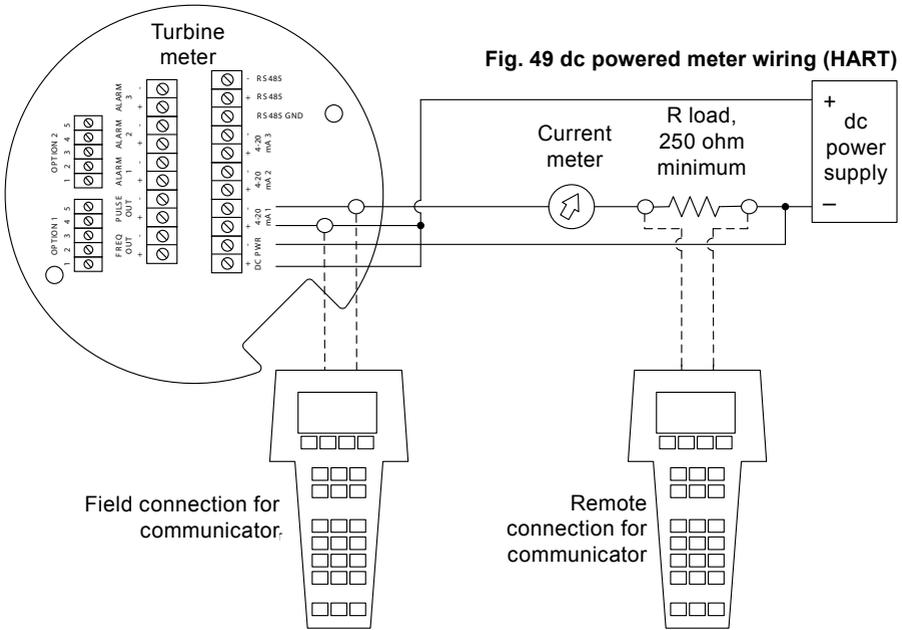
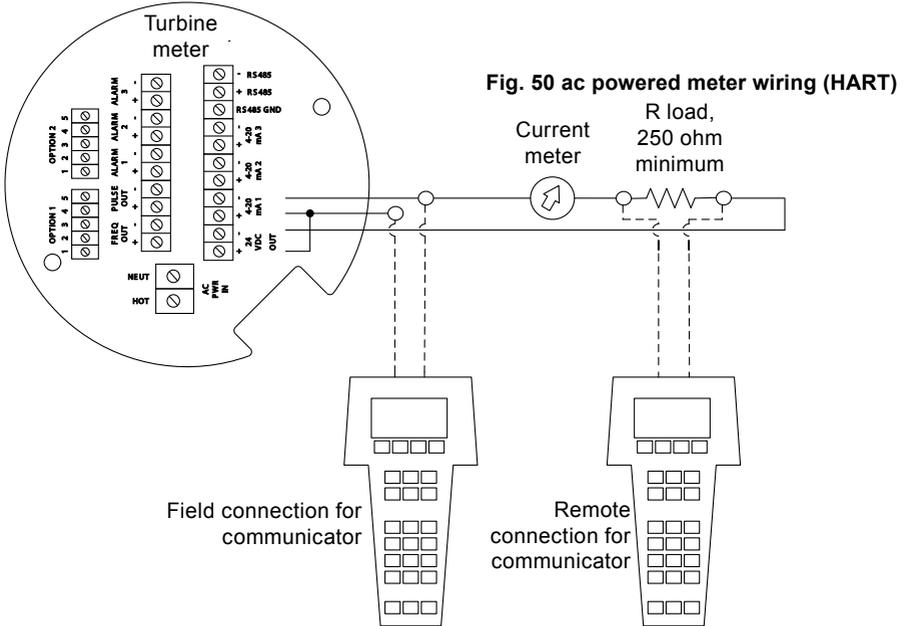


Fig. 48 Loop Powered Meter Wiring (HART)

5.2.2 dc Powered Meter Wiring

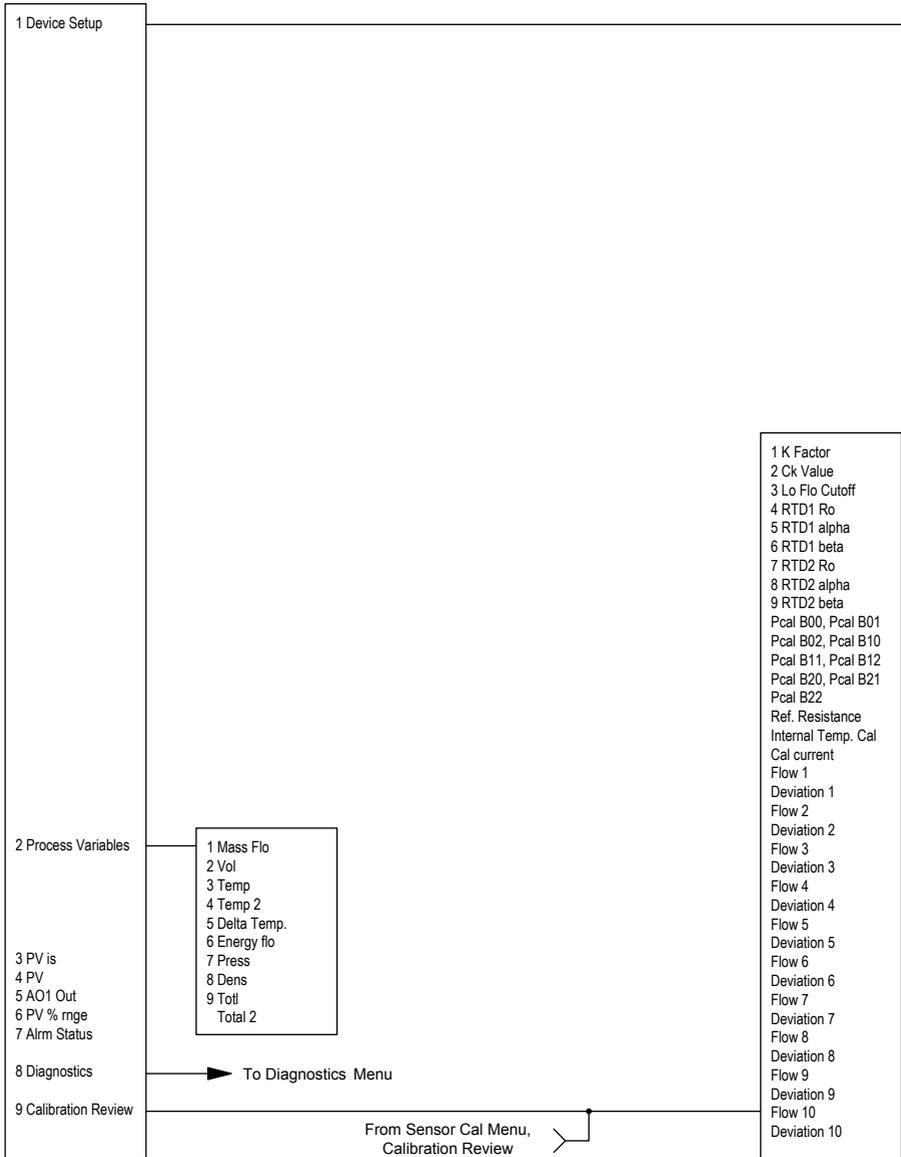


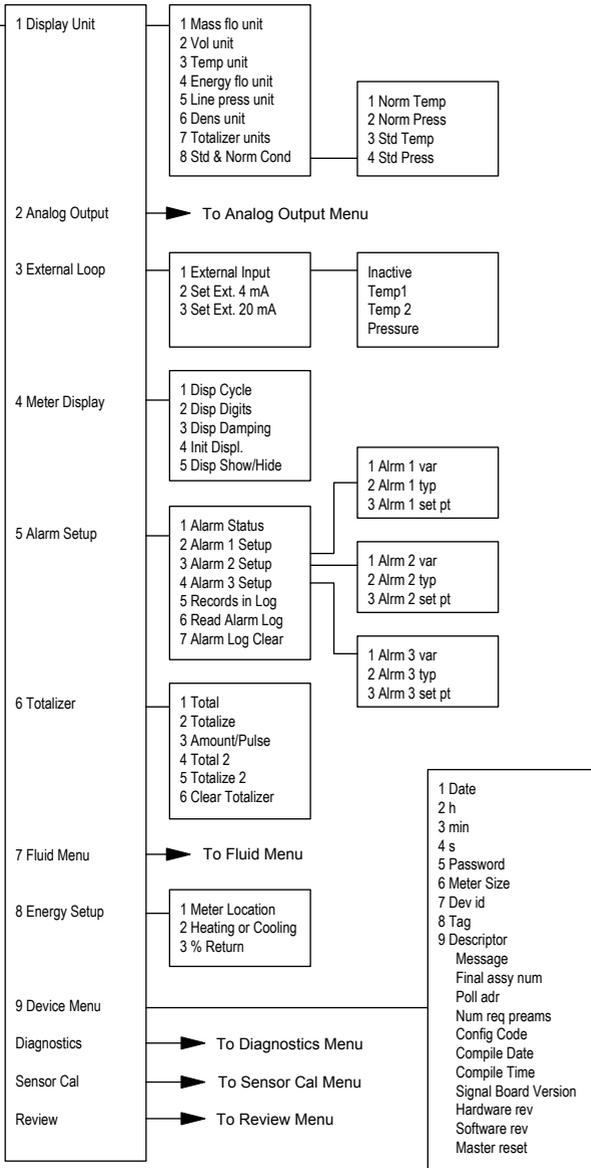
5.2.3 ac powered meter wiring



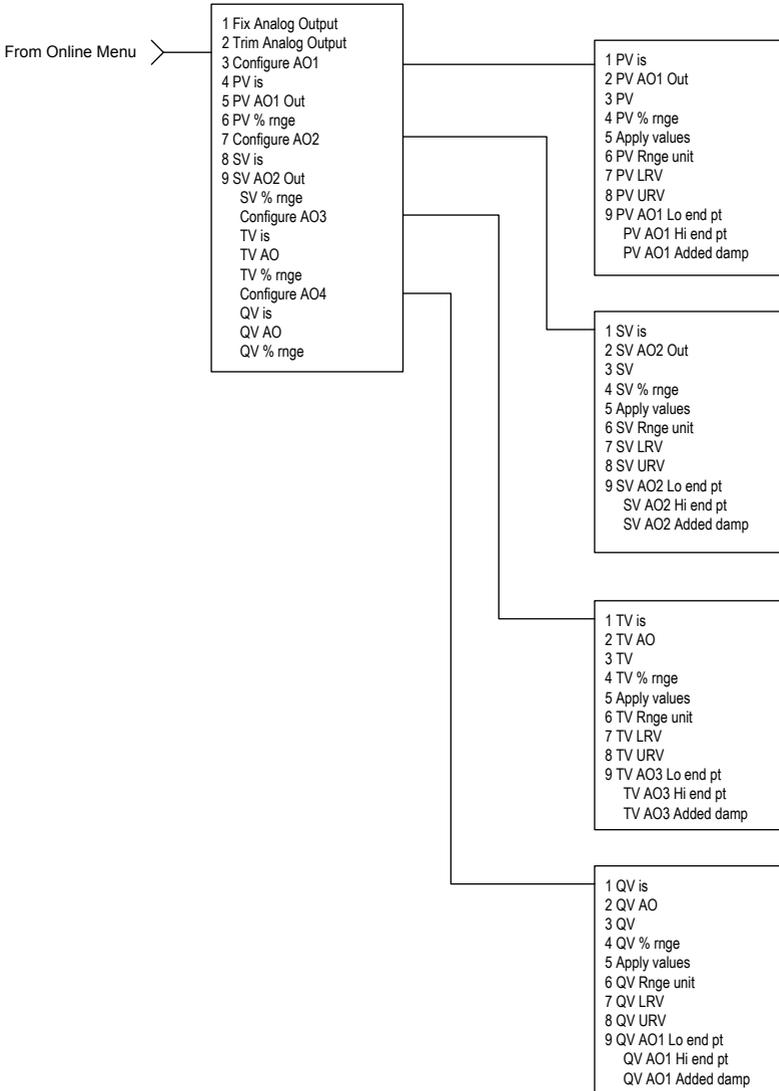
5.3 HART Commands with the DD menu

5.3.1 Online Menu

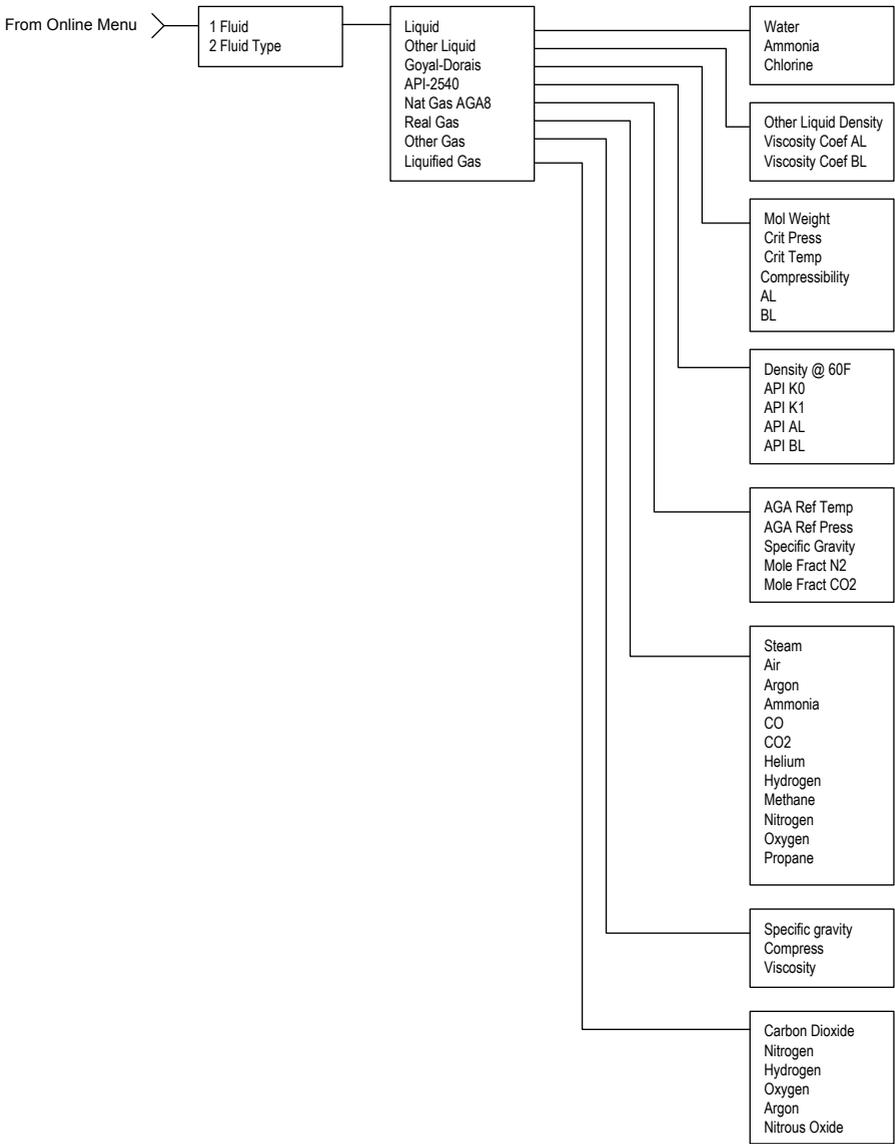




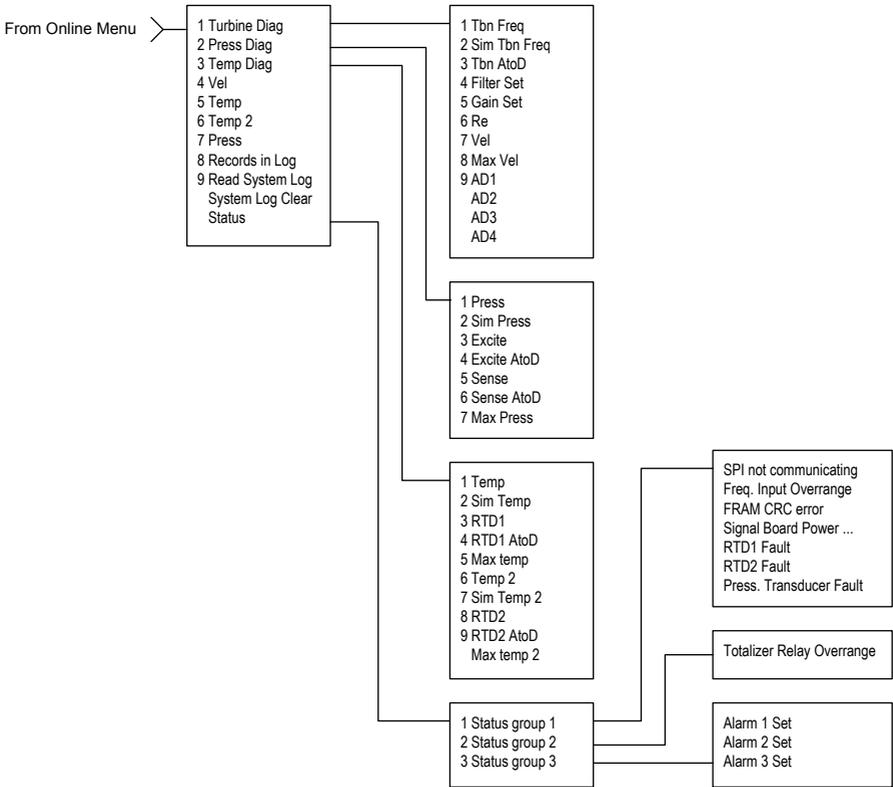
5.3.2 Analogue output menu



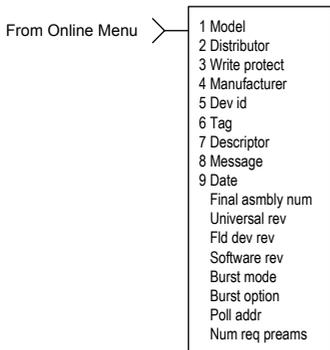
5.3.3 Fluid menu



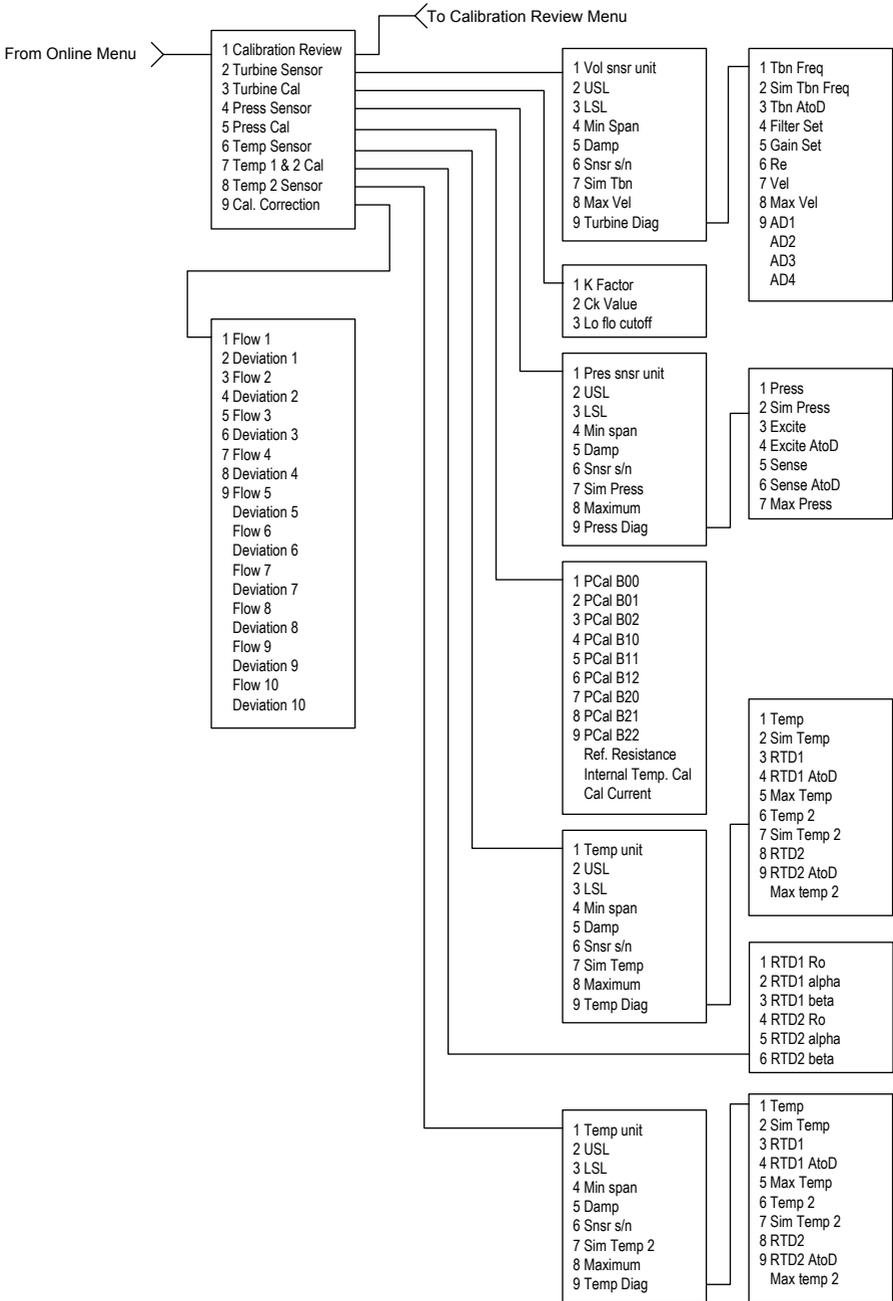
5.3.4 Diagnostics menu



5.3.5 Review menu

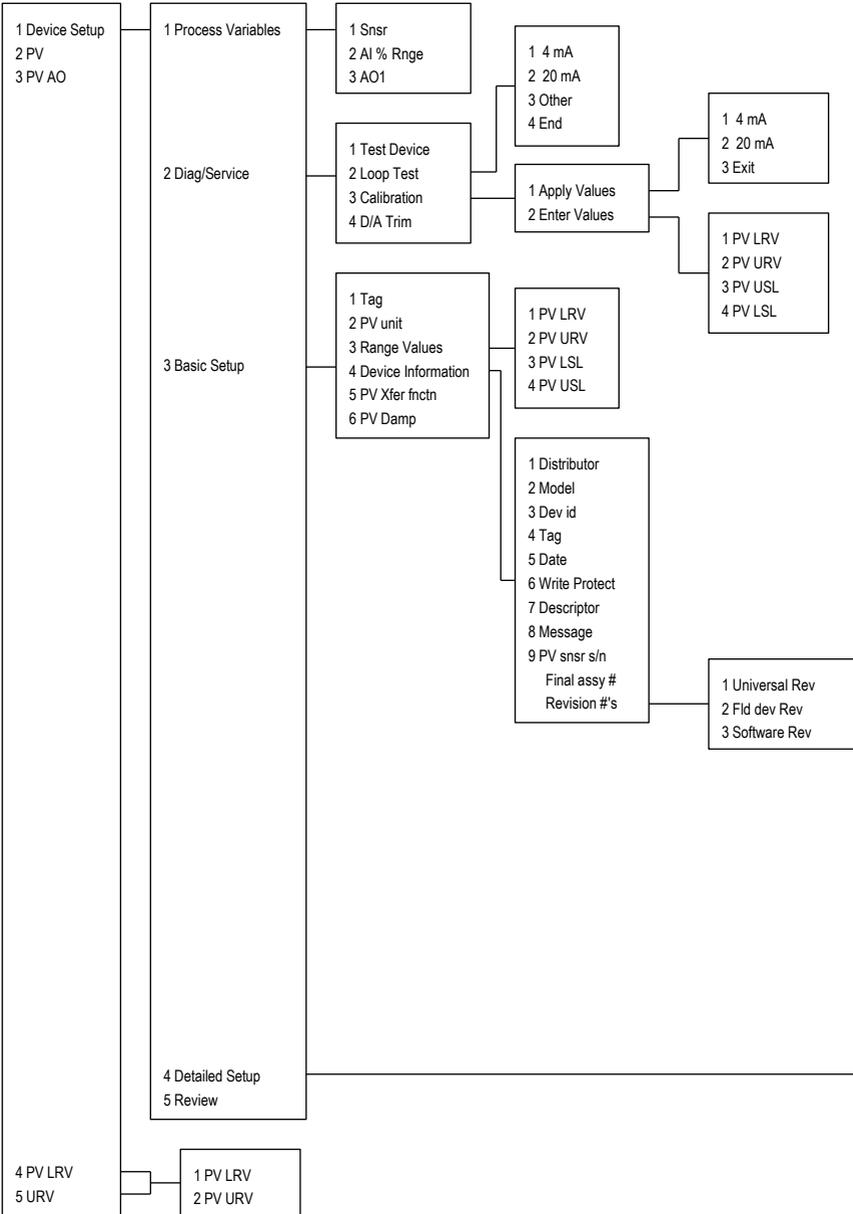


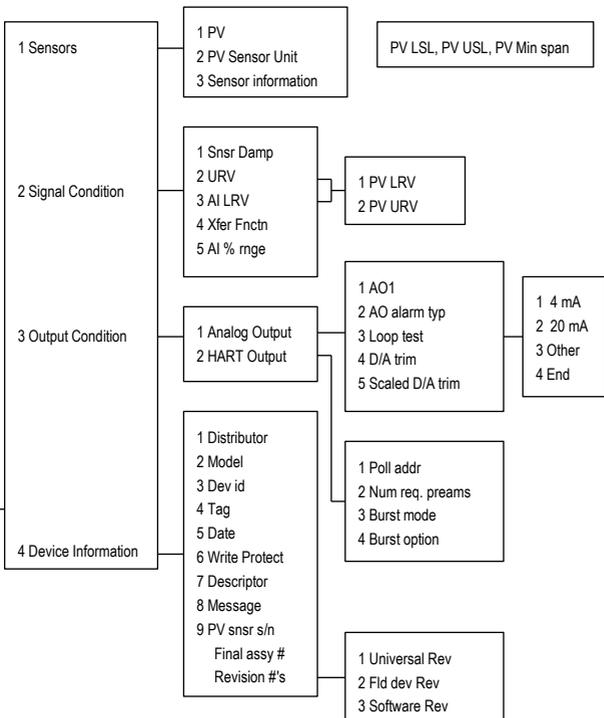
5.3.6 Sensor cal menu



5.4 HART commands with generic DD menu

Online Menu





5.4.1 Fast key sequence

Use password 16363.

| Sequence | Description | Access | Notes |
|--------------|---------------|--------|---|
| 1,1,1 | Snsr | View | Primary variable value |
| 1,1,2 | AI % Rnge | View | Analogue output % range |
| 1,1,3 | AO1 | View | Analogue output, mA |
| 1,2,1 | Test Device | N/A | Not used |
| 1,2,2,1 | 4 mA | View | Loop test, fix Analogue output at 4 mA |
| 1,2,2,2 | 20 mA | View | Loop test, fix Analogue output at 20 mA |
| 1,2,2,3 | Other | Edit | Loop test, fix Analogue output at mA value entered |
| 1,2,2,4 | End | | Exit loop test |
| 1,2,3,1,1 | 4 mA | N/A | Not used, apply values |
| 1,2,3,1,2 | 20 mA | N/A | Not used, apply values |
| 1,2,3,1,3 | Exit | | Exit apply values |
| 1,2,3,2,1 | PV LRV | Edit | Primary variable lower range value |
| 1,2,3,2,2 | PV URV | Edit | Primary variable upper range value |
| 1,2,3,2,3 | PV USL | View | Primary variable upper sensor limit |
| 1,2,3,2,4 | PV LSL | View | Primary variable lower sensor limit |
| 1,2,4 | D/A Trim | Edit | Calibrate electronics 4 mA and 20 mA values |
| 1,3,1 | Tag | Edit | Tag |
| 1,3,2 | PV unit | Edit | Primary variable units |
| 1,3,3,1 | PV LRV | Edit | Primary variable lower range value |
| 1,3,3,2 | PV URV | Edit | Primary variable upper range value |
| 1,3,3,3 | PV LSL | View | Primary variable upper sensor limit |
| 1,3,3,4 | PV USL | View | Primary variable lower sensor limit |
| 1,3,4,1 | Distributor | N/A | Not used |
| 1,3,4,2 | Model | N/A | Not used |
| 1,3,4,3 | Dev id | View | Device identification |
| 1,3,4,4 | Tag | Edit | Tag |
| 1,3,4,5 | Date | Edit | Date |
| 1,3,4,6 | Write Protect | View | Write protect |
| 1,3,4,7 | Descriptor | Edit | Turbine flowmeter |
| 1,3,4,8 | Message | Edit | 32 character alphanumeric message |
| 1,3,4,9 | PV snsr s/n | View | Primary variable sensor serial number |
| 1,3,4.menu | Final assy # | Edit | Final assembly number |
| 1,3,4.menu,1 | Universal Rev | View | Universal revision |
| 1,3,4.menu,2 | Fld dev Rev | View | Field device revision |
| 1,3,4.menu,3 | Software Rev | View | Software revision |
| 1,3,5 | PV Xfer fnctn | View | Linear |
| 1,3,6 | PV Damp | Edit | Primary variable damping (time constant) in seconds |

| Sequence | Description | Access | Notes |
|--------------|--------------------|--------|---|
| 1,4,1,1 | PV | View | Primary variable value |
| 1,4,1,2 | PV Sensor Unit | Edit | Primary variable units |
| 1,4,1,3 | Sensor Information | View | PV LSL, PV USL, PV Min span |
| 1,4,2,1 | Snsr Damp | Edit | Primary variable damping (time constant) in seconds |
| 1,4,2,2,1 | PV LRV | Edit | Primary variable low range value |
| 1,4,2,2,2 | PV URV | Edit | Primary variable upper range value |
| 1,4,2,3,1 | PV LRV | Edit | Primary variable low range value |
| 1,4,2,3,2 | PV URV | Edit | Primary variable upper range value |
| 1,4,2,4 | Xfer Fnctn | View | Linear |
| 1,4,2,5 | AI % rng | View | Analogue output % range |
| 1,4,3,1,1 | AO1 | View | Analogue output, mA |
| 1,4,3,1,2 | AO alarm typ | N/A | Not used |
| 1,4,3,1,3,1 | 4 mA | View | Loop test, fix Analogue output at 4 mA |
| 1,4,3,1,3,2 | 20 mA | View | Loop test, fix Analogue output at 20 mA |
| 1,4,3,1,3,3 | Other | Edit | Loop test, fix Analogue output at mA value entered |
| 1,4,3,1,3,4 | End | | Exit loop test |
| 1,4,3,1,4 | D/A trim | Edit | Calibrate electronics 4 mA and 20 mA values |
| 1,4,3,1,5 | Scaled D/A trim | N/A | Not used |
| 1,4,3,2,1 | Poll addr | Edit | Poll address |
| 1,4,3,2,2 | Num req. preams | View | Number of required preambles |
| 1,4,3,2,3 | Burst mode | N/A | Not used |
| 1,4,3,2,4 | Burst option | N/A | Not used |
| 1,4,4,1 | Distributor | N/A | Not used |
| 1,4,4,2 | Model | N/A | Not used |
| 1,4,4,3 | Dev id | View | Device identification |
| 1,4,4,4 | Tag | Edit | Tag |
| 1,4,4,5 | Date | Edit | Date |
| 1,4,4,6 | Write Protect | View | Write protect |
| 1,4,4,7 | Descriptor | Edit | Turbine flowmeter |
| 1,4,4,8 | Message | Edit | 32 character alphanumeric message |
| 1,4,4,9 | PV snsr s/n | View | Primary variable sensor serial number |
| 1,4,4.menu | Final assy # | Edit | Final assembly number |
| 1,4,4.menu,1 | Universal Rev | View | Universal revision |
| 1,4,4.menu,2 | Fld dev Rev | View | Field device revision |
| 1,4,4.menu,3 | Software Rev | View | Software revision |
| 1,5 | Review | N/A | Not used |
| 2 | PV | View | Primary variable value |
| 3 | PV AO | View | Analogue output, mA |
| 4,1 | PV LRV | Edit | Primary variable lower range value |
| 4,2 | PV URV | Edit | Primary variable upper range value |
| 5,1 | PV LRV | Edit | Primary variable lower range value |
| 5,2 | PV URV | Edit | Primary variable upper range value |

5.5 Modbus communications



Warning!

Place controls in manual mode when making configuration changes to the turbine meter.

5.5.1 Applicable flowmeter models

Spirax Sarco RIM20 Mass flowmeters with Modbus communication protocol and firmware version 4.00.58 and above.

5.5.2 Overview

This document describes the preliminary implementation of the Modbus communication protocol for use in monitoring common process variables in the Spirax Sarco RIM20 rotor insertion flowmeter. The physical layer utilizes the half-duplex RS-485 port, and the Modbus protocol.

5.5.3 Reference documents

The following documents are available online from www.modbus.org.
Modbus Application Protocol Specification V1.1
Modbus Over Serial Line Specification & Implementation Guide V1.0
Modicon modbus Protocol Reference Guide PI-MBUS-300 Rev. J

5.5.4 Wiring

An RS485 daisy chained network configuration as depicted below is recommended. Do not use a star, ring, or cluster arrangement.

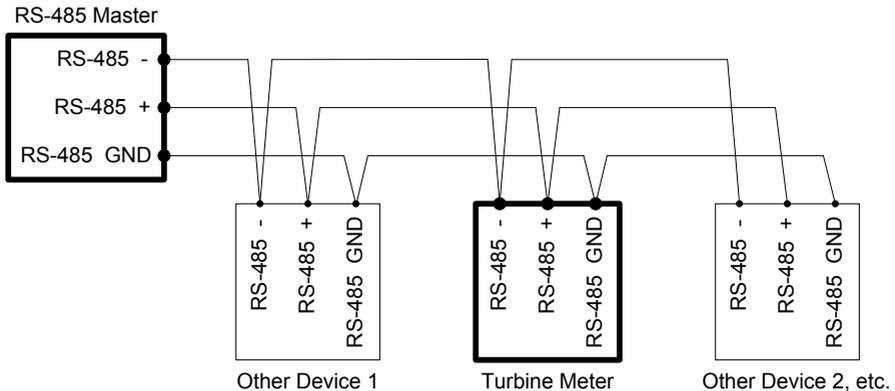


Fig. 51 RS-485 Wiring (MODBUS)

5.5.5 Pin Labeling (among devices)

"RS-485 -" ="A" ="TxD-/RxD-" ="Inverting pin"

"RS-485 +" ="B" ="TxD+/RxD+" ="Non-Inverting pin"

"RS-485 GND" ="GND" ="G" ="SC" ="Reference"

5.5.6 Menu Items

The following menu items are in the Output Menu and allow selection and control of the Modbus communication protocol.

5.5.7 Address

When the Modbus protocol is selected, the Modbus address is equal to the user programmable device address if it is in the range 1...247, in accordance with the Modbus specification. If the device address is zero or is greater than 247, then the Modbus address is internally set to 1.

5.5.8 Comm protocol

The Comm Protocol menu allows selection of "Modbus RTU Even," "Modbus RTU Odd," or "Modbus RTU None2," or "Modbus RTU None1," (non-standard Modbus) with Even, Odd and None referring to the parity selection. When even or odd parity is selected, the unit is configured for 8 data bits, 1 parity bit and 1 stop bit; with no parity, the number of stop bits is 1 (non-standard) or 2. When changing the protocol, the change is made as soon as the Enter key is pressed.

5.5.10 Modbus units

The Modbus Units menu is to control what units, where applicable, the meter's variables will be displayed in. Internal - these are the base units of the meter, °F, psi a, lbm/sec , ft 3/sec, Btu/sec , lbm/ft 3 Display - variables are displayed in user selected display unit.

5.5.11 Modbus order

The byte order within registers and the order in which multiple registers containing floating point or long integer data are transmitted may be changed with this menu item. According to the Modbus specification, the most significant byte of a register is transmitted first, followed by the least significant byte. The Modbus specification does not prescribe the order in which registers are transmitted when multiple registers represent values longer than 16 bits.

Using this menu item, the order in which registers representing floating point or long integer data and/or the byte order within the registers may be reversed for compatibility with some PLCs and PC software.

The following four selections are available in this menu; when selecting an item, the protocol is changed immediately without having to press the Enter key.

| | |
|----------------|--|
| 0-1:2-3 | Most significant register first, most significant byte first (default) |
| 2-3:0-1 | Least significant register first, most significant byte first |
| 1-0:3-2 | Most significant register first, least significant byte first |
| 3-2:1-0 | Least significant register first, least significant byte first |

Table 2 Byte Order

Note that all of the registers are affected by the byte order, including strings and registers representing 16-bit integers; the register order only affects the order of those registers representing 32-bit floating point and long integer data, but does not affect single 16-bit integers or strings.

5.5.12 Modbus protocol

The Modbus RTU protocol is supported in this implementation. Supported baud rates are 1200, 2400, 4800, 9600, 19200, 38400, 57600, and 115200. The default baud rate is 19200 baud. Depending upon the Modbus protocol selected, data are transmitted in 8-bit data frames with even or odd parity and 1 stop bit, or no parity and 2 or 1 (non-standard) stop bits. The current Modbus protocol specification does not define register usage, but there is an informal register numbering convention derived from the original (now obsolete) Modicon modbus protocol specification, and used by many vendors of Modbus capable products.

| Registers | Usage | Valid function codes |
|--------------------|---|--|
| 00001-09999 | Read/write bits ("coils") | 01 (read coils) 05 (write single coil) 15 (write multiple coils) |
| 10001-19999 | Read-only bits ("discrete inputs") | 02 (read discrete inputs) |
| 30001-39999 | Read-only 16 bit registers ("input registers"), IEEE 754 floating point register pairs, arbitrary length strings encoded as two ASCII characters per 16-bit register | 03 (read holding registers) 04 (read input registers) |
| 40001-49999 | Read/write 16-bit registers ("holding registers"), IEEE 754 floating point register pairs, arbitrary length strings encoded as two ASCII characters per 16-bit register | 03 (read holding registers) 06 (write single register) 16 (write multiple registers) |

Each range of register numbers maps to a unique range of addresses that are determined by the function code and the register number. The address is equal to the least significant four digits of the register number minus one, as shown in the following table.

| Registers | Function codes | Data type and address range |
|--------------------|----------------|---------------------------------------|
| 00001-09999 | 01, 05, 15 | Read/write bits 0000-9998 |
| 10001-19999 | 02 | Read-only bits 0000-9999 |
| 30001-39999 | 03, 04 | Read-only 16-bit registers 0000-9998 |
| 40001-49999 | 03, 06, 16 | Read/write 16-bit registers 0000-9998 |

5.6 Register definitions

The meter serial number and those variables that are commonly monitored (mass, volume and energy flowrates, total, pressure, temperature, density, viscosity, Reynolds number, and diagnostic variables such as frequency, velocity, gain, amplitude and filter setting) are accessible via the Modbus protocol. Long integer and floating point numbers are accessed as pairs of 16-bit registers in the register order selected in the Modbus Order menu. Floating point numbers are formatted as single precision IEEE 754 floating point values.

The flowrate, temperature, pressure, and density variables may be accessed as either the flowmeter internal base units or in the user-programmed display units, which is determined by the programming Output Menu's "Modbus Units" item. The display units strings may be examined by accessing their associated registers. Each of these units string registers contain 2 characters of the string, and the strings may be 2 to 12 characters in length with unused characters set to zero. Note that the byte order affects the order in which the strings are transmitted. If the Modbus Order menu (see page 2) is set to 0-1:2-3 or 2-3:0-1, then the characters are transmitted in the correct order; if set to 1- 0:3-2 or 3-2:1-0, then each pair of characters will be transmitted in reverse order.

| Registers | Variable | Data type | Units | Function code | Addresses |
|-------------|-------------------|---------------|----------------|---------------|-----------|
| 65100-65101 | Serial number | unsigned long | — | 03, 04 | |
| 30525-30526 | Totalizer | unsigned long | display units* | 03, 04 | 524-525 |
| 32037-32042 | Totalizer units | string | — | 03, 04 | 2036-2041 |
| 30009-30010 | Mass flow | float | display units* | 03, 04 | 8-9 |
| 30007-30008 | Volume flow | float | display units* | 03, 04 | 6-7 |
| 30005-30006 | Pressure | float | display units* | 03, 04 | 4-5 |
| 30001-30002 | Temperature | float | display units* | 03, 04 | 0-1 |
| 30029-30030 | Velocity | float | ft/sec | 03, 04 | 28-29 |
| 30015-30016 | Density | float | display units* | 03, 04 | 14-15 |
| 30013-30014 | Viscosity | float | cP | 03, 04 | 12-13 |
| 30031-30032 | Reynolds number | float | — | 03, 04 | 30-31 |
| 30025-30026 | Turbine frequency | float | Hz | 03, 04 | 24-25 |
| 34532 | Gain | char | — | 03, 04 | 4531 |
| 30085-30086 | Turbine amplitude | float | Vrms | 03, 04 | 84-85 |
| 30027-30028 | Filter setting | float | Hz | 03, 04 | 26-27 |

Table 3 Register Definitions

The following registers are available with the energy meter firmware:

| Registers | Variable | Data type | Units | Function code | Addresses |
|--------------------|--------------------|---------------|----------------|---------------|-----------|
| 30527-30528 | Totalizer #2 | unsigned long | display units* | 03, 04 | 526-527 |
| 32043-32048 | Totalizer #2 units | string | — | 03, 04 | 2042-2047 |
| 30003-30004 | Temperature #2 | float | display units* | 03, 04 | 2-3 |
| 30011-30012 | Energy flow | float | display units* | 03, 04 | 10-11 |

The following registers contain the display units strings:

| Registers | Variable | Data type | Units | Function code | Addresses |
|--------------------|-------------------|-----------|-------|---------------|-----------|
| 32007-32012 | Volume flow units | string | — | 03, 04 | 2006-2011 |
| 32001-32006 | Mass flow units | string | — | 03, 04 | 2000-2005 |
| 32025-32030 | Temperature units | string | — | 03, 04 | 2024-2029 |
| 32019-32024 | Pressure units | string | — | 03, 04 | 2018-2023 |
| 32031-32036 | Density units | string | — | 03, 04 | 2030-2035 |
| 32013-32017 | Energy flow units | string | — | 03, 04 | 2012-2017 |

Function codes 03 (read holding registers) and 04 (read input registers) are the only codes supported for reading these registers, and function codes for writing holding registers are not implemented. We recommend that the floating point and long integer registers be read in a single operation with the number of registers being a multiple of two. If these data are read in two separate operations, each reading a single 16-bit register, then the value will likely be invalid.

The floating point registers with values in display units are scaled to the same units as are displayed, but are instantaneous values that are not smoothed. If display smoothing is enabled (non-zero value entered in the Display TC item in the Display Menu), then the register values will not agree exactly with the displayed values.

5.6.1 Exception status definitions

The Read Exception Status command (function code 07) returns the exception status byte, which is defined as follows. This byte may be cleared by setting "coil" register #00003 (function code 5, address 2, data = 0xff00).

| Bit(s) | Definition |
|--------|---|
| 0-1 | Byte order (see Modbus Order on page 2) 0 = 3-2:1-0 1 = 2-3:0-1 2 = 1-0:3-2 3 = 0-1:2-3 |
| 2 | Temperature sensor fault |
| 3 | Pressure sensor fault |
| 4 | A/D converter fault |
| 5 | Period overflow |
| 6 | Pulse overflow |
| 7 | Configuration changed |

5.6.2 Discrete input definitions

The status of the three alarms may be monitored via the Modbus Read Discrete Input command (function code 02). The value returned indicates the state of the alarm, and will be 1 only if the alarm is enabled and active. A zero value is transmitted for alarms that are either disabled or inactive,

| Registers | Variable | Function code | Address |
|-----------|----------------|---------------|---------|
| 10001 | Alarm #1 state | 02 | 0 |
| 10002 | Alarm #2 state | 02 | 1 |
| 10003 | Alarm #3 state | 02 | 2 |

5.6.3 Control register definitions

The only writeable registers in this implementation are the Reset Exception Status, Reset Meter and Reset Totalizer functions, which are implemented as "coils" which may be written with the Write Single Coil command (function code 05) to address 8 through 10, respectively, (register #00009 through #00011).

The value sent with this command must be either 0x0000 or 0xff00, or the meter will respond with an error message; the totalizer will be reset or exception status cleared only with a value of 0xff00.

5.6.4 Error responses

If an error is detected in the message received by the unit, the function code in the response is the received function code with the most significant bit set, and the data field will contain the exception code byte, as follows:

| Exception Code | Description |
|----------------|---|
| 01 | Invalid function code — function code not supported by device |
| 02 | Invalid data address — address defined by the start address and number of registers is out of range |
| 03 | Invalid data value — number of registers = 0 or >125 or incorrect data with the Write Single Coil command |

If the first byte of a message is not equal to the unit's Modbus address, if the unit detects a parity error in any character in the received message (with even or odd parity enabled), or if the message CRC is incorrect, the unit will not respond.

5.6.5 Command message format

The start address is equal to the desired first register number minus one. The addresses derived from the start address and the number of registers must all be mapped to valid defined registers, or an invalid data address exception will occur.

| Device address | Function code | Start address | N = Number of registers | CRC |
|------------------|---------------|--------------------|-------------------------|---------|
| 8 bits, 1... 247 | 8 bits | 16 bits, 0... 9998 | 16 bits, 1 ... 125 | 16 bits |

5.6.6 Normal response message format

| Device address | Function code | Byte count | Data | CRC |
|------------------|---------------|------------|----------------------|---------|
| 8 bits, 1... 247 | 8 bits | 8 bits | (N) 16-bit registers | 16 bits |

5.6.7 Exception response message format

| Device address | Function code | Exception code | CRC |
|------------------|---------------|----------------|---------|
| 8 bits, 1... 247 | 8 bits | 8 bits | 16 bits |

5.6.8 Examples

Read the exception status byte from the device with address 1:

```
01 07 41 E2
01 Device address
07 Function code, 04 = read exception status
```

A typical response from the device is as follows:

```
01 07 03 62 31
01 Device address
07 Function code
03 Exception status byte
62 31 CRC
```

Request the first 12 registers from device with address 1:

```
01 04 00 00 00 0C F0 0F
01 Device address
04 Function code, 04 = read input register
00 00 Starting address
00 0C Number of registers = 12
F0 0F CRC
```

A typical response from the device is as follows: *note these are the older register definitions

```
01 04 18 00 00 03 E8 00 00 7A 02 6C 62 00 00 41 BA 87 F2 3E BF
FC 6F 42 12 EC 8B 4D D1
01 Device address
04 Function code
18 Number of data bytes = 24
00 00 03 E8 Serial number = 1000 (unsigned long)
00 00 7A 02 Totalizer = 31234 lbm (unsigned long)
6C 62 00 00 Totalizer units ="lb" (string, unused characters
are 0)
41 BA 87 F2 Mass flowrate = 23.3164 lbm/sec (float)
3E BF FC 6F Volume flowrate = 0.3750 ft3 /sec (float)
42 12 EC 8B Pressure = 36.731 psi a (float)
4D D1 CRC
```

An attempt to read register(s) that don't exist

```
01 04 00 00 00 50 F1 D2
01 Device address
04 Function code 4 = read input register
00 00 Starting address
00 50 Number of registers = 80
F0 36 CRC
```

results in an error response as follows:

```
01 84 02 C2 C1
01 Device address
84 Function code with most significant bit set indicates
error response
02 Exception code 2 = invalid data address
C2 C1 CRC
```

Request the state all three alarms:

```
01 02 00 00 00 03 38 0B
01 Device address
02 Function code 2 = read discrete inputs
00 00 Starting address
00 03 Number of inputs = 3
38 0B CRC
```

and the unit responds with:

```
01 02 01 02 20 49
01 Device address
02 Function code
01 Number of data bytes = 1
02 Alarm #2 on, alarms #1 and #3 off
20 49 CRC
```

To reset the totalizer:

```
01 05 00 00 FF 00 8C 3A
01 Device address
05 Function code 5 = write single coil
00 09 Coil address = 9
FF 00 Data to reset totalizer
8C 3A CRC (not the correct CRC EJS-02-06-07)
```

The unit responds with an identical message to that transmitted, and the totalizer is reset. If the "coil" is turned off as in the following message, the response is also identical to the transmitted message, but the totalizer is not affected.

```
01 05 00 00 00 00 CD CA
01 Device address
05 Function code 5 = write single coil
00 00 Coil address = 0
00 00 Data to "turn off coil" does not reset totalizer
CD CA CRC
```

5.7 BACnet MS/TP communications

The BACnet Master-Slave/Token-Passing (MS/TP) driver implements a data link protocol that uses the services of the RS-485 physical layer. The MS/TP bus is based on BACnet standard protocol SSPC-135, Clause 9. BACnet MS/TP protocol is a peer-to-peer, multiple master protocols based on token passing. Only master devices can receive the token, and only the device holding the token is allowed to originate a message on the bus. The token is passed from master device to master device using a small message.

The token is passed in consecutive order starting with the lowest address. Slave devices on the bus only communicate on the bus when responding to a data request from a master device.

5.8 Baud Rates on the MS/TP Bus

An mS/TP bus can be configured to communicate at one of four different baud rates. It is very important that all of the devices on an mS/TP bus communicate at the same baud rate. The baud rate setting determines the rate at which devices communicate data over the bus. The baud rate settings available on RIM20 Vortex Mass flowmeters are 9600, 19200, 38400, 57600 and 115200

5.8.1 Baud Rate and MAC address configuration

1. Power on the IUT
2. Press Enter to go configuration menu
3. Give the factory password 16363 (Use Up and Down arrows to enter the digits)
4. Navigate to Output menu
5. Navigate to Output Menu by using right or left arrow buttons
6. Press Down button and reach Baud Rate MAC address, and Device Instance screens
7. Change the required settings and press Exit & Enter buttons to save the configuration
8. Do steps from b to g, and change the comm. Type as Hart.
9. Reboot the device by power off and on.

Note:

- a. IUT support 9600, 19200, 38400, 57600, 115200 baud rates
- b. MAC address range is 0-127

5.9 Supported BACnet objects

A BACnet object represents physical or virtual equipment information, as a digital input or parameters. The RIM20 Vortex Mass flowmeters presents the following object types:

- a. Device Object
- b. Analogue Input
- c. Binary Input
- d. Binary Value

Each object type defines a data structure composed by properties that allow the access to the object information. The below table shows the implemented properties for each Vortex Mass flowmeters object type.

| Properties | Object Types | | | |
|---------------------------------|-------------------------------------|-------------------------------------|-------------------------------------|-------------------------------------|
| | Device | Analogue input | Binary input | Binary value |
| Object_Identifier | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> |
| Object_Name | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> |
| Object_Type | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> |
| System_Status | <input checked="" type="checkbox"/> | | | |
| Vendor_Name | <input checked="" type="checkbox"/> | | | |
| Vendor_Identifier | <input checked="" type="checkbox"/> | | | |
| Model_Name | <input checked="" type="checkbox"/> | | | |
| Firmware_Revision | <input checked="" type="checkbox"/> | | | |
| Application-Software-Version | <input checked="" type="checkbox"/> | | | |
| Protocol_Version | <input checked="" type="checkbox"/> | | | |
| Protocol_Revision | <input checked="" type="checkbox"/> | | | |
| Protocol_Services_Supported | <input checked="" type="checkbox"/> | | | |
| Protocol_Object_Types_Supported | <input checked="" type="checkbox"/> | | | |
| Object_List | <input checked="" type="checkbox"/> | | | |
| Max_ADPU_Length_Accepted | <input checked="" type="checkbox"/> | | | |
| Segmentation_Supported | <input checked="" type="checkbox"/> | | | |
| ADPU_Timeout | <input checked="" type="checkbox"/> | | | |
| Number_Of_ADPU_Retries | <input checked="" type="checkbox"/> | | | |

| Properties | Object Types | | | |
|------------------------|-------------------------------------|---|---|---|
| | Device | Analogue input | Binary input | Binary value |
| Max_Masters | <input checked="" type="checkbox"/> | | | |
| Max_Info_Frames | <input checked="" type="checkbox"/> | | | |
| Device_Address_Binding | <input checked="" type="checkbox"/> | | | |
| Database_Revision | <input checked="" type="checkbox"/> | | | |
| Status_Flags | | | | |
| Event_State | | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> |
| Reliability | | | | |
| Out_Of_Service | | <input checked="" type="checkbox"/> (W) | <input checked="" type="checkbox"/> (W) | <input checked="" type="checkbox"/> (W) |
| Units | | <input checked="" type="checkbox"/> | | |
| Polarity | | | <input checked="" type="checkbox"/> (W) | |
| Priority_Array | | | | |
| Relinquish_Default | | | | |
| Status_Flag | | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> | <input checked="" type="checkbox"/> |
| Present_Value | | <input checked="" type="checkbox"/> (W) | <input checked="" type="checkbox"/> (W) | <input checked="" type="checkbox"/> (W) |
| Inactive_Text | | | | |
| Active_Text | | | | |

(W) - Writable Property.

5.9.1 Device object:

The Device object default property values are as follows -

| Property name | Default values |
|---------------------------------|---|
| object-identifier | 7 |
| object-name | Device,1 |
| object-type | Device |
| system-status | operational |
| vendor-name | Spirax Sarco |
| vendor-identifier | 558 |
| model-name | Multivariable Flowmete |
| firmware-revision | N/A |
| application-software- | |
| version | 1.07 |
| protocol-version | 1 |
| protocol-revision | 4 |
| protocol-services- | |
| supported | {F,F,F,F,F,F,F,F,F,F,F,F,F,T,F,T,T,T,T,F,F,F,F,F,F,F,F,F,F,T,T,F,F,F,F,F} |
| protocol-object-types-supported | {T,F,F,T,F,T,F,F,T,F,F,F,F,F,F,F,F,F,F,F,F,F} |
| object-list | {(Analogue-input,1), (Analogue-input,2), (Analogue-input,3), (Analogue-input,4), (Analogue-input,5), (Analogue-input,6), (Analogue-input,7), (Analogue-input,8), (Analogue-input,9), (Analogue-input,10), (Analogue-input,11), (Analogueinput, 12), (Analogue-input,13), (Analogue-input,14), (Analogueinput, 15), (Analogue-input,16), (Analogue-input,17), (Analogueinput, 18), (Analogue-input,19), (binary-input,1), (binary-input, 2), (binary-input, 3), (binary-input,4), (binary-value,1), (device,7) } |
| max-apdu-length-accepted | 300 |
| segmentation-supported | no-segmentation |
| apdu-timeout | 3000 |
| number-of-APDU-retries | 1 |
| max-master | 127 |
| max-info-frames | 1 |
| device-address-binding | () |
| database-revision | 0 |

Note - Device Communication Control: Password -"Spirax Sarco"

5.9.2 Analogue input object:

Vortex Mass flowmeters Analogue Input type objects are described in the below Table -

| Object instance | Object name | Unit | Description |
|-----------------|---------------|--|---|
| 1 | Volume flow | cubic-feet-per-second, cubic-feet-per-minute, us-gallons-per-minute, imperial-gallons-per- minute, litres-per-minute, litres-per-second, litres-per-hour, cubic-meters-per-second, cubic-meters-per-minute, cubic-meters-per-hour | This AI object is used to measure volume flow. |
| 2 | Mass flow | pounds-mass-per-second, grams-per-second, kilograms-per-second , kilograms-per-minute , kilograms-per-hour, pounds-mass-per-minute , pounds-mass-per-hour, tons-per-hour, grams-per-second , grams-per-minute | This AI object is used to measure mass flow. |
| 3 | Temperature 1 | degrees-Celsius, degrees-Kelvin, degrees-Fahrenheit | This AI object measures temperature in one of the given Unit. |
| 4 | Temperature 2 | degrees-Celsius, degrees-Kelvin, degrees-Fahrenheit | This AI object measures temperature in one of the given Unit. |
| 5 | Pressure | pounds-force-per-square-" "-of-water, "-of-mercury, millimeters-of-mercury, bars, millibars, pascals, kilopascals | TBD |
| 6 | Density | kilograms-per-cubic-meter | TBD |
| 7 | Energy Flow | Kilowatts, Horsepower, btus-per-hour,, kilo-btus-per-hour, megawatts | TBD |

| Object instance | Object name | Unit | Description |
|-----------------|---------------------------|--|--|
| 8 | Totalizer 1 & Totalizer 2 | <p>If Totalizer selection for Mass measure - pounds-mass-per-second, grams-per-second, kilograms-per-second , kilograms-per-minute , kilograms-per-hour, pounds-mass-per-minute , pounds-mass-per-hour, tons-per-hour, grams-per-second , grams-per-minute</p> <p>If Totalizer selection for Volume measure - cubic-feet-per-second, cubic-feet-per-minute, us-gallons-per-minute, imperial-gallons-per-minute, litres-per-minute, litres-per-second, litres-per-hour, cubic-meters-per-second, cubic-meters-per-minute, cubic-meters-per-hour</p> <p>If Totalizer selection for Energy measure - Kilowatts, Horsepower, btus-per-hour,, kilo-btus-per-hour, megawatts</p> | An electronic counter which records the total accumulated flow over a certain range of time. |
| 10 | StatusRegister | NO UNITS | TBD |
| 11 | Channel 1 (4-20mA) | milliamperes | TBD |
| 12 | Channel 2 (4-20mA) | milliamperes | TBD |
| 13 | Channel 3 (4-20mA) | milliamperes | TBD |
| 14 | Scaled Freq | hertz | TBD |
| 15 | Flow Velocity | feet-per-second | TBD |
| 16 | Viscosity | centipoises | TBD |
| 17 | Frequency | hertz | TBD |
| 18 | VorTex Amp | millivolts | TBD |
| 19 | FilterSetting | hertz | TBD |

5.9.3 Binary input object:

Vortex Mass flowmeters Binary Input type objects are described in the below Table.

| Object instance | Object name | Description |
|-----------------|-------------|---|
| 1 | Alarm1 | The status of the three alarms may be monitored via the Modbus command. The value returned indicates the state of the alarm, and will be 1 only if the alarm is enabled and active. A zero value is transmitted for alarms that are either disabled or inactive |
| 2 | Alarm2 | |
| 3 | Alarm3 | |
| 4 | External | TBD |

Note - Binary Input 4, Present value always read zero, because no information available from client, so the polarity property doesn't impact on Present value property when the Out of service property is false.

5.9.4 Binary value object:

Vortex Mass flowmeters Binary Value type objects are described in the below Table.

| Object instance | Object name | Description |
|-----------------|-------------|-------------------|
| 1 | Reset | Reset's Totalizer |

5.10 ANNEX - BACnet protocol implementation conformance statement

Date: 19-April-2012

Applications Software Version: 1.07

Firmware Revision: N/A

BACnet Protocol Revision: 4

BACnet Standardized Device Profile (Annex L):

- BACnet Operator Workstation (B-OWS)
- BACnet Advanced Operator Workstation (B-AWS)
- BACnet Operator Display (B-OD)
- BACnet Building Controller (B-BC)
- BACnet Advanced Application Controller (B-AAC)
- BACnet Application Specific Controller (B-ASC)
- BACnet Smart Sensor (B-SS)
- BACnet Smart Actuator (B-SA)

5.10.1 List all BACnet interoperability building blocks supported (Annex K):

| BIBBs |
|----------|
| DS-RP-B |
| DS-WP-B |
| DM-DDB-B |
| DM-DOB-B |
| DM-dcC-B |
| DS-RPM-B |
| DS-WPM-B |

| Services supported | |
|------------------------------|----------|
| Read Property | Execute |
| Write Property | Execute |
| Read Property Multiple | Execute |
| Write Property Multiple | Execute |
| Who-Is | Execute |
| I-Am | Initiate |
| Who-Has | Execute |
| I-Have | Initiate |
| Device Communication Control | Execute |

5.10.2 Segmentation capability:

- Able to transmit segmented messages - Window Size
- Able to receive segmented messages - Window Size

5.10.3 Standard object types supported

| Standard object types supported | | | | |
|---------------------------------|-----------------------|------------------------|--------------------------------|--------------------|
| Object type | Dynamically creatable | Dynamically deleteable | Additional writable properties | Range restrictions |
| Analogue Input (AI) | No | No | None | None |
| Binary Input (BI) | No | No | None | None |
| Binary Value | No | No | None | None |
| Device | No | No | None | None |

| Standard object types supported writable properties | | | |
|---|---------------|----------------|----------|
| Object type | Properties | | |
| Analogue Input (AI) | Present Value | Out-Of-Service | |
| Binary Input (BI) | Present Value | Out-Of-Service | Polarity |
| Binary Value | Present Value | Out-Of-Service | |
| Device | | | |

5.10.4 Object list

| Properties of Analogue Input/Value Objects Type | | | | | | |
|---|--------------------|---------------|--------------|-------------|----------------|-------|
| ID | Name | Present value | Status flags | Event state | Out of service | Units |
| A11 | Volume Flow | ? | F,F,F,F | Normal | False | ? |
| A12 | Mass Flow | ? | F,F,F,F | Normal | False | ? |
| A13 | Temperature 1 | ? | F,F,F,F | Normal | False | ? |
| A14 | Temperature 2 | ? | F,F,F,F | Normal | False | ? |
| A15 | Pressure | ? | F,F,F,F | Normal | False | ? |
| A16 | Density | ? | F,F,F,F | Normal | False | ? |
| A17 | Energy Flow | ? | F,F,F,F | Normal | False | ? |
| A18 | Totalizer 1 | ? | F,F,F,F | Normal | False | ? |
| A19 | Totalizer 2 | ? | F,F,F,F | Normal | False | ? |
| A110 | StatusRegister | ? | F,F,F,F | Normal | False | ? |
| A111 | Channel 1 (4-20mA) | ? | F,F,F,F | Normal | False | ? |
| A112 | Channel 2 (4-20mA) | ? | F,F,F,F | Normal | False | ? |
| A113 | Channel 3 (4-20mA) | ? | F,F,F,F | Normal | False | ? |
| A114 | Scaled Freq | ? | F,F,F,F | Normal | False | ? |
| A115 | Flow Velocity | ? | F,F,F,F | Normal | False | ? |
| A116 | Viscosity | ? | F,F,F,F | Normal | False | ? |
| A117 | Frequency | ? | F,F,F,F | Normal | False | ? |
| A118 | VorTex Amp | ? | F,F,F,F | Normal | False | ? |
| A119 | FilterSetting | ? | F,F,F,F | Normal | False | ? |

| Properties of Analogue Input/Value Objects Type | | | | | | |
|---|----------|---------------|--------------|-------------|----------------|----------|
| ID | Name | Present value | Status flags | Event state | Out of service | Polarity |
| B11 | Alarm1 | ? | F,F,F,F | Normal | False | Normal |
| B12 | Alarm2 | ? | F,F,F,F | Normal | False | Normal |
| B13 | Alarm3 | ? | F,F,F,F | Normal | False | Normal |
| B14 | External | ? | F,F,F,F | Normal | False | Normal |

| Properties of Analogue Input/Value Objects Type | | | | | | |
|---|-------|---------------|--------------|------------|----------------|----------------|
| ID | Name | Present value | Status flags | Event fate | Out of fervice | out-of-service |
| BV1 | Reset | ? | F,F,F,F | Normal | False | False |

5.10.5 Data link layer options:

- BACnet IP, (Annex J)
- BACnet IP, (Annex J), Foreign Device
- ISO 8802-3, Ethernet (Clause 7)
- ANSI/ATA 878.1, 2.5 Mb. ARCNET (Clause 8)
- ANSI/ATA 878.1, EIA-485 ARCNET (Clause 8), baud rate(s)
- MS/TP master (Clause 9), baud rate(s): 9600, 19200, 38400
- MS/TP slave (Clause 9), baud rate(s):
- Point-To-Point, EIA 232 (Clause 10), baud rate(s):
- Point-To-Point, modem, (Clause 10), baud rate(s):
- LonTalk, (Clause 11), medium:
- Other:

5.10.6 Device address binding:

Is static device binding supported? (This is currently necessary for two- way communication with MS/TP slaves and certain other devices.) :

- Yes
- No

5.10.7 Networking options:

- Router, Clause 6 - List all routing configurations, e.g., ARCNET- Ethernet, Ethernet-MS/TP, etc.
- Annex H, BACnet Tunneling Router over IP
- BACnet/IP Broadcast Management Device (BBMD)
 - Does the BBMD support registrations by Foreign Devices? Yes No
 - Does the BBMD support network address translation? Yes No

5.10.8 Network security options:

- Non-secure Device - is capable of operating without BACnet Network Security
- Secure Device - is capable of using BACnet Network Security (NS-SD BVBB)
- Multiple Application-Specific Keys:
 - Supports encryption (NS-ED BVBB)
 - Key Server (NS-KS BVBB)

5.10.9 Character sets supported:

Indicating support for multiple character sets does not imply that they can all be supported simultaneously.

- ANSI X3.4
- IBM™/Microsoft™DBCS
- ISO 8859-1
- ISO 10646 (UCS-2)
- ISO 10646 (UCS-4)
- JIS C 6226

If this product is a communication gateway, describe the types of non- BACnet equipment/networks(s) that the gateway supports:

N/A

5.11 Acronyms and definitions

| Item | Description |
|---------------|---|
| APDU | Application Protocol Data Unit |
| BACnet | Building Automation and Control Network- Data communication protocol |
| MS/TP | Master-Slave Token passing(a twisted pair RS485 network created by BACnet) |
| BIBB | BACnet Interoperability Building Block (Specific individual function blocks for data exchange between interoperable devices). |
| BV | Binary Value |
| BI | Binary Input |
| AI | Analogue Input |
| RP | Read Property |
| WP | Write Property |
| RPM | Read Property Multiple |
| WPM | Write Property Multiple. |
| DDB | Dynamic Device Binding |
| DOB | Dynamic Object Binding |
| dcC | Device communication Control |

6. Troubleshooting and repair



Warning!

Before attempting any flowmeter repair, verify that the line is not pressurized. Always remove main power before disassembling any part of the mass flowmeter.

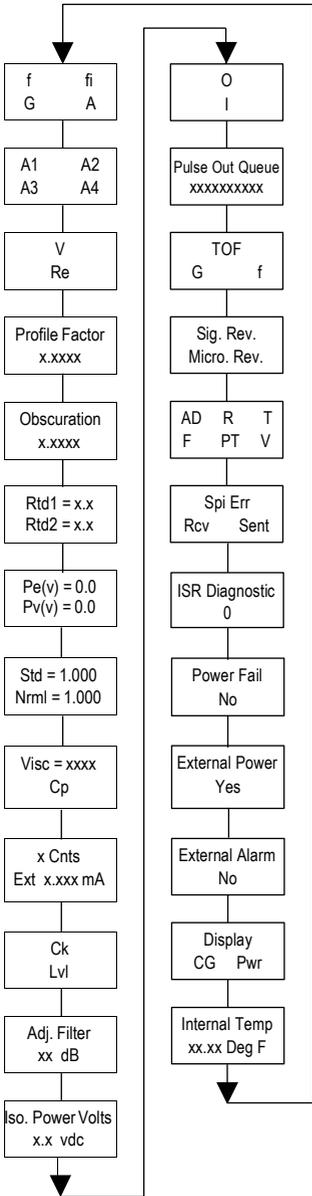
6.1 Hidden diagnostics menus

The menus shown on the following page can be accessed using the password 16363, then moving to the display that reads "Diagnostics Menu" and pressing ENTER (rather than one of the arrow keys).

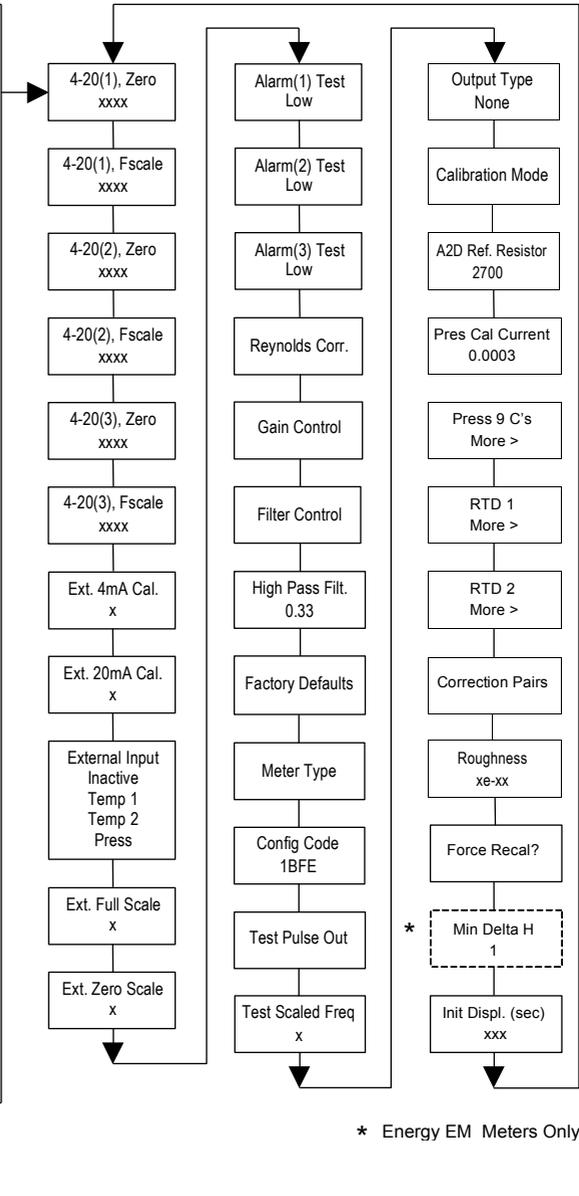
Use the right arrow key to move to the second column. Press EXIT to move from the second column back to the first, press EXIT while in the first column to return to the setup menus. Caution: password 16363 will allow full access to the configuration and should be used carefully to avoid changes that can adversely alter the function of the meter.

Each of the menus on the following page will first be defined followed by specific troubleshooting steps.

Level one values



Level two values



* Energy EM Meters Only

6.2 Level one hidden diagnostics values

| | |
|---------------------------|--|
| f | Turbine frequency (Hz). |
| fi | Adaptive filter - should be approximately 25% higher than the turbine frequency, this is a low-pass filter. If the meter is using the Filter Control (see below) in the manual mode, fi will be displayed as fm. |
| G | Gain (applied to turbine signal amplitude). Gain defaults to 1.0 and can be changed using the Gain Control (see below). |
| A | Amplitude of turbine signal in Volts rms. |
| A1, A2, A3, A4 | A/D counts representing the turbine signal amplitude. Each stage (A1-A4) cannot exceed 512. Beginning with stage A1, the A/D counts increase as the flow increases. When stage A1 reaches 512, it will shift to stage A2. This will continue as the flowrate increases until all 4 stages read 512 at high flowrates. Higher flowrates (stronger signal strength) will result in more stages reading 512. |
| V | Calculated average pipe velocity (ft/sec). |
| Re | Calculated Reynolds number. |
| Profile Factor | Factory use only. |
| Obscuration Factor | Factory use only. |
| RTD1 | Resistance value of integral RTD in ohms. |
| RTD2 | Optional RTD resistance value in ohms. |
| Pe(v) | Pressure transducer excitation voltage |
| Pv(v) | Pressure transducer sense voltage. |
| Stnd | Density of fluid at standard conditions. |
| Nrml | Density of fluid at normal conditions. |
| Viscosity | Calculated viscosity of flowing fluid. |
| x Cnts | A/D counts from the external 4-20 mA input. |
| Ext x.xxx mA | Calculated external 4-20 mA input from the digital counts. |
| Ck | Calculated Ck at current operating conditions. Ck is a variable in the equation that relates signal strength, density, and velocity for a given application. It is used for noise rejection purposes. Ck directly controls the fi value (see above). If the Ck is set too low (in the calibration menu), then the fi value will be too low and the turbine signal will be rejected resulting in zero flowrate being displayed. The calculated Ck value in this menu can be compared to the actual Ck setting in the calibration menu to help determine if the Ck setting is correct. |

| | |
|-----------------------------|---|
| Lvl | Threshold level. If the Low Flow Cutoff in the calibration menu is set above this value, the meter will read zero flow. The Lvl level can be checked at no flow. At no flow, the Lvl must be below the Low Flow Cutoff setting or the meter will have an output at no flow. |
| Adj. Filter | Adjustable filter. Displays the filtering in decibels. Normally reads zero. If this value is consistently -5 or -10, for example, the Ck or density setting may be wrong. |
| Iso. Power Volts | Nominally 2.7 Vdc, if less than this check the flowmeter input power. |
| O,I | Factory use only. |
| Pulse Out Queue | Pulse output queue. This value will accumulate if the totalizer is accumulating faster than the pulse output hardware can function. The queue will allow the pulses to "catch up" later if the flowrate decreases. A better practice is to slow down the totalizer pulse by increasing the value in the (unit)/pulse setting in the totalizer menu. |
| TOF, G, f | Factory use only. |
| Sig. Rev | Signal board hardware and firmware revision. |
| Miro Rev | Microprocessor board hardware and firmware revision. |
| AD, R, T, F, PT, V | Factory use only. |
| SPI Err, Rcv, Sent | Factory use only. |
| ISR Diagnostic | Factory use only. |
| Power Fail | Factory use only. |
| External Power | Factory use only. |
| External Alarm | Factory use only. |
| Display CG, PWR | Factory use only. |
| Internal Temperature | Electronics temperature. |

6.3 Level two hidden diagnostics values

| | |
|-------------------------|--|
| 4-20(1) Zero | Analogue counts to calibrate zero on Analogue output 1. |
| 4-20(1) FScale | Analogue counts to cal. full scale on Analogue output 1. |
| 4-20(2) Zero | Analogue counts to calibrate zero on Analogue output 2. |
| 4-20(2) FScale | Analogue counts to cal. full scale on Analogue output 2. |
| 4-20(3) Zero | Analogue counts to calibrate zero on Analogue output 3. |
| 4-20(3) FScale | Analogue counts to cal. full scale on Analogue output 3. |
| Ext. 4 mA Cal. | Enter 0 for auto calibration or enter factory supplied A/D counts. Note: You must connect a known 4.00mA input if you are going to calibrate the unit. |
| Ext. 20 mA Cal. | Enter 0 for auto calibration or enter factory supplied A/D counts. Note: You must connect a known 20.00 mA input if you are going to calibrate the unit. |
| External Input | Enter what the external 4-20 mA input represents, i.e. Temperature 1, Temperature 2, or Pressure. The meter will use this for its internal calculations. |
| Ext. Full Scale | Enter the full scale units that correlate to the 20 mA point. Note: It must be in the units for the selected input type such as Deg F, Deg C, Psi a, Bar A, etc. |
| Ext. Zero Scale | Same as above but for the 4 mA point. |
| Alarm (1) Test | Used as a test to verify that the alarm circuit is functioning. When low is selected the alarm will initiate a low alarm on the output. When High is selected it will give a high alarm on the output. |
| Alarm (2) Test | Used as a test to verify that the alarm circuit is functioning. When low is selected the alarm will initiate a low alarm on the output. When High is selected it will give a high alarm on the output. |
| Alarm (3) Test | Used as a test to verify that the alarm circuit is functioning. When low is selected the alarm will initiate a low alarm on the output. When High is selected it will give a high alarm on the output. |
| Reynolds Corr. | Reynolds number correction for the flow profile. |
| Gain Control | Manual gain control (factory use only). Leave set at 1. |
| Filter control | Manual filter control. This value can be changed to any number to force the fi value to a constant. A value of zero activates the automatic filter control which sets fi at a level that floats above the f value. |
| High Pass Filter | Filter setting - Factory use only |

| | |
|---|---|
| Factory Defaults | Reset factory defaults. If you change this to Yes and press Enter, all the factory configuration is lost and you must reconfigure the entire program. Consult the factory before performing this process, it is required only in very rare cases. |
| Config Code | Factory use only. |
| Test Pulse Out | Force totalizer pulse. Set to Yes and press enter to send one pulse. Very useful to test totalizer counting equipment. |
| Test Scaled Freq | Enter a frequency value in order to test the scaled frequency output. Return to 0 to stop the test. |
| Output Type | Factory use only. |
| Calibration mode | Factory use only. |
| A2D Ref. Resistor | Factory use only. |
| Pressure Cal Current | Calibration value for the electronics and pressure transducer combination. Consult Factory for value. |
| Pressure 9Cs | Nine pressure coefficients unique to the pressure transducer. Use the RIGHT ARROW to access all nine coefficients. Press. Max psi = Based on installed sensor. |
| Press. Min psi | 0 psi aRTD1. Press the RIGHT ARROW to access: Ro = RTD resistance at 0 °C (1000 ohms). A = RTD coefficient A (.0039083). B = RTD coefficient B (-5.775e-07). RTD1 Max Deg. F = 500 RTD1 Min Deg. F = -330 |
| RTD2 | Second RTD configuration, for special applications only. |
| Correction Pairs | ft3/sec (1 through 10) |
| | %Dev. (1 through 10) |
| Roughness | Factory use only. |
| Force Recal? | Factory use only. |
| Min. Delta H - Energy EM meters only | Sets the deadband for totalization to begin. Must be greater than this number (1 default) to initiate the totalizer. |
| Init Displ. (sec) | Enter a value in seconds to initialize the display every xxx seconds. Enter a value of 0 to disable initializing the display. |

6.4 Analogue output calibration

To check the 4-20 mA circuit, connect a DVM in series with the output loop. Select zero or full scale (from the second column of the hidden diagnostics) and then actuate the enter key twice. This action will cause the meter to output its 4 mA or 20 mA conditions.

If the DVM indicates a current greater than ± 0.006 mA from 4 or 20, adjust the setting up or down until the output is calibrated.

Note: these settings are not for adjusting the output zero and span to match a flow range, that function is located in the Output Menu.

6.5 Troubleshooting the flowmeter



Warning!

Before attempting any flowmeter repair, verify that the line is not pressurized. Always remove main power before disassembling any part of the mass flowmeter. Use hazardous area precautions if applicable. Static sensitive electronics - use electro-static discharge precautions.

6.6 First check items:

- Installation direction correct
- Installation depth correct (insertion style meter)
- Power and wiring correct
- Application fluid correct
- Meter range correct for the application
- Meter configuration correct
- Describe Installation Geometry i.e. upstream diameters, valve position, downstream diameters, etc.

6.7 Record values:

Record the following values from the Run menu with the meter installed in order to determine the operating state of the flowmeter:

| | With Flow | With No Flow (if possible) |
|-------------------|-----------|----------------------------|
| Flow = | | |
| Temperature= | | |
| Pressure = | | |
| Density = | | |
| Error Messages? = | | |

Record the following values from the Hidden Diagnostics Menu with the meter installed:
 (Use password 16363 to access.)

| | With Flow | With No Flow (if possible) |
|--------------------|-----------|----------------------------|
| f = | | |
| f _i = | | |
| A = | | |
| A1 = | | |
| A2 = | | |
| A3 = | | |
| A4 = | | |
| V = | | |
| RTD1 = | | |
| RTD2 = | | |
| Pe(V) = | | |
| Pv(V) = | | |
| Ck = | | |
| Lvl = | | |
| Adj. Filter = | | |
| Iso. Power Volts = | | |
| Sig. Rev = | | |

Record the following values from the Calibration menu

| | |
|-------------------|--|
| Vortex Coef Ck = | |
| Low Flow Cutoff = | |

6.8 Determine the fault

6.8.1 Symptom: output at no flow

1. The low flow cutoff is set too low. At no flow, go to the first column of the hidden diagnostics menu and record the Lvl value. The low flow cutoff must be set above this value.
2. Example: at no flow , Lvl = 25. Set the low flow cutoff in the Calibration menu to approximately 28 and the meter will no longer read a flowrate at no flow.

6.8.2 Symptom: erratic output

1. The flowrate may be too low, just at the cutoff of the meter range, and the flow cycles above and below the cutoff making an erratic output. Consult the factory if necessary to confirm the meter range based on current operating conditions. It may be possible to lower the low flow cutoff to increase the meter range. See the example above for output at no flow, only this time the low flow cutoff is set too high. You can lower this value to increase the meter range as long as you do not create the output at no flow condition previously described.
2. Mechanical installation may be incorrect. Verify the straight run is adequate as described in Section 2. Verify the insertion depth and flow direction.
3. The meter may be reacting to actual changes in the flow stream. The output can be smoothed using a time constant. The displayed values can be smoothed using the time constant in the Display Menu. The Analogue outputs can be smoothed using the time constant in the Output Menu. A time constant of 1 will result in the change in value reaching 63% of its final value in one second. A time constant of 4 is 22%, 10 is 9.5% and 50 is 1.9% of the final value in one second. The time constant equation is shown below (TC = Time Constant).

$$\% \text{ change to final value in one second} = 100 (1 - e(-1/TC))$$

4. The coefficient Ck may be incorrectly set. The Ck is a value in the equation used to determine if a frequency represents a valid turbine signal given the fluid density and signal amplitude. In practice, the Ck value controls the adaptive filter, fi, setting. During flow, view the f and fi values in the first column of the hidden diagnostics. The fi value should be approximately 10- 20 % higher than the f value. If you raise the Ck setting in the Calibration menu, then the fi value will increase. The fi is a low pass filter, so by increasing it or lowering it, you can alter the range of frequencies that the meter will accept. If the turbine signal is strong, the fi value will increase to a large number - this is correct.

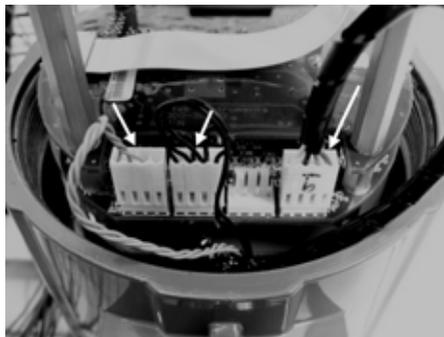


Fig. 52 Electronics stack sensor connections

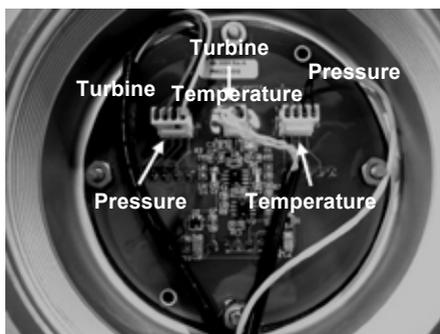


Fig. 53 Remote feed through board sensor connections

6.8.3 Symptom: no output

1. For remote mounted electronics, carefully check all the wiring connections in the remote mount junction box. There are 18 connections that must be correct, verify each color (black and red), shield, and wire number.
2. Turn on the pressure and temperature display in the Display Menu and verify that the pressure and temperature are correct.
3. Using ESD precautions and hazardous area precautions, remove the electronics enclosure window cover. Disconnect the turbine sensor from the electronics stack or remote feed through board. Refer to Figure 54. Measure the resistance from each outside pin to the meter ground should read a very low resistance. Measure the resistance from the center pin to the meter ground - this should be grounded to the meter.

With the sensor still disconnected, go to the first column of the hidden diagnostics and display the turbine frequency, f. Hold a finger on the three exposed pins on the Analogue board. The meter should read electrical noise, 60 Hz for example.

If all readings are correct, re-install turbine sensor wires.

4. Verify all meter configuration and troubleshooting steps previously described. There are many possible causes of this problem, consult factory if necessary.

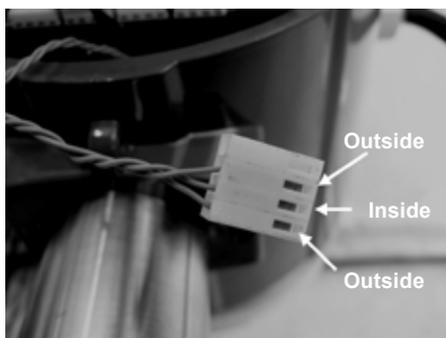


Fig. 54 Turbine Sensor Connector

6.8.4 Symptom: meter displays temperature fault

1. For remote mounted electronics, carefully check all the wiring connections in the remote mount junction box. There are 18 connections that must be correct, verify each color (black and red), shield, and wire number.
2. Go to the first column of the hidden diagnostics and check the resistance of the rtd1. It should be about 1080 ohms at room temperature.
3. Using ESD precautions and hazardous area precautions, remove the electronics enclosure window cover. Disconnect the temperature sensor from the electronics stack or the remote feed through board. Refer to Figure 55. Measure the resistance across the outside pins of the temperature sensor connector. It should read approximately 1080 ohms at room temperature (higher resistance at higher temperatures).
4. Consult factory with findings

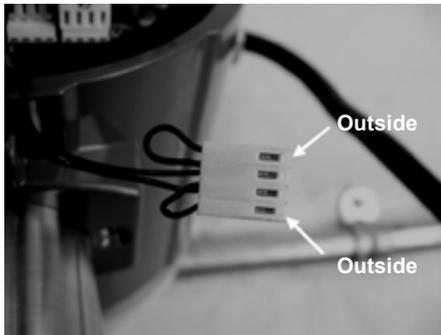


Fig. 55 Temperature Sensor Connector

6.8.5 Symptom: meter displays pressure fault

1. For remote mounted electronics, carefully check all the wiring connections in the remote mount junction box. There are 18 connections that must be correct, verify each color (black and red), shield, and wire number.
2. Using ESD precautions and hazardous area precautions, remove the electronics enclosure window cover. Disconnect the pressure sensor from the electronics stack or the remote feed through board. Measure the resistance across the outside pins of the pressure sensor connector, then across the inside pins. Both readings should be approximately 4000 ohms.
3. Go to the first column of the hidden diagnostics and record the Pe(V) and Pv(V) values and consult the factory with findings.

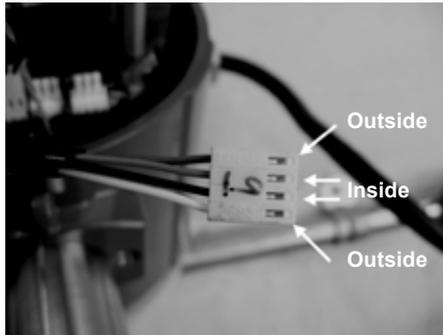


Fig. 56 Pressure Sensor Connector

6.9 Electronics assembly replacement (All Meters)



Warning!

Before attempting any flowmeter repair, verify that the line is not pressurized. Always remove main power before disassembling any part of the mass flowmeter.

The electronics boards are electrostatically sensitive. Wear a grounding wrist strap and make sure to observe proper handling precautions required for static-sensitive components.

1. Turn off power to the unit.
2. Locate and loosen the small set screw which locks the larger enclosure cover in place. Unscrew the cover to expose the electronics stack.
3. Locate the sensor harnesses which come up from the neck of the flowmeter and attaches to the circuit boards. Make note of the location of each sensor connection. Refer to Figures 52 and 53. The turbine sensor connection is on the left, the temperature sensor connection (if present) is second from the left, and the pressure sensor connection (if present) is the right most connector. Use small pliers to pull the sensor wiring connectors off of the circuit boards.
4. Locate and loosen the small set screw which locks the smaller enclosure cover in place. Unscrew the cover to expose the field wiring strip. Tag and remove the field wires.
5. Remove the screws that hold the black wiring label in place, remove the label.
6. Locate the 4 Phillips head screws which are spaced at 90- degrees around the terminal board. These screws hold the electronics stack in the enclosure. Loosen these screws (Note: that these are captive screws, they will stay inside the enclosure).
7. Carefully remove the electronics stack from the opposite side of the enclosure. If the electronics stack will not come out, gently tap the terminal strip with the screw driver handle. This will loosen the rubber sealing gasket on the other side of the enclosure wall. Be careful that the stack does not hang up on the loose sensor harnesses.
8. Repeat steps 1 through 6 in reverse order to install the new electronics stack.

6.10 Returning equipment to the factory

Before returning any RIM20 flowmeter to the factory, you must request a Return material Authorization (RMA) number. To obtain an RMA number and the correct shipping address, contact Customer Service at:

When contacting Customer Service, be sure to have the meter serial number and model code.

Please see the Meter Troubleshooting Checklist for additional items which may help with problem isolation. When requesting further troubleshooting guidance, please record the values on the checklist at no flow and during flow if possible.

7. Appendixes

7.1 Appendix A - Product specifications

Accuracy

| Process variables | RIM20 rotor insertion flowmeters (1) Liquid, Gas & Steam |
|---------------------|--|
| Mass flowrate | ±2% of rate(2) over a 30:1 range(3) |
| Volumetric flowrate | ±1.5% of rate over a 30:1 range(3) |
| Temperature | ±2 °F (±1 °C) |
| Pressure | 0.3% of transducer full scale |
| Density | 0.5% of reading(2) |

Notes:

(1) Accuracies stated are for the total mass flow through the pipe.

(2) ver 50 to 100% of the pressure transducer's full scale.

(3) Nominal rangeability is stated. Precise rangeability depends on fluid and pipe size.

Repeatability

Mass flowrate: 0.2% of rate.

Volumetric flowrate: 0.1% of rate.

Temperature: ±0.2 °F (±0.1 °C).

Pressure: 0.05% of full scale.

Density: 0.1% of reading.

Stability over 12 months

Mass flowrate: 0.2% of rate maximum.

Volumetric flowrate: Negligible error.

Temperature: ±0.1 °F (±0.5 °C) maximum.

Pressure: 0.1% of full scale maximum.

Density: 0.1% of reading maximum.

Response time

Adjustable from 1 to 100 seconds.

Material capability

Any gas, liquid or steam compatible with 316L stainless steel. Not recommended for multi-phase fluids.

Flowrates

Typical mass flow ranges are given in the following tables. Precise flow depends on the fluid and pipe size. Consult factory for sizing program.

Typical Metric flowrates

Saturated steam (kg/h)

| Rotor | Pressure | Nominal pipe size | | | | | | |
|-------|-----------|-------------------|--------|--------|--------|--------|--------|--------|
| | | 80 mm | 150 mm | 200 mm | 300 mm | 400 mm | 600 mm | |
| R40 | 1.4 bar g | Minimum | 17 | 72 | 127 | 297 | 491 | 1219 |
| | | Maximum | 225 | 929 | 1642 | 3817 | 6270 | 15367 |
| | 5 bar g | Minimum | 42 | 173 | 306 | 713 | 1176 | 2907 |
| | | Maximum | 537 | 2216 | 3915 | 9090 | 14905 | 36400 |
| | 10 bar g | Minimum | 75 | 310 | 549 | 1279 | 2106 | 5194 |
| | | Maximum | 962 | 3963 | 6999 | 16239 | 26600 | 64815 |
| R30 | 1.4 bar g | Minimum | 20 | 82 | 146 | 341 | 563 | 1396 |
| | | Maximum | 329 | 1358 | 2399 | 5575 | 9149 | 22384 |
| | 5 bar g | Minimum | 48 | 198 | 350 | 817 | 1347 | 3328 |
| | | Maximum | 785 | 3237 | 5716 | 13265 | 21735 | 52993 |
| | 10 bar g | Minimum | 86 | 355 | 629 | 1465 | 2411 | 5943 |
| | | Maximum | 1405 | 5786 | 10215 | 23687 | 38771 | 94337 |
| R20 | 1.4 bar g | Minimum | 35 | 146 | 259 | 604 | 995 | 2463 |
| | | Maximum | 530 | 2187 | 3863 | 8968 | 14704 | 35898 |
| | 5 bar g | Minimum | 85 | 350 | 620 | 1444 | 2377 | 5856 |
| | | Maximum | 1265 | 5207 | 9194 | 21322 | 34903 | 84940 |
| | 10 bar g | Minimum | 152 | 628 | 1111 | 2586 | 4252 | 10448 |
| | | Maximum | 2261 | 9303 | 16419 | 38049 | 62227 | 151156 |
| R10 | 1.4 bar g | Minimum | 61 | 253 | 448 | 1045 | 1721 | 4247 |
| | | Maximum | 1098 | 4522 | 7985 | 18520 | 30320 | 73805 |
| | 5 bar g | Minimum | 147 | 606 | 1072 | 2496 | 4103 | 10082 |
| | | Maximum | 2615 | 10755 | 18979 | 43967 | 71883 | 174497 |
| | 10 bar g | Minimum | 263 | 1087 | 1921 | 4466 | 7335 | 17975 |
| | | Maximum | 4672 | 19197 | 33862 | 78386 | 128050 | 310382 |

Typical Metric flowrates

Air (nm³/h) at 20 °C

| Rotor | Pressure | Nominal pipe size | | | | | | |
|-------|-----------|-------------------|--------|--------|--------|---------|---------|---------|
| | | 80 mm | 150 mm | 200 mm | 300 mm | 400 mm | 600 mm | |
| R40 | 1.4 bar g | Minimum | 12 | 49 | 87 | 204 | 337 | 838 |
| | | Maximum | 154 | 639 | 1 130 | 2 628 | 4 320 | 10 607 |
| | 5 bar g | Minimum | 74 | 305 | 540 | 1 259 | 2 072 | 5 107 |
| | | Maximum | 946 | 3 898 | 6 884 | 15 969 | 26 152 | 63 694 |
| | 10 bar g | Minimum | 137 | 567 | 1 002 | 2 332 | 3 835 | 9 423 |
| | | Maximum | 1 751 | 7 205 | 12 718 | 29 476 | 48 216 | 117 169 |
| R30 | 1.4 bar g | Minimum | 14 | 56 | 100 | 234 | 386 | 960 |
| | | Maximum | 226 | 934 | 1 651 | 3 839 | 6 306 | 15 455 |
| | 5 bar g | Minimum | 84 | 350 | 619 | 1 441 | 2 373 | 5 844 |
| | | Maximum | 1 382 | 5 690 | 10 046 | 23 290 | 38 115 | 92 698 |
| | 10 bar g | Minimum | 157 | 649 | 1 148 | 2 671 | 4 390 | 10 779 |
| | | Maximum | 2 556 | 10 511 | 18 548 | 42 965 | 70 237 | 170 473 |
| R20 | 1.4 bar g | Minimum | 24 | 100 | 178 | 415 | 684 | 1 696 |
| | | Maximum | 365 | 1 505 | 2 660 | 6 179 | 10 139 | 24 794 |
| | 5 bar g | Minimum | 150 | 618 | 1 094 | 2 544 | 4 182 | 10 271 |
| | | Maximum | 2 224 | 9 149 | 16 145 | 37 407 | 61 166 | 148 520 |
| | 10 bar g | Minimum | 278 | 1 146 | 2 026 | 4 709 | 7 731 | 18 929 |
| | | Maximum | 4 110 | 16 888 | 29 789 | 68 956 | 112 643 | 273 032 |
| R10 | 1.4 bar g | Minimum | 42 | 174 | 308 | 718 | 1 184 | 2 927 |
| | | Maximum | 756 | 3 115 | 5 502 | 12 768 | 20 919 | 50 995 |
| | 5 bar g | Minimum | 259 | 1 069 | 1 890 | 4 393 | 7 214 | 17 668 |
| | | Maximum | 4 595 | 18 874 | 33 290 | 77 048 | 125 842 | 304 938 |
| | 10 bar g | Minimum | 480 | 1 980 | 3 499 | 8 125 | 13 323 | 32 541 |
| | | Maximum | 8 481 | 34 799 | 61 349 | 141 871 | 231 535 | 560 318 |

Typical Imperial flowrates

Saturated steam (lb/h)

| Rotor | Pressure | Nominal pipe size | | | | | | |
|-------|-----------|-------------------|--------|--------|---------------|---------|---------|---------|
| | | 3" | 6" | 8" | 1DN50 (2") | 16" | 24" | |
| R40 | 5 psi g | Minimum | 22 | 91 | 162 | 378 | 625 | 1 555 |
| | | Maximum | 287 | 1 187 | 2 098 | 4 883 | 8 029 | 19 727 |
| | 100 psi g | Minimum | 119 | 496 | 878 | 2 046 | 3 371 | 8 328 |
| | | Maximum | 1 540 | 6 350 | 11 216 | 26 034 | 42 668 | 104 092 |
| | 200 psi g | Minimum | 220 | 913 | 1 615 | 3 761 | 6 191 | 15 249 |
| | | Maximum | 2 827 | 11 643 | 20 558 | 47 681 | 78 064 | 190 027 |
| R30 | 5 psi g | Minimum | 25 | 105 | 186 | 434 | 717 | 1 782 |
| | | Maximum | 420 | 1 735 | 3 068 | 7 135 | 11 721 | 28 745 |
| | 100 psi g | Minimum | 137 | 568 | 1 006 | 2 344 | 3 861 | 9 530 |
| | | Maximum | 2 251 | 9 272 | 16 373 | 37 984 | 62 207 | 151 526 |
| | 200 psi g | Minimum | 253 | 1 046 | 1 850 | 4 308 | 7 088 | 17 446 |
| | | Maximum | 4 129 | 16 994 | 29 996 | 69 532 | 113 761 | 276 542 |
| R20 | 5 psi g | Minimum | 45 | 186 | 330 | 770 | 1 270 | 3 150 |
| | | Maximum | 677 | 2 797 | 4 943 | 11 485 | 18 849 | 46 119 |
| | 100 psi g | Minimum | 243 | 1 005 | 1 778 | 4 140 | 6 811 | 16 762 |
| | | Maximum | 3 623 | 14 915 | 26 328 | 61 035 | 99 870 | 242 834 |
| | 200 psi g | Minimum | 447 | 1 848 | 3 268 | 7 601 | 12 492 | 30 657 |
| | | Maximum | 6 643 | 27 317 | 48 203 | 111 658 | 182 535 | 443 035 |
| R10 | 5 psi g | Minimum | 78 | 323 | 572 | 1 334 | 2 199 | 5 440 |
| | | Maximum | 1 405 | 5 790 | 10 227 | 23 736 | 38 897 | 94 870 |
| | 100 psi g | Minimum | 421 | 1 739 | 3 075 | 7 153 | 11 755 | 28 849 |
| | | Maximum | 7 490 | 30 791 | 54 325 | 125 807 | 205 605 | 498 759 |
| | 200 psi g | Minimum | 774 | 3 195 | 5 647 | 13 123 | 21 541 | 52 728 |
| | | Maximum | 13 719 | 56 341 | 99 362 | 229 926 | 375 467 | 909 528 |

Typical Imperial flowrates

Air (SCFM) at 70 °F

| Rotor | Pressure | Nominal pipe size | | | | | | |
|-------|-----------|-------------------|------|-------|---------------|--------|--------|--------|
| | | 3" | 6" | 8" | 1DN50 (2") | 16" | 24" | |
| R40 | 5 psi g | Minimum | 7 | 31 | 55 | 129 | 213 | 529 |
| | | Maximum | 98 | 404 | 714 | 1660 | 2729 | 6702 |
| | 100 psi g | Minimum | 62 | 255 | 451 | 1051 | 1730 | 4257 |
| | | Maximum | 790 | 3252 | 5741 | 13313 | 21791 | 53019 |
| | 200 psi g | Minimum | 117 | 484 | 857 | 1992 | 3273 | 8031 |
| | | Maximum | 1494 | 6146 | 10846 | 25128 | 41083 | 99739 |
| R30 | 5 psi g | Minimum | 9 | 36 | 63 | 148 | 244 | 606 |
| | | Maximum | 143 | 590 | 1043 | 2426 | 3984 | 9765 |
| | 100 psi g | Minimum | 71 | 292 | 517 | 1204 | 1980 | 4871 |
| | | Maximum | 1153 | 4746 | 8376 | 19412 | 31753 | 77152 |
| | 200 psi g | Minimum | 134 | 555 | 981 | 2281 | 3747 | 9186 |
| | | Maximum | 2181 | 8964 | 15814 | 36617 | 59832 | 145094 |
| R20 | 5 psi g | Minimum | 15 | 63 | 112 | 262 | 432 | 1071 |
| | | Maximum | 230 | 951 | 1680 | 3904 | 6406 | 15665 |
| | 100 psi g | Minimum | 125 | 517 | 913 | 2124 | 3489 | 8557 |
| | | Maximum | 1855 | 7628 | 13458 | 31168 | 50942 | 123591 |
| | 200 psi g | Minimum | 237 | 979 | 1730 | 4020 | 6595 | 16126 |
| | | Maximum | 3506 | 14397 | 25389 | 58747 | 95927 | 232348 |
| R10 | 5 psi g | Minimum | 26 | 110 | 195 | 454 | 748 | 1849 |
| | | Maximum | 478 | 1968 | 3476 | 8067 | 13217 | 32219 |
| | 100 psi g | Minimum | 216 | 893 | 1578 | 3666 | 6016 | 14715 |
| | | Maximum | 3831 | 15728 | 27734 | 64166 | 104762 | 253698 |
| | 200 psi g | Minimum | 410 | 1691 | 2987 | 6933 | 11362 | 27714 |
| | | Maximum | 7230 | 29650 | 52259 | 120804 | 197092 | 476732 |

Linear range

| Rotor | Fluid: Gas or steam | | | |
|------------|---------------------|--------|------------------|--------|
| | Minimum velocity | | Maximum velocity | |
| | m/sec | ft/sec | m/sec | ft/sec |
| R40 | 1.07 | 3.5 | 13.11 | 43.0 |
| R30 | 1.22 | 4.0 | 19.05 | 62.5 |
| R25 | 1.52 | 5.0 | 24.38 | 80.0 |
| R20 | 2.13 | 7.0 | 30.48 | 100.0 |
| R15 | 2.59 | 8.5 | 41.03 | 134.6 |
| R10 | 3.66 | 12.0 | 62.48 | 205.0 |

Process fluid pressure

| RIM20 Pressure ratings | | | |
|---|------------------------------|----------|-------------------|
| Probe seal | Process connection | Material | Rating |
| Compression fitting | 2" MNPT | 316L SS | ANSI 600 lb |
| | 2" 150 lb flange, DN50 PN16 | 316L SS | ANSI 150 lb, PN16 |
| | 2" 300 lb flange, DN50 PN40 | 316L SS | ANSI 300 lb, PN40 |
| | 2" 600 lb flange, DN50 PN63 | 316L SS | ANSI 600 lb, PN63 |
| Packing gland | 2" MNPT | 316L SS | ANSI 300 lb |
| | 2" 150 lb flange, DN50, PN16 | 316L SS | ANSI 150 lb, PN16 |
| | 2" 300 lb flange, DN50, PN16 | 316L SS | ANSI 300 lb, PN40 |
| Packing gland with permanent retractor | 2" MNPT | 316L SS | ANSI 600 lb |
| | 2" 150 lb flange, DN50 PN16 | 316L SS | ANSI 150 lb, PN16 |
| | 2" 300 lb flange, DN50, PN40 | 316L SS | ANSI 300 lb, PN40 |
| | 2" 600 lb flange, DN50 PN63 | 316L SS | ANSI 600 lb, PN63 |

Pressure transducer ranges

| Pressure sensor ranges(1), bar a (psi a) | | | |
|--|-------|-----------------------------|-------|
| Full scale operating pressure | | Maximum over-range pressure | |
| bar a | psi a | bar a | psi a |
| 2 | 30 | 4 | 60 |
| 7 | 100 | 14 | 200 |
| 20 | 300 | 41 | 600 |
| 34 | 500 | 69 | 1000 |
| 100 | 1500 | 175 | 2500 |

Note:

(1) To maximize accuracy, specify the lowest full scale operating pressure range for the application. To avoid damage, the flowmeter must never be subjected to pressure above the over-range pressure shown above.

12 to 36 Vdc, 25 mA, 1 W max., Loop Powered Volumetric or Mass 12 to 36 Vdc, 300 mA, 9 W max. Multiparameter Mass options 100 to 240 Vac, 50/60 Hz, 5 W max. Multiparameter Mass options

Class I Equipment (Grounded Type)

Power requirements

Installation (Over-voltage) Category II for transient over-voltages

AC & dc Mains supply voltage fluctuations are not to exceed +/-10% of the rated supply voltage range.

User is responsible for the provision of an external Disconnect Means (and Over-Current Protection) for the equipment (both ac and dc models).

Alphanumeric 2 x 16 LCD digital display.

Display

Six push-button switches (up, down, right, left, enter, exit) operable through explosion-proof window using hand-held magnet. Viewing at 90-degree mounting intervals.

Process fluid and ambient temperature

Process Fluid:

Standard temperature sensor: -55 °C to 232 °C (-67 °F to 450 °F)

High Temperature sensor: -267 °C to 454 °C (-448 °F to 850 °F)

Ambient:

Operating temperature range: -40 to 60 °C (-40 to 140 °F)

Storage temperature range: -40 to 85 °C (-40 to 185 °F)

Maximum relative humidity: 0-98%, non-condensing conditions

Maximum altitude: 2,000 meters (6,560 feet)

Pollution Degree 2 for the ambient environment

| | |
|--|--|
| Output signals (1) | <p>Analogue: Volumetric Meter: field rangeable linear 4-20 mA output signal (1200 Ohms maximum loop resistance) selected by user for mass flowrate or volumetric flowrate.</p> <p>Communications: HART, MODBUS RTU, BACnet MS/TP</p> <p>Multiparameter Meter: up to three field rangeable linear 4-20 mA output signals (1200 Ohms maximum loop resistance) selected from the five parameters-mass flowrate, volumetric flowrate, tem- perature, pressure and density.</p> <p>Pulse:Pulse output for totalization is a 50-millisecond duration pulse operating a solid-state relay capable of switching 40 Vdc, 40 mA maximum.</p> <p>Note: (1) All outputs are optically isolated and require external power for operation.</p> |
| Alarms | Up to three programmable solid-state relays for high, low or window alarms capable of switching 40 Vdc, 40 mA maximum. |
| Totalizer | Based on user-determined flow units, six significant figures in scientific notation. Total stored in non-volatile memory. |
| Wetted materials | <p>316L stainless steel.</p> <p>302 stainless steel.</p> <p>17-4 PH stainless steel. Tungsten carbide. Sapphire</p> <p>Teflon® packing gland below 260 °C (500 °F).</p> <p>Graphite packing gland above 260 °C (500 °F).</p> |
| Enclosure protection classification | NEMA 4X and IP66 cast enclosure. |
| Electrical ports | Two ¾" female NPT ports. |
| Mounting connections | <p>Permanent installation: DN50 (2") MNPT; 150, 300, 600 lb ANSI flange, PN16, PN40, PN63 flange with compression fitting probe seal.</p> <p>Hot Tap(1) Installation: DN50 (2") MNPT; 150, 300, 600 lb ANSI flange, PN16, PN40, PN63 flange and optional retractor with packing gland probe seal.</p> <p>Note: (1) Removable under line pressure.</p> |
| Mounting position | Meter must be perpendicular within ±5° of the pipe centerline. |
| Certifications | <p>Material Certificate - US Mill certs on all pressure retaining parts</p> <p>Pressure Test Certificate</p> <p>Certificate of Conformance</p> <p>NACE Certification (MR0175)</p> |
| Conformity | CE marked only |

7.2 Appendix B Approvals

Low Voltage Directive

Directive 2014/35/EU

EN 61010-1:2010

Electromagnetic Compatibility Directive

Directive 2014/30/EU

EN 61000-6-2:2005

EN 55011:2009 + A1:2010 Group 1 Class A



7.3 Appendix C flowmeter calculations

Flowing velocity

$$V_f = \frac{f}{K_c}$$

Volume flowrate

$$Q_v = V_f A$$

Mass flowrate

$$Q_m = V_f A \rho$$

Where:

A = Cross sectional area of the pipe (ft²)

f = Turbine meter frequency (pulses / sec)

K_c = Meter factor corrected for Reynolds Number (pulses / ft)

Q_v = Volume flowrate (ft³ / sec)

Q_m = Mass flowrate (lbm / sec)

V_f = Flowing velocity (ft / sec)

ρ = Density (lbm / ft³)

Fluid calculations

Calculations for Steam T & P

When "Steam T & P" is selected in the "Real Gas" selection of the Fluid Menu, the calculations are based on the equations below.

Density

The density of steam is calculated from the formula given by Keenan and Keys. The given equation is for the volume of the steam.

$$v = \frac{4.555.04 \cdot T}{\rho} + B$$

$$B = B_0 + B_0^2 g_1(\tau) \tau \cdot \rho + B_0^4 g_2(\tau) \tau^3 \cdot \rho^3 - B_0^{13} g_3(\tau) \tau^{12} \cdot \rho^{12}$$

$$B_0 = 1.89 - 2641.62 \cdot \tau \cdot 10^{80870r^2}$$

$$g_1(\tau) = 82.546 \cdot \tau - 1.6246 \cdot 10^5 \cdot \tau^2$$

$$g_2(\tau) = 0.21828 - 1.2697 \cdot 10^5 \cdot \tau^2$$

$$g_3(\tau) = 3.635 \cdot 10^{-4} - 6.768 \cdot 10^{64} \cdot \tau^{24}$$

Where tau is 1/ temperature in Kelvin.

The density can be found from 1/(v/ standard density of water).

Viscosity

The viscosity is based on an equation given by Keenan and Keys.

$$\eta(\text{poise}) = \frac{1.501 \cdot 10^{-5} \sqrt{T}}{1 + 446.8 / T}$$

Where T is the temperature in Kelvin

Calculations for Gas ("Real Gas" and "Other Gas")

Use this formula to determine the settings for "Real Gas; Gas" selections and "Other Gas" selections entered in the Fluid Menu. The calculations for gas were taken from Richard W. Miller, Flow Measurement Engineering Handbook (Third Edition, 1996).

Density

The density for real gases is calculated from the equation:

$$\rho = \frac{GM_w^{\text{Air}} P_f}{Z_f R_0 T_f}$$

Where G is the specific gravity, M_w is the molecular weight of air, p_f is the flowing pressure, Z is flowing compressibility, R_0 is the universal gas constant, and T is the flowing temperature. The specific gravity, and R_0 are known and are stored in a table used by the Turbine meter. The hard coefficient to find is the compressibility, Z. Z is found using the Redlich-Kwong Equation (Miller page 2-18).

The Redlich-Kwong Equation uses the reduced temperature and pressure to calculate the compressibility factor. The equations are non linear and an iterative solution is used. The Turbine program uses Newton's Method on the Redlich-Kwong equations to iteratively find the compressibility factor. The critical temperature and pressure used in the Redlich-Kwong equation are stored in the fluid data table with the other coefficients.

Viscosity

The viscosity for real gases is calculated using the exponential equation for two known viscosities. The equation is:

$$\mu_{cP} = aT_K^n$$

Where a and n are found from two known viscosities at two temperatures.

$$n = \frac{1n [(\mu_{cP})^2 / (\mu_{cP})^1]}{1n(T_{K2} / T_{K1})}$$

and

$$a = \frac{(\mu_{cP})^1}{T_{K1}^n}$$

Calculations for liquid

Use this formula to determine the settings for "Goyal-Dorais" selections and "Other Liquid" selections entered in the Fluid Menu. The liquid calculations were taken from Richard W. Miller, Flow Measurement Engineering Handbook (Third Edition, 1996).

Density

The liquid density is found using the Goyal-Doraiswamy Equation.

Goyal-Doraiswamy uses the critical compressibility, critical pressure and critical temperature, along with the molecular weight to find the density.

The equation for specific gravity is:

$$G_F = \frac{p_c Mw}{T_c} \left(\frac{0.008}{Z_c^{0.773}} - 0.01102 \right) \frac{T_f}{T_c}$$

The specific gravity can then be converted into density.

Viscosity

The liquid viscosity is found by Andrade's equation. This uses two viscosities at different temperatures to extrapolate the viscosity.

Andrade's equation:

$$\mu = A_L \exp \frac{B_L}{T_{deg R}}$$

To find A and B

$$B_L = \frac{T_{deg R1} T_{deg R2} \ln(\mu_1 / \mu_2)}{T_{deg R1} - T_{deg R2}}$$

$$A_L = \frac{\mu_1}{\exp(B_L / T_{deg R1})}$$

The temperatures are all in degrees Rankin. Do not believe the subscript R means they are reduced temperatures.

7.4 Appendix D Glossary

| | | |
|----------|-------------------------------|--|
| | A | Cross sectional area. |
| A | ACFM | Actual Cubic Feet Per Minute (volumetric flowrate). |
| | ASME | American Society of Mechanical Engineers. |
| B | BTU | British Thermal Unit, an energy measurement. |
| C | Cenelec | European Electrical Code. |
| | Compressibility factor | A factor used to correct for the non-ideal changes in a fluid is density due to changes in temperature and/or pressure. |
| | CSA | Canadian Standards Association. |
| D | D | Diameter of a flow channel. |
| | f | Frequency generated by a turbine flowmeter, usually in Hz. |
| | Flow channel | A pipe, duct, stack, or channel containing flowing fluid. |
| | Flow profile | A map of the fluid velocity vector (usually non- uniform) in a cross-sectional plane of a flow channel (usually along a diameter). |
| F | FM | Factory Mutual. |
| | Ft | Foot, 1 DN50 (2"), a measure of length. |
| | Ft2 | Square feet, measure of area. |
| | Ft3 | Cubic feet, measure of volume. |
| G | GPM | Gallons Per Minute. |
| H | Hz | Hertz, cycles per second. |

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| I | Insertion flowmeter | A flowmeter which is inserted into a hole in the user's pipeline. |
| J | Joule | A unit of energy equal to one watt for one second. Also equal to a Newton-meter. |
| L | LCD | Liquid crystal display. |
| M | \dot{m} | Mass flowrate. |
| | mA | Milli-amp, one thousandth of an ampere of current. |
| | μ | Viscosity, a measure of a fluid's resistance to shear stress. Honey has high viscosity, alcohol has low viscosity. |
| P | ΔP | Permanent pressure loss. |
| | P | Line pressure (psi a or bar absolute). |
| | ρ_{act} | The density of a fluid at the actual temperature and pressure operating conditions. |
| | ρ_{std} | The density of a fluid at standard conditions (usually 14.7 psi a and 202 °C). |
| | Permanent | Unrecoverable drop in pressure. Pressure Loss |
| | Pitch | The angle of the blades of a turbine rotor. |
| | PRTD | An resistance temperature detector (RTD) with platinum as its element. Used because of high stability. |
| | psi a | Pounds per square" absolute (equals psi g + atmospheric pressure). Atmospheric pressure is typically 14.696 psi at sea level. |
| | psi g | Pounds per square" gauge. |
| | PV | Liquid vapor pressure at flowing conditions (psi a or bar absolute). |

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| Q | Q | Flowrate, usually volumetric. |
| R | Rangeability | Highest measurable flowrate divided by the lowest measurable flowrate. |
| | Reynolds number | A dimensionless number equal to the density of a fluid or Retimes the velocity of the fluid times the diameter of the fluid channel, divided by the fluid viscosity (i.e., $Re = \rho VD/\mu$). The Reynolds number is an important number for turbine flowmeters because it is used to determine the minimum measurable flowrate. It is the ratio of the inertial forces to the viscous forces in a flowing fluid. |
| | Rotor | The velocity sensing element of a turbine flowmeter. Rotors are manufactured with the blades at a certain pitch. The pitch of the rotor blades determine the maximum velocity the turbine flowmeter can be used in. |
| | RTD | Resistance temperature detector, a sensor whose resistance increases as the temperature rises. |
| S | scfm | Standard cubic feet per minute (flowrate converted to standard conditions, usually 14.696 psi a and 682 F). |
| T | Totalizer | An electronic counter which records the total accumulated flow over a certain range of time. |
| | Traverse | The act of moving a measuring point across the width of a flow channel. |
| U | Uncertainty | The closeness of agreement between the result of a measurement and the true value of the measurement. |
| | V | Velocity or voltage. |
| V | Vac | Volts, alternating current. |
| | Vdc | Volts, direct current. |

